Research Article

# Variational-Like Inequalities and Equilibrium Problems with Generalized Monotonicity in Banach Spaces

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We introduce the notion of relaxed  $(\rho - \theta) - \eta$ -invariant pseudomonotone mappings, which is weaker than invariant pseudomonotone maps. Using the KKM technique, we establish the existence of solutions for variational-like inequality problems with relaxed  $(\rho - \theta) - \eta$ -invariant pseudomonotone mappings in reflexive Banach spaces. We also introduce the concept of  $(\rho - \theta)$ -pseudomonotonicity for bifunctions, and we consider some examples to show that  $(\rho - \theta)$ pseudomonotonicity generalizes both monotonicity and strong pseudomonotonicity. The existence of solution for equilibrium problem with  $(\rho - \theta)$ -pseudomonotone mappings in reflexive Banach spaces are demonstrated by using the KKM technique.

### **1. Introduction**

Let *K* be a nonempty subset of a real reflexive Banach space *X*, and let *X*<sup>\*</sup> be the dual space of *X*. Consider the operator  $T : K \to X^*$  and the bifunction  $\eta : K \times K \to X$ . Then the variational-like inequality problem (in short, VLIP) is to find  $\overline{x} \in K$ , such that

$$\langle T\overline{x}, \eta(y, \overline{x}) \rangle \ge 0, \quad \forall y \in K,$$
 (1.1)

where  $\langle \cdot, \cdot \rangle$  denote the pairing between *X* and *X*<sup>\*</sup>.

If we take  $\eta(x, y) = x - y$ , then (1.1) becomes to find  $\overline{x} \in K$ , such that

$$\langle T\overline{x}, y - \overline{x} \rangle \geq 0, \quad \forall y \in K,$$
 (1.2)

which is classical variational inequality problems (VIPs). These problems have been studied in both finite and infinite dimensional spaces by many authors [1–3]. VIP has numerous applications in optimization, nonlinear analysis, and engineering sciences.

In the study of VLIP and VIP, monotonicity is the most common assumption for the operator *T*. Recently many authors established the existence of solutions for (VIP) and VLIP under generalized monotonicity assumptions, such as quasimonotonicity, relaxed monotonicity, densely pseudomonotonicity, relaxed  $\eta$ - $\alpha$ -monotonicity, and relaxed  $\eta$ - $\alpha$ -pseudomonotonicity (see [1, 3–6] and the references therein). In 2008 [7], Behera et al. defined various concepts of generalized ( $\rho$ - $\theta$ )- $\eta$ -invariant monotonicities which are proper generalization of generalized invariant monotonicity introduced by Yang et al. [8]. Chen [9] defined semimonotonicity and studied semimonotone scalar variational inequalities problems in Banach spaces. Fang and Huang [3] obtained the existence of solution for VLIP using relaxed  $\eta$ - $\alpha$ -monotone mappings in the reflexive Banach spaces. In [1], Bai et al. extended the results of [3] with relaxed  $\eta$ - $\alpha$ -pseudomonotone mappings and provided the existence of solution of the variational-like inequalities problems in reflexive Banach spaces. Bai et al. [10] studied variational inequalities problems with the setting of densely relaxed  $\mu$ -pseudomonotone operators and relaxed  $\mu$ -quasimonotone operators, respectively.

Inspired and motivated by [1, 3, 10], we introduce the concept of relaxed  $(\rho-\theta)$ - $\eta$ -invariant pseudomonotone mappings. Using the KKM technique, we establish the existence of solutions for Variational-like inequality problems with relaxed  $(\rho-\theta)-\eta$ -invariant pseudomonotone mappings. We also introduce the notion of  $(\rho-\theta)$ -pseudomonotonicity for bifunctions, and study some examples to show that  $(\rho-\theta)$ -pseudomonotonicity is proper generalization of monotonicity and the strong pseudomonotonicity. The existence of solutions of equilibrium problem with  $(\rho-\theta)$ -pseudomonotone mappings in reflexive Banach spaces are demonstrated, by using the KKM technique.

#### 2. Preliminaries

Let *X* be a real reflexive Banach space and *K* be a nonempty subset of *X*, and *X*<sup>\*</sup> be the space of all continuous linear functionals on *X*. Consider the functions  $T : K \to X^*$ ,  $\eta : K \times K \to X$  and  $\theta : K \times K \to \mathbb{R}$  and  $\rho \in \mathbb{R}$ .

*Definition 2.1.* The operator  $T : K \to X^*$  is said to be relaxed  $(\rho - \theta) - \eta$ -invariant pseudomonotone mapping with respect to  $\eta$  and  $\theta$ , if for any pair of distinct points  $x, y \in K$ , one has

$$\langle Tx, \eta(y, x) \rangle \ge 0 \Longrightarrow \langle Ty, \eta(x, y) \rangle + \rho |\theta(x, y)|^2 \le 0.$$
 (2.1)

*Remark* 2.2. (i) If we take  $\rho = 0$  then from (2.1) it follows that  $\langle Tx, \eta(y, x) \rangle \ge 0 \Rightarrow \langle Ty, \eta(x, y) \rangle \le 0$ , for all  $x, y \in K$ , here *T* is said to be invariant pseudomonotone, see [8].

