

## ON HOLOMORPHICALLY PROJECTIVE MAPPINGS OF $e$ -KÄHLER MANIFOLDS

IRENA HINTERLEITNER

ABSTRACT. In this paper we study fundamental equations of holomorphically projective mappings of  $e$ -Kähler spaces (i.e. classical, pseudo- and hyperbolic Kähler spaces) with respect to the smoothness class of metrics. We show that holomorphically projective mappings preserve the smoothness class of metrics.

### 1. INTRODUCTION

First we study the general dependence of holomorphically projective mappings of classical, pseudo- and hyperbolic Kähler manifolds (shortly  $e$ -Kähler) in dependence on the smoothness class of the metric. We present well known facts, which were proved by Domashev, Kurbatova, Mikeš, Prvanović, Otsuki, Tashiro etc., see [2, 3, 6, 7, 8, 9, 10, 11, 12, 15, 16, 17, 18, 19]. In these results no details about the smoothness class of the metric were stressed. They were formulated “for sufficiently smooth” geometric objects.

### 2. KÄHLER MANIFOLDS

In the following definition we introduce generalizations of Kähler manifolds.

**Definition 1.** An  $n$ -dimensional (pseudo-)Riemannian manifold  $(M, g)$  is called an  $e$ -Kähler manifold  $K_n$ , if beside the metric tensor  $g$ , a tensor field  $F$  ( $\neq \text{Id}$ ) of type  $(1, 1)$  is given on the manifold  $M_n$ , called a *structure*  $F$ , such that the following conditions hold:

$$(1) \quad F^2 = e \text{Id}; \quad g(X, FX) = 0; \quad \nabla F = 0,$$

where  $e = \pm 1$ ,  $X$  is an arbitrary vector of  $TM_n$ , and  $\nabla$  denotes the covariant derivative in  $K_n$ .

If  $e = -1$ ,  $K_n$  is a (*pseudo*-)Kähler space (also *elliptic Kähler space*) and  $F$  is a *complex structure*. As  $A$ -spaces, these spaces were first considered by P. A. Shirokov, see [14]. Independently they were studied by E. Kähler [5].

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If  $e = +1$ ,  $K_n$  is a *hyperbolic Kähler space* (also *para Kähler space*, see [1]) and  $F$  is a *product structure*. The spaces  $K_n^+$  were considered by P. K. Rashevskij [13].

The  $e$ -Kähler spaces introduced here are called shortly “Kähler” in the literature [10, 16]. By our definition we want to give a unified notation for all classes.

3. HOLOMORPHICALLY PROJECTIVE MAPPING THEORY  
FOR  $K_n \rightarrow \bar{K}_n$  OF CLASS  $C^1$

Assume the  $e$ -Kähler manifolds  $K_n = (M, g, F)$  and  $\bar{K}_n = (\bar{M}, \bar{g}, \bar{F})$  with metrics  $g$  and  $\bar{g}$ , structures  $F$  and  $\bar{F}$ , Levi-Civita connections  $\nabla$  and  $\bar{\nabla}$ , respectively. Here  $K_n, \bar{K}_n \in C^1$ , i.e.  $g, \bar{g} \in C^1$  which means that their components  $g_{ij}, \bar{g}_{ij} \in C^1$ .

Likewise, as in [11] we introduce the following notations.

**Definition 2.** A curve  $\ell$  in  $K_n$  which is given by the equation  $\ell = \ell(t)$ ,  $\lambda = d\ell/dt$ , ( $\neq 0$ ),  $t \in I$ , where  $t$  is a parameter is called *analytically planar*, if under the parallel translation along the curve, the tangent vector  $\lambda$  belongs to the two-dimensional distribution  $D = \text{Span} \{ \lambda, F\lambda \}$  generated by  $\lambda$  and its conjugate  $F\lambda$ , that is, it satisfies

$$\nabla_t \lambda = a(t)\lambda + b(t)F\lambda,$$

where  $a(t)$  and  $b(t)$  are some functions of the parameter  $t$ .

Particularly, in the case  $b(t) = 0$ , an analytically planar curve is a geodesic.

