

## Solution of a polylocal problem using Tchebychev polynomials

Eugen Drăghici, Daniel Pop

### Abstract

Consider the problem:

$$\begin{aligned}Ly(x) &= r(x), \quad -1 \leq x \leq 1, \\y(a) &= A, \quad y(b) = B \\-1 &< a < b < 1, \quad a, b, A, B \in \mathbb{R},\end{aligned}$$

where

$$Ly(x) := -\frac{d}{dx}\left(\frac{dy}{dx}\right) + q(x) \cdot y(x), \quad -1 \leq x \leq 1$$

and

$$q(x), r(x) \in C[-1, 1], \quad y(x) \in C^2[-1, 1].$$

The aim of this paper is to present an approximate solution of this problem based on Tchebychev polynomials. We construct the approximation using Tchebychev-Gauss-Lobatto interpolation nodes. Also we use Maple 10 to obtain numerical results.

Dedicated to the memory of *prof. Alexandru Lupas* (1942-2007)

**2000 Mathematical Subject Classification:** 34B10

## 1 Introduction

The purpose of this paper is to approximate the solution of the following problem:

$$(1) \quad \left\{ \begin{array}{l} Ly(x) = r(x), \quad -1 \leq x \leq 1, \\ y(a) = A, \quad y(b) = B \\ -1 < a < b < 1, \quad a, b, A, B \in \mathbb{R}, \end{array} \right.$$

where:

$$(2) \quad Ly(x) := -\frac{d}{dx}\left(\frac{dy}{dx}\right) + q(x) \cdot y(x), \quad -1 \leq x \leq 1$$

and  $q(x), r(x) \in C[-1, 1]$ ,  $y(x) \in C^2[-1, 1]$ , using a *Collocation method*.

This is not a *two boundary value problem*, since  $-1 < a < b < 1$ .

We have two initial value problem on  $[-1, a]$  and  $[b, 1]$ , respectively, and on  $[a, b]$  a classical boundary value problem, the existence and the uniqueness for (1) assure existence and uniqueness of these problems.

**Historical note.** In 1966, two researchers from Tiberiu Popoviciu Institute of Romanian Academy, Cluj-Napoca, *Dumitru Ripianu and Oleg Arama* published a paper on a polylocal problem, see([6])

## 2 Principles of the method

The implementation is inspired from([2]). Our method is based on first kind *Tchebychev polynomials* ([3]) and ([5]).

**Definition 1** The polynomials  $T_n(x)$ ,  $n \in \mathbb{N}$  defined by :

$$(3) \quad T_n(x) := \cos(n \arccos(x)), x \in [-1, 1]$$

are called the Tchebychev polynomials of the first kind.

**Definition 2** The polynomials  $U_n(x)$ ,  $n \in \mathbb{N}$  defined by:

$$(4) \quad U_n(x) = \frac{\sin(n+1) \cdot \arccos x}{(n+1) \cdot \sqrt{1-x^2}}$$

are called the Tchebychev polynomials of the second kind.

To describe the basic method in this and later section we choose a nonuniform mesh of the given interval  $[-1, 1]$  therefore:

$$(5) \quad \Delta : x_j = \cos \frac{j \cdot \pi}{n}, j = 1, \dots, n .$$

The are the zeros of *Tchebychev polynomials of second kind*.

The form of solution is:

$$(6) \quad u(x) = \sum_{k=0}^{n+1} c_k \cdot T_k(x)$$

where  $T_k(x)$  is the  $k$ -th degree first kind *Tchebychev polynomials* on interval  $[-1, 1]$ .

We shall choose the basis such that the following conditions hold:

- the solution verifies the differential equation

$$(7) \quad Lu(x_j) = r_j, j = 1, 2, \dots, n$$

- the solution verifies

$$(8) \quad u(a) = A, u(b) = B.$$

We choose this mesh (3), because in ([2], pag30) prove that interpolation at *Tchebychev points* is nearly optimal . Since the mesh(3) has  $n$  points, we include the points  $a, b$  and suppose that  $a, b \neq x_j$  for all  $j = 1, 2, \dots, n$ .