(ii) If we take  $\rho = 0$ , and  $\eta(x, y) = x - y$ , then (2.1) reduces to  $\langle Tx, y - x \rangle \ge 0 \Rightarrow \langle Ty, x - y \rangle \le 0$ , for all  $x, y \in K$ , and *T* is said to be pseudomonotone map.

(iii) If  $\theta(x, y) = ||x - y||$ ,  $\eta(x, y) = x - y$ ,  $\rho < 0$ , that is, let  $\rho = -\mu^2$  (where  $\mu \in \mathbb{R}$ ). Then (2.1) follows that  $\langle Tx, y - x \rangle \ge 0 \Rightarrow \langle Ty, y - x \rangle \ge -\mu^2 ||x - y||^2$ , and *T* is called relaxed  $\mu$ -pseudomonotone mapping [10].

It is obvious that every invariant pseudomonotone mapping is relaxed  $(\rho - \theta) - \eta$ invariant pseudomonotone. However, the converse is not true in general, which is illustrated by the following counterexample. *Example 2.3.* Let  $K = [0, \pi/2]$  and  $T : [0, \pi/2] \rightarrow \mathbb{R}$  be defined by

$$Tx = \sin x - 1. \tag{2.2}$$

Let the functions  $\eta$  and  $\theta$  be defined by

$$\eta(x, y) = \cos x - \cos y,$$

$$\theta(y, x) = \begin{cases} \sqrt{\cos x - \cos y}, & x \le y; \\ 1, & y < x. \end{cases}$$
(2.3)

Now,  $\langle Tx, \eta(y, x) \rangle = (\sin x - 1)(\cos y - \cos x) \ge 0$ , when  $x \le y$  or  $x = \pi/2$ . Take  $\rho = -3$ , then

$$\langle Ty, \eta(x,y) \rangle - 3 |\theta(y,x)|^2 = (\sin y - 1)(\cos x - \cos y) - 3(\cos x - \cos y), \quad x \le y$$
  
=  $(\cos x - \cos y)(\sin y - 4)$  (2.4)  
 $\le 0.$ 

Therefore *T* is relaxed  $(\rho - \theta) - \eta$ -invariant pseudomonotone mapping with respect to  $\eta$  and  $\theta$ . But *T* is not invariant pseudomonotone mapping with respect to the same  $\eta$ . In fact, if we take  $x = \pi/2$  and y = 0. Therefore we have

$$\langle Tx, \eta(y, x) \rangle = 0. \tag{2.5}$$

However,

$$\langle Ty, \eta(x, y) \rangle = (-1) \left( \cos \frac{\pi}{2} - \cos 0 \right) = 1 > 0.$$
 (2.6)

*Definition 2.4.* The operator  $T : K \to X^*$  is said to be relaxed  $(\rho - \theta) - \eta$ -invariant quasimonotone mapping with respect to  $\eta$  and  $\theta$ , if for any pair of distinct points  $x, y \in K$ , one has

$$\langle Tx, \eta(y, x) \rangle > 0 \Longrightarrow \langle Ty, \eta(x, y) \rangle + \rho |\theta(x, y)|^2 \le 0.$$
 (2.7)

Next, we will show that relaxed  $(\rho - \theta) - \eta$ -invariant quasimonotonicity and relaxed  $(\rho - \theta) - \eta$ -invariant pseudomonotonicity coincide under some conditions. For this we need the following  $\eta$ -hemicontinuity definition.

*Definition* 2.5 (see [3]). Let  $T : K \to X^*$  and  $\eta : K \times K \to X$ . *T* is said to be  $\eta$ -hemicontinuous if for any fixed  $x, y \in K$ , the mapping  $f : [0,1] \to \mathbb{R}$  defined by  $f(t) = \langle T(x+t(y-x)), \eta(y,x) \rangle$  is continuous at 0<sup>+</sup>.

**Lemma 2.6.** Let *T* be an  $\eta$ -hemicontinuous and relaxed ( $\rho$ - $\theta$ )- $\eta$ -invariant quasimonotone on *K*. Assume that the mapping  $x \mapsto \langle Ty, \eta(x, y) \rangle$  is concave and  $\theta : K \times K \to \mathbb{R}$  is hemicontinuous in the second argument. Then for every  $x, y \in K$  with  $\langle Ty, \eta(x, y) \rangle \ge 0$  one has either  $\langle Tx, \eta(y, x) \rangle + \rho |\theta(y, x)|^2 \le 0$  or  $\langle Ty, \eta(z, y) \rangle \le 0$ , for all  $z \in K$ .

*Proof.* Suppose there exists some  $z \in K$  such that  $\langle Ty, \eta(z, y) \rangle > 0$ . Then we have to prove that  $\langle Tx, \eta(y, x) \rangle + \rho |\theta(x, y)|^2 \leq 0$ .

