

**CHARACTERIZATIONS OF RANDOM APPROXIMATIONS**

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ABSTRACT. Some characterizations of random approximations are obtained in a locally convex space through duality theory.

## 1. INTRODUCTION AND PRELIMINARIES

Random approximation theory has received much attention after the publication of survey paper by Bharucha-Reid [3] in 1976. The interested reader is referred to recent papers in normed space framework by Tan and Yaun [11], Sehgal and Singh [10], Papageorgiou [7], Lin [5], Beg and Shahzad [2] and Beg [1]. The interplay between random approximation and random fixed point results is interesting and valuable (see for example [5], [7] and [11]). The applications of this closely related concept to random differential equations and integral equations in the context of Banach spaces may be found in Itoh [4] and O'Regan [6] respectively. So random approximations are needed in the study of random equations. Recently, Beg [1] obtained a characterization of random approximations in a normed space by employing the Hahn-Banach separation theorem. Characterization theorems of best approximation in the locally convex space setting have been considered in [8]. In this paper, we establish the characterizations concerning existence of random approximation in locally convex spaces by using the Hahn Banach extension theorem and a result of Tukey [13] about separation of convex sets; in particular Theorem 1 provides a random version of Theorem 2.1 of Rao and Elumalai [8] and Theorem 2 sets an analogue for metrizable locally convex spaces of the theorem due to Beg [1].

We now fix our terminology. Let  $(\Omega, \Sigma)$  be a measurable space where  $\Sigma$  is a sigma algebra of subsets of  $\Omega$  and  $M$  a subset of a locally convex space  $E$  over the field  $F$  of real or complex numbers. A map  $T : \Omega \times M \rightarrow E$  is called a random operator if for each fixed  $x \in M$ , the map  $T(\cdot, x) : \Omega \rightarrow E$  is measurable. Let  $(E, d)$  be a metrizable locally convex space.

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- (i) The ball with radius  $r$  and centre at  $x$  is defined as  $B_r(x) = \{z \in E : d(z, x) \leq r\}$ ; in particular the ball  $B_r(0)$  has centre at 0.
- (ii)  $d(x, M) = \inf_{u \in M} d(x, u)$ .
- (iii)  $P_M(x) = \{y \in M : d(x, y) = d(x, M)\}$  (set of best approximations of  $x$  from  $M$ ).
- (iv) For a ball  $B_r(0)$  in  $(E, d)$ , the set  $\{z \in E : d(z, 0) = r\}$  is called metric boundary of  $B_r(0)$ . In general, the topological boundary of  $B_r(0)$  is contained in its metric boundary. In case metric and topological boundaries of  $B_r(0)$  coincide, we say  $B_r(0)$  is bounding (cf. [12]).

In this note,  $\text{cl}$ ,  $\text{int}$ ,  $E^*$  and  $E \setminus M$  denote the closure, interior, dual of  $E$  and difference of sets  $E$  and  $M$ , respectively.

## 2. RESULTS

**Theorem 1.** *Let  $E$  be a separable locally convex space with family  $P$  of seminorms and  $M$  a subspace of  $E$ . Suppose  $T : \Omega \times M \rightarrow E$  is a random operator and  $\xi : \Omega \rightarrow M$  a measurable map such that  $T(\omega, \xi(\omega)) \in E \setminus M$ . Then  $\xi$  is a random best approximation for  $T$  (i.e.,  $p(\xi(\omega) - T(\omega, \xi(\omega))) = d_p(T(\omega, \xi(\omega)), M)$  for each  $p \in P$ ) if and only if for every  $p \in P$  there exists  $f^p \in E^*$  such that*

- (a)  $f^p(g) = 0$  for all  $g \in M$ .
- (b)  $|f^p(T(\omega, \xi(\omega)) - \xi(\omega))| = p(T(\omega, \xi(\omega)) - \xi(\omega))$ .
- (c)  $|f^p(T(\omega, \xi(\omega)) - g)| \leq p(T(\omega, \xi(\omega)) - g)$  for all  $g \in M$ .

**Proof.** Suppose that  $\xi$  is a random approximation for  $T$ . Then for each  $p \in P$  and  $g \in M$ ,

$$p(T(\omega, \xi(\omega)) - \xi(\omega)) \leq p(T(\omega, \xi(\omega)) - g).$$

In particular, for any  $0 \neq \alpha \in F$  and  $g \in M$ ,

$$(i) \quad p(T(\omega, \xi(\omega)) - \xi(\omega)) \leq p\left(T(\omega, \xi(\omega)) - \left(\xi(\omega) - \frac{g}{\alpha}\right)\right).$$

Let  $B = \{g + \alpha(T(\omega, \xi(\omega)) - \xi(\omega)) : \alpha \in F\}$ .