**Remark 1** • *If  $a = x_j, b = x_j$  then we increment  $n$ .*

- *the method do not depend on conditions on  $q(x)$ .*
- *The Tchebychev polynomials are generated via the orthopoly package with the Maple sequence:*

$$> S := (x, k, a, b) -> T(k, ((b - a) * x + a + b) / 2) :$$

### 3 Numerical Results

We shall give two examples. For each example we plot the exact and approximate solution and generate the execution profile with the pair *profile-showprofile* see ([4])

- ***First we approximate a oscillating solution :***

$$(9) \quad \begin{aligned} -Z''(t) - 243 \cdot Z(t) &= t; -1 \leq t \leq 1 \\ Z(-1) &= Z(1) = 0 \end{aligned}$$

with conditions:

$$(10) \quad Z\left(-\frac{1}{4}\right) = \frac{-\sin\left(\frac{9\sqrt{3}}{4}\right)}{243 \sin(9\sqrt{3})} + \frac{1}{972}$$

$$(11) \quad Z\left(\frac{1}{2}\right) = \frac{\sin\left(\frac{9\sqrt{3}}{2}\right)}{243 \sin(9\sqrt{3})} - \frac{1}{486}$$

The exact solution provided by *dsolve* is:

$$Z(t) = \frac{\sin(9\sqrt{3}t) - t \sin(9\sqrt{3})}{243 \sin(9\sqrt{3})}$$

Since

$$\int_{-1}^1 |q(x)| dx > 2$$

using disconjugate criteria given by *Lyapunov* (1893) the problem (9) has an oscillatory solution. We used Maple 8 to solve the problem exactly and to approximate the solution, for  $n = 17$  and  $n = 50$ . We also plot the error in semilogarithmic scale.

**The cod Maple is:**

```
> restart; with(orthopoly);with(CodeTools);with(plots):
> S:=(x,k,a,b)->T(k,((b-a)*x+a+b)/2);
S := (x, k, a, b) -> T(k, 1/2 (b - a) x + 1/2 a + 1/2 b)
> genceb:=proc(x,n,q,r,c0,d0,alpha,beta)
> local k, ecY, ecd, C, h, Y, c, a, b;
> global S;
> a:=x[0]; b:=x[n-1];
> Y:=0;
```

```

> for k from 0 to n+1 do
> Y:=Y+c[k]*S(t,k,a,b);
> end do;
> Y:=simplify(Y);
> ecY:=-diff(Y,t$2)+q(t)*Y=r(t):
> ecd:=Array(0..n+1);
> for k from 0 to n-1 do
> ecd[k]:=eval(ecY,t=x[k]):
> end do;
> ecd[n]:=eval(Y,t=c0)=alpha:
> ecd[n+1]:=eval(Y,t=d0)=beta:
> C:=solve({seq(ecd[k],k=0..n+1)},[seq(c[k],k=0..n+1)]);
> assign(C):
> return Y:
> end proc:

>#we define the function from differential equations
> q:=t->-243: r:=t->t:
> ecz:=-diff(Z(t),t$2)+q(t)*Z(t)=r(t):
> dsolve({ecz,Z(-1)=0,Z(1)=0},Z(t)):simplify(%):
> assign(%):
> n:=17: b:=1: a:=-1: c0:=-1/4: d0:=1/2:alpha:=eval(Z(t),t=c0);
>beta=eval(Z(t),t=d0);
> u:=[-1/4,seq((b-a)/2*cos(k*Pi/n)+(a+b)/2,k=1..n),1/2]:
> u:=sort(evalf(u)):
> n:=nops(u);x:=Array(0..n-1,u):

```

```

> eval(x):
> profile(genceb): Y:=genceb(x,n,q,r,-1/4,1/2,alpha,beta)
> plot(Y,t=-1..1,title=" Approx TCHEBYCHEV");
> plot(Z(t),t=-1..1,color=[GREEN],title="Exact Solution");
> p1:=plot([Y,Z(t)],t=-1..1,title="Exact&Approx.solution;n=17");
> p2:=plots[pointplot]([[-1/4,eval(Z(t),t=-1/4)],[1/2,eval(Z(t),t=1/2)]],
> symbol=circle,symbolsize=30,color=[BLACK]):
> plots[display]({p1,p2});showprofile(genceb);
> plot(log(Y-Z(t)),t=-0.99..0.99,title="Error in Semilog. scale;n=17",
color=[BLUE]);
> #quit

```

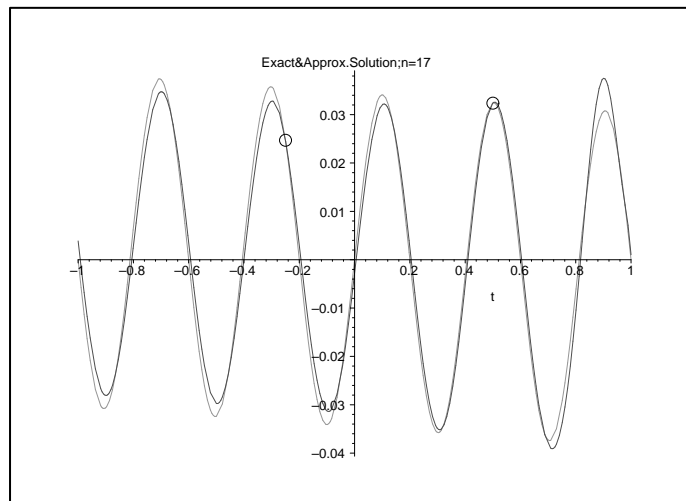


Fig. 1. The graph of exact and approximate solution, oscillating problem,  $n=17$