Let  $x_t = tz + (1 - t)x$ ,  $0 < t \le 1$ . Then

$$\langle Ty, \eta(x_t, y) \rangle \ge t \langle Ty, \eta(z, y) \rangle + (1 - t) \langle Ty, \eta(x, y) \rangle$$
  
> 0. (2.8)

Since *T* is relaxed  $(\rho - \theta) - \eta$ -invariant quasimonotone on *K*, we have

$$\langle Tx_t, \eta(y, x_t) \rangle + \rho |\theta(y, x_t)|^2 \le 0.$$
(2.9)

Since *T* is  $\eta$ -hemicontinuous and  $\theta$  is hemicontinuous in the first variable and letting  $t \to 0$ , we have

$$\langle Tx, \eta(y, x) \rangle + \rho |\theta(y, x)|^2 \le 0.$$
 (2.10)

Denote  $K^{\perp} = \{z \in K^* : \langle z, \eta(x, y) \rangle = 0$ , for all  $x, y \in K\}$ , and

$$T(K) = \{Tx : x \in K\}$$
(2.11)

*Definition* 2.7. A point  $x_0 \in K$  is said to be a  $\eta$ -positive point of  $T : K \to X^*$  on K if for all  $x \in K$ , either  $Tx \in K^{\perp}$  or there exists  $y \in K$  such that  $\langle Tx, \eta(y, x_0) \rangle > 0$ .

Let  $K_T$  denotes the set of all  $\eta$ -positive points of T on K. Now we give a characterization of relaxed ( $\rho$ - $\theta$ )- $\eta$ -invariant pseudomonotone.

**Lemma 2.8.** Let T be  $\eta$ -hemicontinuous and relaxed  $(\rho-\theta)-\eta$ -invariant quasimonotone on K with  $T(K) \cap K^{\perp} = \phi$ . Assume that the mapping  $x \mapsto \langle Ty, \eta(x, y) \rangle$  is concave and  $\theta$  is hemicontinuous. Then T is relaxed  $(\rho-\theta)-\eta$ -invariant pseudomonotone on  $K_T$ .

*Proof.* Let  $x, y \in K_T$  with  $\langle Tx, \eta(y, x) \rangle \ge 0$ . Therefore by the previous Lemma, we have either

$$\langle Ty, \eta(x,y) \rangle + \rho |\theta(x,y)|^2 \le 0 \text{ or } \langle Tx, \eta(z,y) \rangle \le 0, \quad \forall z \in K.$$
 (2.12)

Now we will show that the second inequality in (2.12) is impossible. In fact, since  $x \in K_T$  and  $Tx \notin K^{\perp}$ , there exists  $z \in K$  such that  $\langle Tx, \eta(z, x) \rangle > 0$ , which shows that the second inequality in (2.12) is impossible. Therefore,

$$\langle Ty, \eta(x, y) \rangle + \rho |\theta(x, y)|^2 \le 0,$$
 (2.13)

hence *T* is relaxed  $(\rho - \theta) - \eta$ -invariant pseudomonotone on  $K_T$ .

*Remark* 2.9. Lemmas 2.6 and 2.8 generalize Bai et al. [10] results [Lemma 2.1 and Proposition 2.1] from the case of relaxed  $\mu$ -quasimonotone operators to relaxed ( $\rho$ - $\theta$ )- $\eta$ -invariant quasimonotone operators.

*Definition 2.10.* Let  $f : K \to 2^X$  be a set-valued mapping. Then f is said to be KKM mapping if for any  $\{y_1, y_2, \ldots, y_n\}$  of K one has  $co\{y_1, y_2, \ldots, y_n\} \subset \bigcup_{i=1}^n f(y_i)$ , where  $co\{y_1, y_2, \ldots, y_n\}$  denotes the convex hull of  $y_1, y_2, \ldots, y_n$ .

**Lemma 2.11** (see [11]). Let M be a nonempty subset of a Hausdorff topological vector space X and let  $f : M \to 2^X$  be a KKM mapping. If f(y) is closed in X for all  $y \in M$  and compact for some  $y \in M$ , then  $\bigcap_{y \in M} f(y) \neq \phi$ .

**Theorem 2.12** (see [12]). Bounded, closed, convex subset of a reflexive Banach space is weakly compact.

## **3. VLIP with Relaxed** $(\rho - \theta) - \eta$ -Invariant Pseudomonotonicity

In this section, we establish the existence of the solution for VLIP, using relaxed  $(\rho - \theta) - \eta$ -invariant pseudomonotone mappings in reflexive Banach spaces.

**Theorem 3.1.**  $T : K \to X^*$  is  $\eta$ -hemicontinuous and relaxed ( $\rho$ - $\theta$ )- $\eta$ -invariant pseudomonotone mapping. Let the following hold:

- (i)  $\eta(x, y) + \eta(y, x) = 0$ , and  $\theta(x, y) + \theta(y, x) = 0$ , for all  $x, y \in K$ ;
- (ii)  $\theta(x, y)$  is convex in second argument and concave in first argument;
- (iii) for a fixed  $z, y \in K$ , the mapping  $x \mapsto \langle Tz, \eta(x, y) \rangle$  is convex.

Then the following problems (a) and (b) are equivalent:

- (a) find  $x \in K$ ,  $\langle Tx, \eta(y, x) \rangle \ge 0$ , for all  $y \in K$ ;
- (b) find  $x \in K$ ,  $\langle Ty, \eta(x, y) \rangle + \rho |\theta(x, y)|^2 \le 0$ , for all  $y \in K$ .

*Proof.* Assume that  $\overline{x}$  is a solution of (a). Therefore, (b) follows from the definition of relaxed  $(\rho - \theta) - \eta$ -invariant pseudomonotonicity of *T*.