**Definition 3.** A diffeomorphism  $f: K_n \rightarrow \bar{K}_n$  is called a *holomorphically projective mapping* of  $K_n$  onto  $\bar{K}_n$  if  $f$  maps any analytically planar curve in  $K_n$  onto an analytically planar curve in  $\bar{K}_n$ .

Assume a holomorphically projective mapping  $f: K_n \rightarrow \bar{K}_n$ . Since  $f$  is a diffeomorphism, we can suppose local coordinate charts on  $M$  or  $\bar{M}$ , respectively, such that locally,  $f: K_n \rightarrow \bar{K}_n$  maps points onto points with the same coordinates, and  $\bar{M} = M$ .

A manifold  $K_n$  admits a holomorphically projective mapping onto  $\bar{K}_n$  if and only if the following equations [10, 16]:

$$(2) \quad \bar{\nabla}_X Y = \nabla_X Y + \psi(X)Y + \psi(Y)X + e\psi(FX)FY + e\psi(FY)FX$$

hold for any tangent fields  $X, Y$  and where  $\psi$  is a differential form. If  $\psi \equiv 0$  than  $f$  is *affine* or *trivially holomorphically projective*. Beside these facts it was proved [10, 16] that  $\bar{F} = \pm F$ ; for this reason we can suppose that  $\bar{F} = F$ . In local form:

$$\bar{\Gamma}_{ij}^h = \Gamma_{ij}^h + \psi_i \delta_j^h + \psi_j \delta_i^h + e\psi_i \delta_j^h + e\psi_j \delta_i^h,$$

where  $\Gamma_{ij}^h$  and  $\bar{\Gamma}_{ij}^h$  are the Christoffel symbols of  $K_n$  and  $\bar{K}_n$ ,  $\psi_i, F_i^h$  are components of  $\psi, F$  and  $\delta_i^h$  is the Kronecker delta,  $\psi_i = \psi_\alpha F_i^\alpha, \delta_i^h = F_i^h$ .

Here and in the following we will use the conjugation operation of indices in the way

$$A_{\dots \bar{i} \dots} = A_{\dots k \dots} F_i^k.$$

Equations (2) are equivalent to the following equations

$$(3) \quad \begin{aligned} \nabla_Z \bar{g}(X, Y) &= 2\psi(Z)\bar{g}(X, Y) + \psi(X)\bar{g}(Y, Z) + \psi(Y)\bar{g}(X, Z) \\ &\quad - e\psi(FX)\bar{g}(FY, Z) - e\psi(FY)\bar{g}(FX, Z). \end{aligned}$$

In local form:

$$\bar{g}_{i,j,k} = 2\psi_k \bar{g}_{ij} + \psi_i \bar{g}_{jk} + \psi_j \bar{g}_{ik} - e\psi_{\bar{i}} \bar{g}_{\bar{j}\bar{k}} - e\psi_{\bar{j}} \bar{g}_{\bar{i}\bar{k}},$$

where “ $\bar{\cdot}$ ” denotes the covariant derivative on  $K_n$ . It is known that

$$\psi_i = \partial_i \Psi, \quad \Psi = \frac{1}{2(n+2)} \ln \left| \frac{\det \bar{g}}{\det g} \right|, \quad \partial_i = \partial / \partial x^i.$$

Domashev, Kurbatova and Mikeš [3, 6, 16] proved that equations (2) and (3) are equivalent to

$$(4) \quad \begin{aligned} \nabla_Z a(X, Y) &= \lambda(X)g(Y, Z) + \lambda(Y)g(X, Z) \\ &\quad - e\lambda(FX)g(FY, Z) - e\lambda(FY)g(FX, Z). \end{aligned}$$

In local form:

$$a_{i,j,k} = \lambda_i g_{jk} + \lambda_j g_{ik} - e\lambda_{\bar{i}} g_{\bar{j}\bar{k}} - e\lambda_{\bar{j}} g_{\bar{i}\bar{k}},$$

where

$$(5) \quad (a) \quad a_{ij} = e^{2\Psi} \bar{g}^{\alpha\beta} g_{\alpha i} g_{\beta j}; \quad (b) \quad \lambda_i = -e^{2\Psi} \bar{g}^{\alpha\beta} g_{\beta i} \psi_\alpha.$$

From (4) follows  $\lambda_i = \partial_i \lambda = \partial_i (\frac{1}{4} a_{\alpha\beta} g^{\alpha\beta})$ . On the other hand [10]:

$$(6) \quad \bar{g}_{ij} = e^{2\Psi} \tilde{g}_{ij}, \quad \Psi = \frac{1}{2} \ln \left| \frac{\det \tilde{g}}{\det g} \right|, \quad \|\tilde{g}_{ij}\| = \|g^{i\alpha} g^{j\beta} a_{\alpha\beta}\|^{-1}.$$

The above formulas are the criterion for holomorphically projective mappings  $K_n \rightarrow \bar{K}_n$ , globally as well as locally.