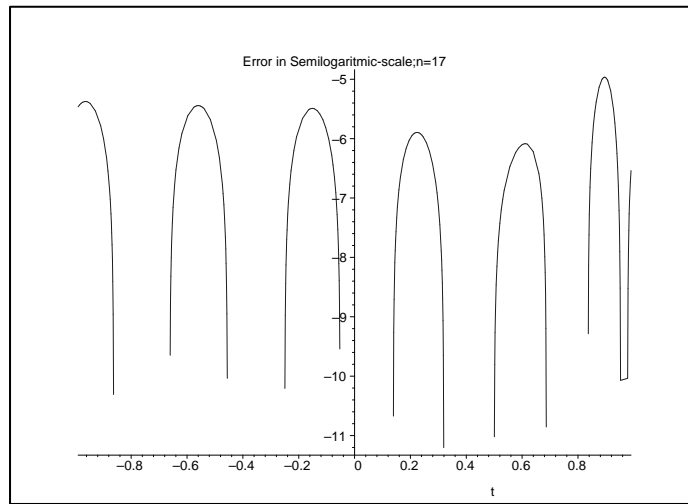


Fig. 2. Error plot, oscillating problem, n=17

Here are the profiles for the procedure in the case of oscillating solution:

function	depth	calls	time	time%	bytes	bytes%
genceb	1	1	1.907	100.00	37992012	100.00
total	1	1	1.907	100.00	37992012	100.00

**For**  $n = 50$ , we obtain a very good approximation , but we must increase the number of decimals with Maple command:

```
> Digits := 18;
```



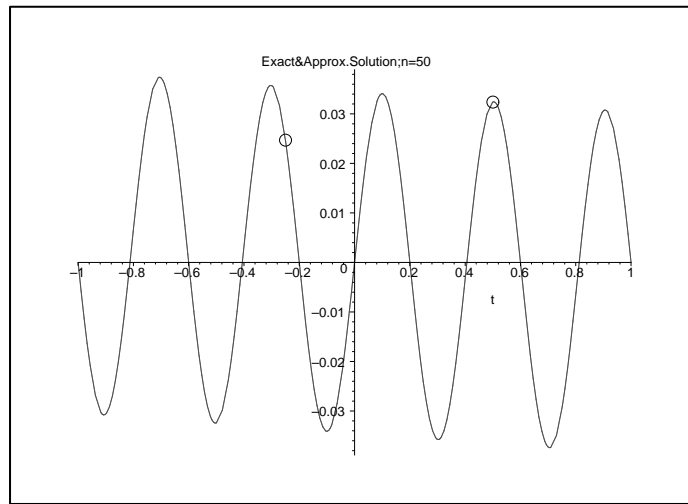


Fig. 3. The graph of exact and approximate solution, oscillating problem,  $n=50$

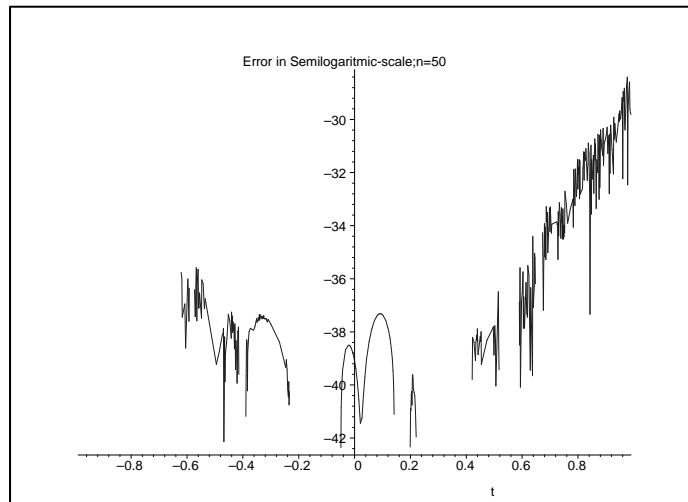


Fig. 4. Error plot, oscillating problem,  $n=50$

Here are the profiles for the procedures in the case of oscillating problem.