Conversely, suppose that there exists an  $\overline{x} \in K$  satisfying (b), that is,

$$\langle Ty, \eta(\overline{x}, y) \rangle + \rho |\theta(\overline{x}, y)|^2 \le 0, \quad \forall y \in K.$$
 (3.1)

Choose any point  $y \in K$  and consider  $x_t = ty + (1 - t)\overline{x}, t \in (0, 1]$ , then  $x_t \in K$ .

*Case I.* When  $\rho = 0$ . Therefore from (3.1) we have

$$\langle Tx_t, \eta(\overline{x}, x_t) \rangle \leq 0,$$

$$\langle Tx_t, -\eta(x_t, \overline{x}) \rangle \leq 0,$$

$$\langle Tx_t, \eta(x_t, \overline{x}) \rangle \geq 0.$$

$$(3.2)$$

Now,

$$\langle Tx_t, \eta(x_t, \overline{x}) \rangle \le t \langle Tx_t, \eta(y, \overline{x}) \rangle + (1-t) \langle Tx_t, \eta(\overline{x}, \overline{x}) \rangle = t \langle Tx_t, \eta(y, \overline{x}) \rangle.$$
(3.3)

From (3.2) and (3.3) we have

$$\langle Tx_t, \eta(y, \overline{x}) \rangle \ge 0.$$
 (3.4)

Since *T* is  $\eta$ -hemicontinuous in the first argument and taking  $t \to 0$  we get

$$\langle T\overline{x}, \eta(y, \overline{x}) \rangle \ge 0, \quad \forall \ y \in K.$$
 (3.5)

Case II. When  $\rho < 0$ , let  $\rho = -k^2$ . From (3.1) we have

$$\langle Tx_t, \eta(\overline{x}, x_t) \rangle \leq k^2 |\theta(\overline{x}, x_t)|^2,$$

$$\Rightarrow \langle Tx_t, \eta(x_t, \overline{x}) \rangle \geq -k^2 |\theta(\overline{x}, x_t)|^2.$$

$$(3.6)$$

From (ii), (iii), (3.3), and (3.6) we get,

$$t\langle Tx_t, \eta(y,\overline{x})\rangle \ge -k^2 t^2 |\theta(\overline{x},y)|^2 \text{ which implies } \langle Tx_t, \eta(y,\overline{x})\rangle \ge -k^2 t |\theta(\overline{x},y)|^2.$$
(3.7)

Since *T* is  $\eta$ -hemicontinuous and taking  $t \to 0$  we have

$$\langle T\overline{x}, \eta(y, \overline{x}) \rangle \ge 0, \quad \forall y \in K.$$
 (3.8)

Case III. When  $\rho > 0$ , let  $\rho = k^2$ . From (3.1) we have

$$\langle Tx_t, \eta(\overline{x}, x_t) \rangle \leq -k^2 |\theta(\overline{x}, x_t)|^2$$

$$\Rightarrow \langle Tx_t, \eta(x_t, \overline{x}) \rangle \geq k^2 |\theta(\overline{x}, x_t)|^2.$$

$$(3.9)$$

From (i), (ii), (iii), (3.3), and (3.9) we get,

$$\langle Tx_t, \eta(y,\overline{x}) \rangle \ge k^2 t |\theta(y,\overline{x})|^2.$$
 (3.10)

Since *T* is  $\eta$ -hemicontinuous and taking  $t \to 0$  we have

$$\langle T\overline{x}, \eta(y, \overline{x}) \rangle \ge 0, \quad \forall y \in K.$$
 (3.11)

**Theorem 3.2.** Let *K* be a nonempty bounded closed convex subset of a real reflexive Banach space X.  $T: K \rightarrow X^*$  is  $\eta$ -hemicontinuous and relaxed ( $\rho$ - $\theta$ )- $\eta$ -invariant pseudomonotone mapping. Let the following hold:

- (i)  $\eta(x, y) + \eta(y, x) = 0$ , and  $\theta(x, y) + \theta(y, x) = 0$ , for all  $x, y \in K$ ;
- (ii)  $\theta(x, y)$  is convex in second argument and concave in first argument, and lower semicontinuous in the first argument;
- (iii) for a fixed  $z, y \in K$ , the mapping  $x \mapsto \langle Tz, \eta(x, y) \rangle$  is convex and lower semicontinuous.

Then the problem (1.1) has a solution.

*Proof.* Consider the set valued mappings  $F : K \to 2^X$  and  $G : K \to 2^X$  such that

$$F(y) = \{x \in K : \langle Tx, \eta(y, x) \rangle \ge 0\}, \quad \forall y \in K,$$
  

$$G(y) = \{x \in K : \langle Ty, \eta(x, y) \rangle + \rho |\theta(x, y)|^2 \le 0\}, \quad \forall y \in K.$$
(3.12)

It is easy to see that  $\overline{x} \in K$  solves the VLIP if and only if  $\overline{x} \in \bigcap_{y \in K} F(y)$ . Thus it suffices to prove  $\bigcap_{y \in K} F(y) \neq \phi$ . To prove this, first we will show that *F* is a KKM mapping.