#### 4. HOLOMORPHICALLY PROJECTIVE MAPPING THEORY FOR $K_n \rightarrow \bar{K}_n$ OF CLASS $C^2$

Let  $K_n$  and  $\bar{K}_n \in C^2$  be  $e$ -Kähler manifolds, then for holomorphically projective mappings  $K_n \rightarrow \bar{K}_n$  the Riemann and the Ricci tensors transform in this way

$$(7) \quad \begin{aligned} (a) \quad \bar{R}_{ijk}^h &= R_{ijk}^h + \delta_k^h \psi_{ij} - \delta_j^h \psi_{ik} - e\delta_k^h \psi_{i\bar{j}} + e\delta_j^h \psi_{i\bar{k}} + 2e\delta_i^h \psi_{j\bar{k}}; \\ (b) \quad \bar{R}_{ij} &= R_{ij} - (n+2)\psi_{ij}, \end{aligned}$$

where  $\psi_{ij} = \psi_{i,j} - \psi_i \psi_j + \psi_{\bar{i}} \psi_{\bar{j}}$  ( $\psi_{ij} = \psi_{ji} = -e\psi_{\bar{i}\bar{j}}$ ).

The tensor of holomorphically projective curvature, which is defined in the following form

$$(8) \quad P_{ijk}^h = R_{ijk}^h + \frac{1}{n+2} (\delta_k^h R_{ij} - \delta_j^h R_{ik} - e\delta_k^h R_{i\bar{j}} + e\delta_j^h R_{i\bar{k}} + 2e\delta_i^h R_{j\bar{k}}),$$

is invariant with respect to holomorphically projective mappings, i.e.  $\bar{P}_{ijk}^h = P_{ijk}^h$ .

The integrability conditions of equations (4) have the following form

$$(9) \quad \begin{aligned} a_{i\alpha}R_{jkl}^\alpha + a_{j\alpha}R_{ikl}^\alpha &= g_{ik}\lambda_{j,l} + g_{jk}\lambda_{i,l} - g_{il}\lambda_{j,k} - g_{jl}\lambda_{i,k} \\ &\quad - eg_{ik}\lambda_{\bar{j},l} - eg_{jk}\lambda_{\bar{i},l} + eg_{il}\lambda_{\bar{j},k} + eg_{jl}\lambda_{\bar{i},k}. \end{aligned}$$

We make the remark that the formulas introduced above, (7), (8) and (9), are not valid when  $K_n \notin C^2$  or  $\bar{K}_n \notin C^2$ .

After contraction with  $g^{jk}$  we get:

$$a_{i\alpha}R_k^\alpha + a_{\alpha\beta}R_{ik}^{\alpha\beta} = e\lambda_{\bar{i},\bar{k}} - (n - 1)\lambda_{i,k},$$

where  $R^\alpha_{il}{}^\beta = g^{\beta k}R^\alpha_{ilk}$ ;  $R_l^\alpha = g^{\alpha j}R_{jl}$  and  $\mu = \lambda_{\alpha,\beta}g^{\alpha\beta}$ .

We contract this formula with  $F_i^j F_k^r$  and from the properties of the Riemann and the Ricci tensors of  $K_n$  we obtain

$$(10) \quad \lambda_{\bar{i},\bar{k}} = -e\lambda_{i,k},$$

and ([3, 9, 10, 15])

$$(11) \quad n\lambda_{i,k} = \mu g_{ik} + a_{i\alpha}R_k^\alpha + a_{\alpha\beta}R_{ik}^{\alpha\beta}.$$

Because  $\lambda_i$  is a gradient-like covector, from equation (11) follows  $a_{i\alpha}R_j^\alpha = a_{j\alpha}R_i^\alpha$ .