Define  $f_0^p$  on  $B$  by  $f_0^p(g + \alpha[T(\omega, \xi(\omega)) - \xi(\omega)]) = \alpha p(T(\omega, \xi(\omega)) - \xi(\omega))$  for all  $g \in M$ . Then  $f_0^p(g) = 0$  for all  $g \in M$  and

$$f_0^p(T(\omega, \xi(\omega)) - \xi(\omega)) = p(T(\omega, \xi(\omega)) - \xi(\omega)).$$

For any  $\alpha \neq 0$  and  $g \in M$ , we have

$$\begin{aligned} |f_0^p(g + \alpha[T(\omega, \xi(\omega)) - \xi(\omega)])| &= |\alpha|p(T(\omega, \xi(\omega)) - \xi(\omega)) \\ &\leq |\alpha|p\left(T(\omega, \xi(\omega)) - \xi(\omega) + \frac{g}{\alpha}\right) \quad (\text{by (i)}) \\ &= p(g + \alpha[T(\omega, \xi(\omega)) - \xi(\omega)]). \end{aligned}$$

For  $\alpha = 0$  and  $g \in M$  this inequality obviously holds.

Hence for each  $z \in B$  and for each  $p \in P$ ,

$$|f_0^p(z)| \leq p(z).$$

Thus by the Hahn-Banach theorem,  $f_0^p$  can be extended to a continuous linear functional  $f^p$  on  $E$  such that  $|f^p(x)| \leq p(x)$  for every  $x \in E$  and

$$|f^p(z)| = |f_0^p(z)| \quad \text{for each } z \in M.$$

The results (a)–(c) are now evident.

Conversely let the conditions (a)–(c) be satisfied. Then from (b) we get for all  $p \in P$  and  $g \in M$ ,

$$\begin{aligned} p(T(\omega, \xi(\omega)) - \xi(\omega)) &= |f^p(T(\omega, \xi(\omega)) - \xi(\omega))| \\ &= |f^p(T(\omega, \xi(\omega)) - g) + f^p(g - \xi(\omega))| \\ &= |f^p(T(\omega, \xi(\omega)) - g)| \quad \text{(by (a))} \\ &\leq p(T(\omega, \xi(\omega)) - g) \quad \text{(by (c)).} \end{aligned}$$

Hence  $p(T(\omega, \xi(\omega)) - \xi(\omega)) = d_p(T(\omega, \xi(\omega)), M)$  for all  $p \in P$ . □

We shall follow the argument used in the proof of Theorem 2.3 of Thaheem [12] to prove the following:

**Theorem 2.** *Let  $(E, d)$  be a separable metrizable locally convex space with  $d$  as invariant metric. Assume that the ball  $B_r(0)$  is convex and bounding and  $M$  a convex subset of  $E$ . Let  $T : \Omega \times M \rightarrow E$  be a random operator and  $\xi : \Omega \rightarrow M$  a measurable map such that  $T(\omega, \xi(\omega)) \notin \text{cl}(M)$ . Then  $\xi$  is a random best approximation for  $T$  if and only if there exists a real continuous linear functional  $f \in E_{\mathbf{R}}^*$  ( $\mathbf{R}$  is the set of real numbers) such that*

- (a)  $f(T(\omega, \xi(\omega)) - \xi(\omega)) = d(T(\omega, \xi(\omega)), \xi(\omega)) = r(\omega) = r$  (say; for notational simplicity).
- (b)  $f(y - \xi(\omega)) \leq 0$  for all  $y$  in  $M$ .
- (c)  $\|f\|_r = \sup\{|f(z)| : z \in B_r(0)\} = r$ .