If possible let *F* not be a KKM mapping. Then there exists  $\{x_1, x_2, ..., x_m\} \in K$  such that  $co\{x_1, x_2, ..., x_m\} \not\subseteq \bigcup_{i=1}^m F(x_i)$ , that means there exists a  $x_0 \in co\{x_1, x_2, ..., x_m\}$ ,  $x_0 = \sum_{i=1}^m t_i x_i$  where  $t_i \ge 0$ , i = 1, 2, ..., m,  $\sum_{i=1}^m t_i = 1$ , but  $x_0 \notin \bigcup_{i=1}^m F(x_i)$ .

Hence,  $(Tx_0, \eta(x_i, x_0)) < 0$ ; for i = 1, 2, ..., m.

From (i) and (iii) it follows that

$$0 = \left\langle Tx_0, \eta(x_0, x_0) \right\rangle \le \sum_{i=1}^m t_i \left\langle Tx_0, \eta(x_i, x_0) \right\rangle < 0, \tag{3.13}$$

which is a contradiction. Hence *F* is a KKM mapping.

From the relaxed  $(\rho - \theta) - \eta$ -invariant pseudomonotonicity of *T* it follows that  $F(y) \subset G(y)$ , for all  $y \in K$ . Therefore *G* is also a KKM mapping.

Since *K* is closed bounded and convex, it is weakly compact. From the assumptions, we know that G(y) is weakly closed for all  $y \in K$ . In fact, because  $x \mapsto \langle Tz, \eta(x, y) \rangle$  and  $x \mapsto \rho |\theta(x, y)|^2$  are lower semicontinuous. Therefore, G(y) is weakly compact in *K*, for each  $y \in K$ . Therefore from Lemma 2.11 and Theorem 3.1 it follows that  $\bigcap_{y \in K} F(y) = \bigcap_{y \in K} G(y) \neq \phi$ . So there exists  $\overline{x} \in K$  such that  $\langle T\overline{x}, \eta(y, \overline{x}) \rangle \ge 0$ , for all  $y \in K$ , that is, (1.1) has a solution.

**Theorem 3.3.** Let K be a nonempty unbounded closed convex subset of a real reflexive Banach space  $X. T : K \to X^*$  is  $\eta$ -hemicontinuous and relaxed ( $\rho$ - $\theta$ )- $\eta$ -invariant pseudomonotone mapping. Let the following hold:

- (i)  $\eta(x, y) + \eta(y, x) = 0$ , and  $\theta(x, y) + \theta(y, x) = 0$ , for all  $x, y \in K$ ;
- (ii)  $\theta(x, y)$  is convex in second argument and concave in first argument, and lower semicontinuous in the first argument;
- (iii) for a fixed  $z, y \in K$ , the mapping  $x \mapsto \langle Tz, \eta(x, y) \rangle$  is convex and lower semicontinuous;
- (iv) *T* is weakly  $\eta$ -coercive, that is, there exits  $x_0 \in K$  such that  $\langle Tx, \eta(x, x_0) \rangle > 0$ , whenever  $||x|| \to \infty$  and  $x \in K$ .

Then (1.1) is solvable.

*Proof.* For r > 0, assume  $K_r = \{y \in K : ||y|| \le r\}$ . Consider the problem: find  $x_r \in K \cap K_r$  such that

$$\langle Tx_r, \eta(y, x_r) \rangle \ge 0, \quad \forall y \in K \cap K_r.$$
 (3.14)

By Theorem 3.2 we know that problem (3.14) has at least one solution  $x_r \in K \cap K_r$ . Choose  $||x_0|| < r$  with  $x_0$  as in condition (iv). Then  $x_0 \in K \cap K_r$  and

$$\langle Tx_r, \eta(x_0, x_r) \rangle \ge 0. \tag{3.15}$$

From (i) we get,

$$\langle Tx_r, \eta(x_0, x_r) \rangle = -\langle Tx_r, \eta(x_r, x_0) \rangle.$$
(3.16)

If  $||x_r|| = r$  for all r, we may choose r large enough so that by the assumption (iv) and (3.16) imply that  $\langle Tx_r, \eta(x_0, x_r) \rangle < 0$ , which contradicts (3.15).

Therefore there exists r such that  $||x_r|| < r$ . For any  $y \in K$ , we can choose 0 < t < 1 small enough such that  $x_r + t(y - x_r) \in K \cap K_r$ .

From (3.14) it follows that

$$0 \leq \langle Tx_r, \eta(x_r + t(y - x_r), x_r) \rangle$$
  

$$\leq t \langle Tx_r, \eta(y, x_r) \rangle + (1 - t) \langle Tx_r, \eta(x_r, x_r) \rangle$$
  

$$= t \langle Tx_r, \eta(y, x_r) \rangle.$$
(3.17)

Hence  $\langle Tx_r, \eta(y, x_r) \rangle \ge 0$ , for all  $y \in K$ .

# **4.** Equilibrium Problem with $(\rho - \theta)$ -Pseudomonotone Mappings

Let *K* be a nonempty subset of a real reflexive Banach space *X*, and consider the bifunction  $f : K \times K \to \mathbb{R}$ . Then the equilibrium problem (in short, EP) is to find  $\overline{x} \in K$ , such that

$$f(\overline{x}, y) \ge 0, \quad \forall y \in K.$$
 (4.1)

Equilibrium problem was first introduced and studied by Blum and Oettli [2] in 1994. EP has many applications in nonlinear analysis, optimization, and game theory. The EP contains many problems as particular cases for examples, mathematical programming problems, complementary problems, Nash equilibrium problems in noncooperative games, variational inequality problems, fixed point problems, and minimax inequality problems.