From (10) follows that the vector field  $\lambda_{\bar{i}} (\equiv \lambda_\alpha F_i^\alpha)$  is a Killing vector field, i.e.  $\lambda_{\bar{i},j} + \lambda_{\bar{j},i} = 0$ .

### 5. HOLOMORPHICALLY PROJECTIVE MAPPINGS BETWEEN $K_n \in C^r$ ( $r > 2$ ) AND $\bar{K}_n \in C^2$

We proof the following theorem

**Theorem 1.** *If  $K_n \in C^r$  ( $r > 2$ ) admits holomorphically projective mappings onto  $\bar{K}_n \in C^2$ , then  $\bar{K}_n \in C^r$ .*

The proof of this theorem follows from the following lemmas.

**Lemma 1** (see [4]). *Let  $\lambda^h \in C^1$  be a vector field and  $\varrho$  a function. If*

$$(12) \quad \partial_i \lambda^h - \varrho \delta_i^h \in C^1$$

*then  $\lambda^h \in C^2$  and  $\varrho \in C^1$ .*

In a similar way we can prove the following: *if  $\lambda^h \in C^r$  ( $r \geq 1$ ) and  $\partial_i \lambda^h - \varrho \delta_i^h \in C^r$  then  $\lambda^h \in C^{r+1}$  and  $\varrho \in C^r$ .*

**Lemma 2.** *If  $K_n \in C^3$  admits a holomorphically projective mapping onto  $\bar{K}_n \in C^2$ , then  $\bar{K}_n \in C^3$ .*

**Proof.** In this case equations (4) and (11) hold. According to the assumptions  $g_{ij} \in C^3$  and  $\bar{g}_{ij} \in C^2$ . By a simple check-up we find  $\Psi \in C^2$ ,  $\psi_i \in C^1$ ,  $a_{ij} \in C^2$ ,  $\lambda_i \in C^1$  and  $R_{ijk}^h, R^h_{ij}{}^k, R_{ij}, R_i^h \in C^1$ .

From the above-mentioned conditions we easily convince ourselves that we can write equation (11) in the form (12), where

$$\lambda^h = g^{h\alpha}\lambda_\alpha \in C^1, \varrho = \mu/n \text{ and } f_i^h = \frac{1}{n}(-\lambda^\alpha \Gamma_{\alpha i}^h - g^{h\gamma} a_{\alpha\gamma} R_i^\alpha + g^{h\gamma} a_{\alpha\beta} R^{\alpha}_{i\gamma}{}^\beta) \in C^1.$$

From Lemma 1 follows that  $\lambda^h \in C^2$ ,  $\varrho \in C^1$ , and evidently  $\lambda_i \in C^2$ . Differentiating (4) twice we convince ourselves that  $a_{ij} \in C^3$ . From this and formula (6) follows that also  $\Psi \in C^3$  and  $\bar{g}_{ij} \in C^3$ .  $\square$

Further we notice that for holomorphically projective mappings between  $e$ -Kähler manifolds  $K_n$  and  $\bar{K}_n$  of class  $C^3$  holds the following third set of equations [6, 8, 9, 15, 10, 16]:

$$(13) \quad \mu_{,k} = 2\lambda_\alpha R_k^\alpha.$$

If  $K_n \in C^r$  and  $\bar{K}_n \in C^2$ , then by Lemma 2,  $\bar{K}_n \in C^3$  and (13) holds. Because the system (4), (11) and (13) is closed, we can differentiate equations (4)  $(r-1)$  times. So we convince ourselves that  $a_{ij} \in C^r$ , and also  $\bar{g}_{ij} \in C^r$  ( $\equiv \bar{K}_n \in C^r$ ).

**Remark.** Moreover, in this case from equation (13) follows that the function  $\mu \in C^{r-1}$ .

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BRNO UNIVERSITY OF TECHNOLOGY, FACULTY OF CIVIL ENGINEERING,  
DEPARTMENT OF MATHEMATICS, ŽIŽKOVA 17, 602 00 BRNO,  
CZECH REPUBLIC  
*E-mail:* `hinterleitner.irena@seznam.cz`