**Proof.** Assume that  $d(\xi(\omega), T(\omega, \xi(\omega))) = d(T(\omega, \xi(\omega)), M)$ . Then  $M$  and  $\text{int}(B_r(T(\omega, \xi(\omega))))$ , where  $r = d(T(\omega, \xi(\omega)), M)$ , are disjoint convex sets. By a result of Tukey [13] (see also Rudin [9]), there is a nonzero continuous real linear functional  $f_{\xi(\omega)} \in E_{\mathbf{R}}^*$  and a real number  $c$  such that

(ii)  $f_{\xi(\omega)}(T(\omega, \xi(\omega)) - y) \geq c \quad \text{for all } y \in M,$

and

$$f_{\xi(\omega)}(T(\omega, \xi(\omega)) - z) < c \quad \text{for all } z \in \text{int}(B_r(T(\omega, \xi(\omega)))).$$

The continuity of  $f_{\xi(\omega)}$  implies that

$$f_{\xi(\omega)}(T(\omega, \xi(\omega)) - z) \leq c \quad \text{for all } z \in B_r(T(\omega, \xi(\omega))).$$

Since  $\xi(\omega) \in M \cap B_r(T(\omega, \xi(\omega)))$ , it follows that

(iii)  $f_{\xi(\omega)}(T(\omega, \xi(\omega)) - \xi(\omega)) = c.$

Obviously  $c$  is nonzero otherwise we get the contradiction that  $f_{\xi(\omega)}$  is identically zero.

Put  $f = (1/c)rf_{\xi(\omega)}$ . This implies by (iii) that

$$\begin{aligned} f(T(\omega, \xi(\omega)) - \xi(\omega)) &= (1/c)rf_{\xi(\omega)}(T(\omega, \xi(\omega)) - \xi(\omega)) = r \\ f(y - \xi(\omega)) &= f(y - T(\omega, \xi(\omega))) + f(T(\omega, \xi(\omega)) - \xi(\omega)) \quad (y \in M) \\ &= (1/c)rf_{\xi(\omega)}(y - T(\omega, \xi(\omega))) + (1/c)rf_{\xi(\omega)}(T(\omega, \xi(\omega)) - \xi(\omega)) \\ &\leq 0 \quad (\text{by (ii) and (iii)}). \end{aligned}$$

It is easy to get by linearity of  $f$  that  $\|f\|_r = r$ .

Conversely suppose that there is a real continuous linear functional  $f$  satisfying the conditions (a)–(c).

If the conclusion is false, then for some  $x$  in  $M$ , we have

$$(iv) \quad d(T(\omega, \xi(\omega)), x) < d(T(\omega, \xi(\omega)), \xi(\omega)).$$

The continuity of scalar multiplication implies that for any  $\epsilon > 0$ , there is  $\beta > 0$  such that

$$(v) \quad d(0, \beta T(\omega, \xi(\omega)) - \beta x) < \epsilon.$$

Consider

$$\begin{aligned} &d(0, (1 + \beta)(T(\omega, \xi(\omega)) - x)) \\ &\leq d(0, T(\omega, \xi(\omega)) - x) + d(T(\omega, \xi(\omega)) - x, (1 + \beta)(T(\omega, \xi(\omega)) - x)) \\ &= d(0, T(\omega, \xi(\omega)) - x) + d(0, \beta T(\omega, \xi(\omega)) - \beta x) \quad (\text{by invariance of } d) \\ &< d(0, T(\omega, \xi(\omega)) - x) + \epsilon \quad (\text{by (v)}) \\ &\leq d(T(\omega, \xi(\omega)), \xi(\omega)) \quad (\text{by (iv)}). \end{aligned}$$

The above inequality and the fact  $f(\xi(\omega) - x) \geq 0$  lead to:

$$\begin{aligned} f((1 + \beta)(T(\omega, \xi(\omega)) - x)) &= (1 + \beta)f(T(\omega, \xi(\omega)) - x) \\ &\geq (1 + \beta)f(T(\omega, \xi(\omega)) - \xi(\omega)). \end{aligned}$$

This implies that  $f(T(\omega, \xi(\omega)) - \xi(\omega))$  is not the supremum of  $f$  over  $B_r(0)$ . This contradiction proves the result.  $\square$

In case  $M$  is a subspace we have the following:

**Corollary.** *Let  $(E, d)$  be a separable metrizable locally convex space with invariant metric  $d$  and  $M$  a subspace of  $E$ . Assume that the ball  $B_r(0)$  is convex and bounding. Suppose that  $T : \Omega \times M \rightarrow E$  is a random operator and  $\xi : \Omega \rightarrow M$  a measurable map such that  $T(\omega, \xi(\omega)) \notin \text{cl}(M)$ . Then  $\xi$  is a random best approximation for  $T$  if and only if there exists a real continuous linear functional  $f \in E_R^*$  such that*

- (a)  $f(T(\omega, \xi(\omega)) - \xi(\omega)) = d(T(\omega, \xi(\omega)), \xi(\omega)) = r(\omega) = r$  (say).
- (b)  $f(y) = 0$  for all  $y$  in  $M$ .
- (c)  $\|f\|_r = r$ .

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