Next we describe a number of particular cases of EP to explain our interest in EP, which have been discussed in [2].

- (i) Optimization problem: let  $\phi : K \to \mathbb{R}$ , and consider minimization problem
  - (M) find  $\overline{x} \in K$  such that  $\phi(\overline{x}) \leq \phi(y)$ , for all  $y \in K$ . If we set  $f(x, y) = \phi(y) - \phi(x)$ , for all  $x, y \in K$ . Then problems EP and (M) are equivalent.
- (ii) Variational inequality problem: if we define  $f(x, y) = \langle Tx, y-x \rangle$  where  $T : K \to X^*$  is a given mapping, where  $X^*$  denotes the space of all continuous linear maps on *X*. Then EP collapses into the classical VIP which states the following,

(VIP) find  $\overline{x} \in X$  such that  $\overline{x} \in K$ , with  $\langle T\overline{x}, y - \overline{x} \rangle \ge 0$ , for all  $y \in K$ .

- (iii) Fixed point problem: let *X* be a Hilbert space, and *K* is a nonempty closed convex subset of *X*. Let  $T : K \to K$  be a given mapping. Then the fixed point problem is to
  - (FPP) find  $\overline{x} \in K$  such that  $\overline{x} = T\overline{x}$ . Set  $f(x, y) = \langle x - Tx, y - x \rangle$ . Then  $\overline{x}$  solves EP if and only if  $\overline{x}$  is a solution of FPP.

The purpose of this section is to establish the existence of solution for equilibrium problems with  $(\rho - \theta)$ -pseudomonotone mappings in the reflexive Banach spaces. We first introduce the notion of  $(\rho - \theta)$ -monotone mappings and  $(\rho - \theta)$ -pseudomonotone mappings. We also provide some examples to justify that  $(\rho - \theta)$ -monotone mapping generalizes weakly monotone maps, and  $(\rho - \theta)$ -pseudomonotone mapping generalizes pseudomonotone, weakly pseudomonotone maps.

Let *K* be a nonempty subset of a real reflexive Banach space *X*. Consider the function  $f : K \times K \to \mathbb{R}$  and  $\theta : K \times K \to \mathbb{R}$  and  $\rho \in \mathbb{R}$ .

*Definition 4.1.* The function  $f : K \times K \to \mathbb{R}$  is said to be  $(\rho - \theta)$ -monotone with respect to  $\theta : K \times K \to \mathbb{R}$  if, for all  $x, y \in K$ , one has

$$f(x,y) + f(y,x) \le \rho |\theta(x,y)|^2.$$
 (4.2)

When

- (i)  $\rho > 0$  and  $\theta(x, y) = ||x y||$ , *f* is weakly monotone;
- (ii)  $\rho = 0$ , *f* is monotone;
- (iii)  $\rho < 0$  and  $\theta(x, y) = ||x y||$ , *f* is strongly monotone.

We now give an example to show that  $(\rho - \theta)$  monotonicity is a generalization of both monotonicity and weakly monotonicity.

*Example 4.2.* Let K = [1, 10]. Let the functions f and  $\theta$  be defined by

$$f(x,y) = x^2 + y^2 + 1, \qquad \theta(x,y) = \sqrt{2(x^2 + y^2) + 4}.$$
 (4.3)

Then

$$f(x,y) + f(y,x) = 2(x^2 + y^2 + 1)$$

$$\leq \rho(2x^2 + 2y^2 + 4), \quad \text{for any } \rho \geq 1.$$
(4.4)

Therefore *f* is  $(\rho - \theta)$ -monotone with respect to  $\theta$ .

There exists no constant  $\rho > 0$  such that  $f(x, y) + f(y, x) \le \rho ||x - y||^2$ , for all  $x, y \in K$ . As if we assume x and y to be such that their difference is very small, then right-hand side of the inequality tends to zero and left-hand side is always greater than 2. Hence f(x, y) is not weakly monotone. Again since f is positive valued, f is not monotone.

*Definition 4.3.* The function  $f : K \times K \to \mathbb{R}$  is said to be  $(\rho - \theta)$ -pseudomonotone with respect to  $\theta$  if for any pair of distinct points  $x, y \in K$ , one has

$$f(x,y) \ge 0$$
 implies  $f(y,x) \le \rho |\theta(x,y)|^2$ . (4.5)

Every ( $\rho$ - $\theta$ )-monotone mapping is a ( $\rho$ - $\theta$ )-pseudomonotone with respect to the same  $\rho$  and  $\theta$ . However, the converse is not true in general, which follows from the following counterexample.