Here are the profiles for the procedure in the case of oscillating solution:

function	depth	calls	time	time%	bytes	bytes%
genceb	1	1	28.749	100.00	455186448	100.00
total	1	1	28.749	100.00	455186448	100.00

• ***The second example is a nonoscillating solution.***

Example is from ([1, page 560]).

$$(12) \quad \begin{aligned} -y'' - y &= x, & x \in [-1, 1] \\ y(-1) &= y(1) = 0 \end{aligned}$$

with conditions:

$$\begin{aligned} y\left(-\frac{1}{4}\right) &= -\frac{\sin \frac{1}{4}}{\sin 1} + \frac{1}{4} \\ y\left(\frac{1}{2}\right) &= \frac{\sin \frac{1}{2}}{\sin 1} - \frac{1}{2} \end{aligned}$$

The exact solution given by *d*solve is  $y(t) = -\frac{-\sin(t)+t\sin 1}{\sin 1}$ . Since

$$\int_{-1}^1 |q(x)| dx \leq 2$$

using disconjugate criteria given by *Lyapunov* (1893) the problem (12) has an nonoscillatory solution. For  $n = 10$ , we plot the graph of exact solution and approximation.

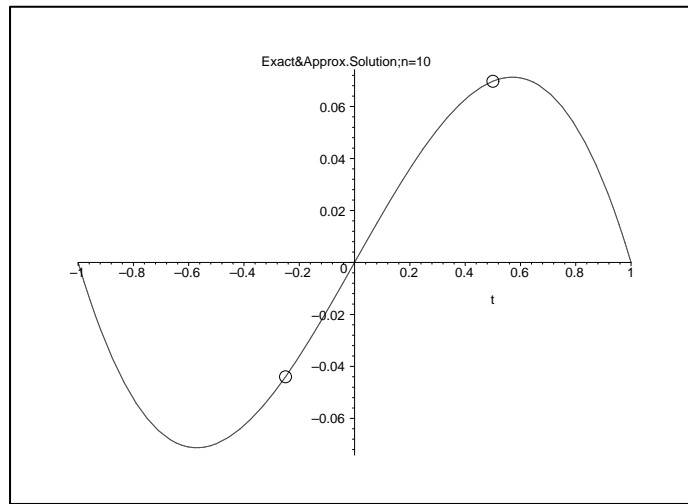


Fig. 5. The graph of exact and approximate solution, non oscillating problem,  $n=10$

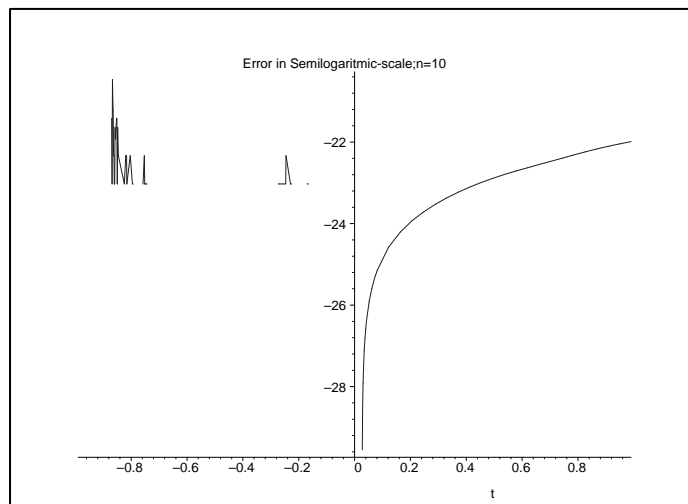


Fig. 6. Error plot, non oscillating problem

The profile in this case is:

function	depth	calls	time	time%	bytes	bytes%
genceb	1	1	0.406	100.00	9541308	100.00
total	1	1	0.406	100.00	9541308	100.00

## 4 Acknowledgements

It is a pleasure to thank:

- prof. dr. Ion Păvăloiu ("Tiberiu-Popovici", Cluj-Napoca ,
- conf. dr Radu Tiberiu Trimbitas ("Babes-Bolyai" University Cluj-Napoca)

for introducing us to the subject matter of this paper.

## References

- [1] R.L. Burden, J.D. Faires, *Numerical Analysis*, PWS Kent Publishing Company, Boston, Massachusetts: 1985.
- [2] C.De Boor, *A practical guide to splines*, Springer-verlag, New York, Heidelberg, Berlin, 1978

- [3] C.Gheorghiu, *Spectral Methods for differential Problems*, Casa Cartii de Stiinta, Cluj-Napoca, 2007.
- [4] A.Heck, *Introduction to Maple*, second edition, Springer-Verlag, 1997
- [5] A.Lupaş *Metode Numerice*, Editura Constant, Sibiu, 2000.
- [6] D.Ripianu, O.Arama, *Quelque recherche actuelles concernant l'equations de Ch. de la Valee Poussin relative au probleme polylocal dans la Theorie des equations differentielles*, Studia Mathematica, 8(31) pp. 19-28, 1966.

Eugen Drăghici

"Lucian Blaga" University

Department of Mathematics

Sibiu, Romania

e-mail: edraghici@gmail.com

Daniel Pop

Ro-Ger University Sibiu

Sibiu, Romania