*Example 4.4.* Let the functions  $f : (0, \pi/2) \times (0, \pi/2) \to \mathbb{R}$  and  $\theta : (0, \pi/2) \times (0, \pi/2) \to \mathbb{R}$  be defined by

$$f(x,y) = (\cos y + 6)^2 - \cos^2 x, \qquad \theta(x,y) = \sqrt{50 + \cos x - \cos y}, \text{ respectively.}$$
(4.6)

Take  $\rho$  = 1. We have to show

$$f(x,y) \ge 0 \quad \text{implies } f(y,x) \le \rho |\theta(x,y)|^2.$$

$$f(x,y) = (\cos y + 6)^2 - \cos^2 x \ge 0, \quad \forall x, y \in \left(0, \frac{\pi}{2}\right).$$

$$(4.7)$$

Now,

$$f(y,x) - \rho |\theta(x,y)|^{2} = (\cos x + 6)^{2} - \cos^{2} y - (50 + \cos x - \cos y)$$
$$= (\cos x + 6)^{2} + \cos y - (50 + \cos^{2} y + \cos x)$$
(4.8)
$$\leq 0.$$

Hence *f* is  $(\rho - \theta)$ -pseudomonotone mapping with respect to  $\theta$ . But *f* is not  $(\rho - \theta)$ -monotone mapping with respect to the same  $\theta$ . In fact,

$$f(x,y) + f(y,x) = (\cos y + 6)^{2} + (\cos x + 6)^{2} - (\cos^{2} x + \cos^{2} y)$$
  
$$\leq |\theta(x,y)|^{2} = (50 + \cos x - \cos y).$$
(4.9)

Note that in the above example, f is neither a monotone nor pseudomonotone mapping.

*Definition 4.5.* The function  $f : K \times K \to \mathbb{R}$  is said to be  $(\rho - \theta)$ -quasimonotone with respect to  $\theta$  if for any pair of distinct points  $x, y \in K$ , one has

$$f(x,y) > 0 \quad \text{implies } f(y,x) \le \rho |\theta(x,y)|^2. \tag{4.10}$$

Next, we will show that  $(\rho - \theta)$ -quasimonotonicity and  $(\rho - \theta)$ -pseudomonotonicity are equivalent under certain conditions.

**Lemma 4.6.** Let f be hemicontinuous and  $(\rho - \theta)$ -quasimonotone on K. Assume that f is concave in the second argument and  $\theta$  is hemicontinuous in the second argument. Then for every  $x, y \in K$  with  $f(y, x) \ge 0$  one has either  $f(x, y) \le \rho |\theta(y, x)|^2$  or  $f(y, z) \le 0$ , for all  $z \in K$ .

*Proof.* Suppose there exists some  $z \in K$  such that f(y, z) > 0. Then we have to prove that  $f(x, y) \le \rho |\theta(x, y)|^2$ .

Let  $x_t = tz + (1 - t)x, 0 < t \le 1$ . Then

$$f(y, x_t) \ge t f(y, z) + (1 - t) f(y, x)$$
  
> 0. (4.11)

Since *T* is relaxed  $(\rho - \theta)$ -quasimonotone on *K*, it implies that

$$f(x_t, y) \le \rho |\theta(y, x_t)|^2.$$
(4.12)

Now letting  $t \to 0$ , we have

$$f(x,y) \le \rho |\theta(y,x)|^2. \tag{4.13}$$

This completes the proof.

**Theorem 4.7.** Let K be a nonempty convex subset of a real reflexive Banach space X. Suppose  $f : K \times K \to \mathbb{R}$  is  $(\rho - \theta)$ -pseudomonotone with respect to  $\theta$  and is hemicontinuous in the first argument with the following conditions:

- (iii)  $\theta(x, y) + \theta(y, x) = 0$ , for all  $x, y \in K$ ;
- (iv)  $\theta$  is convex in first argument and concave in the second argument.

*Then*  $\overline{x} \in K$  *is a solution of* (4.1) *if and only if* 

$$f(y,\overline{x}) \le \rho |\theta(\overline{x},y)|^2, \quad \forall y \in K.$$
 (4.14)

*Proof.* Assume that  $\overline{x}$  is a solution of (4.1) that is,  $f(\overline{x}, y) \ge 0$ , for all  $y \in K$ . Therefore from the definition of  $(\rho - \theta)$  pseudomonotonicity of *T* it follows that

$$f(y,\overline{x}) \le \rho |\theta(\overline{x},y)|^2, \quad \forall y \in K.$$
 (4.15)

Conversely, suppose  $\exists \overline{x} \in K$  satisfying (4.14), that is,

$$f(y,\overline{x}) \le \rho |\theta(\overline{x},y)|^2, \quad \forall y \in K.$$
 (4.16)

Choose any point  $y \in K$  and consider  $x_t = ty + (1 - t)\overline{x}$ ,  $t \in (0, 1]$ , then  $x_t \in K$ .

*Case I.* When  $\rho = 0$ .

Therefore from (4.16) we have

$$f(x_t, \overline{x}) \le 0, \quad \forall y \in K.$$
 (4.17)

Now conditions (i) and (ii) imply that,

$$0 = f(x_t, x_t) \le t f(x_t, y) + (1 - t) f(x_t, \overline{x})$$
  
$$\implies t [f(x_t, \overline{x}) - f(x_t, y)] \le f(x_t, \overline{x}).$$
(4.18)

From (4.17) and (4.18) we have

$$f(x_t, \overline{x}) - f(x_t, y) \le 0, \quad \forall y \in K.$$

$$(4.19)$$

Since *f* is hemicontinuous in the first argument and taking  $t \rightarrow 0$ , it implies that

$$f(\overline{x}, y) \ge 0, \quad \forall y \in K.$$
 (4.20)

Hence  $\overline{x}$  is a solution of (4.1).

*Case II.* When  $\rho < 0$ , let  $\rho = -k^2$ . From (4.16) we have

$$f(x_t, \overline{x}) \le -k^2 |\theta(\overline{x}, x_t)|^2.$$
(4.21)

Now using (4.18), (4.21), and (iv) it follows that

$$f(x_t,\overline{x}) - f(x_t,y) \le -k^2 t \left| \theta(\overline{x},y) \right|^2.$$
(4.22)

Since *f* is hemicontinuous in the first argument and letting  $t \rightarrow 0$ , we get

$$f(\overline{x}, y) \ge 0, \quad \forall y \in K.$$

$$(4.23)$$

*Case III.* When  $\rho > 0$ , let  $\rho = k^2$ .

From (4.16), (4.18), and (iv) we have

$$f(x_t, \overline{x}) \le k^2 |\theta(\overline{x}, x_t)|^2,$$
  
$$\Rightarrow f(x_t, \overline{x}) - f(x_t, y) \le k^2 t |\theta(y, \overline{x})|^2.$$
(4.24)

Since *f* is hemicontinuous in the first argument and taking  $t \rightarrow 0$ , we get

$$f(\overline{x}, y) \ge 0, \quad \forall y \in K.$$
 (4.25)

**Theorem 4.8.** Let K be a nonempty bounded convex subset of a real reflexive Banach space X. Suppose  $f : K \times K \to \mathbb{R}$  is  $(\rho - \theta)$ -pseudomonotone with respect to  $\theta$  and is hemicontinuous in the first argument with the following conditions:

- (i) f(x, x) = 0, for all  $x \in K$ ;
- (ii) for fixed  $z \in K$ , the mapping  $x \mapsto f(z, x)$  is convex and lower semicontinuous;
- (iii)  $\theta(x, y) + \theta(y, x) = 0$ , for all  $x, y \in K$ ;
- (iv)  $\theta$  is convex in first argument and concave in the second argument, and lower semicontinuous in the first argument.

Then the problem (4.1) has a solution.

*Proof.* Consider the two set valued mappings  $F : K \to 2^X$  and  $G : K \to 2^X$  such that

$$F(y) = \{x \in K : f(x, y) \ge 0\}, \quad \forall y \in K,$$
  

$$G(y) = \{x \in K : f(y, x) \le \rho |\theta(x, y)|^2\}, \quad \forall y \in K.$$
(4.26)

It is easy to see that  $\overline{x} \in K$  solves the equilibrium problem (4.1) if and only if  $\overline{x} \in \bigcap_{y \in K} F(y)$ . First to show that F is a KKM mapping. If possible let F not be a KKM mapping. Then there exists  $\{x_1, x_2, \ldots, x_m\} \subset K$  such that  $co\{x_1, x_2, \ldots, x_m\} \not\subseteq \bigcup_{i=1}^m F(x_i)$ , that means there exists a  $x_0 \in co\{x_1, x_2, \ldots, x_m\}$ ,  $x_0 = \sum_{i=1}^m t_i x_i$  where  $t_i \ge 0$ ,  $i = 1, 2, \ldots, m$ ,  $\sum_{i=1}^m t_i = 1$ , but  $x_0 \notin \bigcup_{i=1}^m F(x_i)$ . Hence,  $f(x_0, x_i) < 0$ ; for  $i = 1, 2, \ldots, m$ .

From (i) and (ii) it follows that

$$0 = f(x_0, x_0) \le \sum_{i=1}^{m} t_i f(x_0, x_i) < 0,$$
(4.27)

which is a contradiction. Hence *F* is a KKM mapping.

From the  $(\rho - \theta)$ -pseudomonotonicity of f it follows that  $F(y) \subset G(y)$ , for all  $y \in K$ . Therefore G is also a KKM mapping.

Since *K* is closed bounded and convex, it is weakly compact. From the assumptions, we know that G(y) is weakly closed for all  $y \in K$ . In fact, because  $x \mapsto f(z, x)$  and  $x \mapsto \rho |(\theta(x, z)|^2)$  are lower semicontinuous. Therefore, G(y) is weakly compact in *K*, for each  $y \in K$ 

Therefore from Lemma 2.11 and Theorem 4.7 it follows that  $\bigcap_{y \in K} F(y) = \bigcap_{y \in K} G(y) \neq \phi$ .

So there exists  $\overline{x} \in K$  such that  $f(\overline{x}, y) \ge 0$ , for all  $y \in K$ , that is, (4.1) has a solution.

**Theorem 4.9.** Let *K* be a nonempty unbounded closed convex subset of a real reflexive Banach space *X*. Suppose  $f : K \times K \to \mathbb{R}$  is  $(\rho - \theta)$ -pseudomonotone with respect to  $\theta$  and is hemicontinuous in the first argument and satisfy the following assumptions:

- (i) f(x, x) = 0, for all  $x \in K$ ;
- (ii) for fixed  $z \in K$ , the mapping  $x \mapsto f(z, x)$  is convex and lower semicontinuous;
- (iii)  $\theta(x, y) + \theta(y, x) = 0$ , for all  $x, y \in K$ ;
- (iv)  $\theta$  is convex in first argument and concave in the second argument, and lower semicontinuous in the first argument.
- (v) *f* is weakly coercive, that is, there exists  $x_0 \in K$  such that

$$f(x, x_0) < 0$$
, whenever  $||x|| \to +\infty$ , an  $x \in K$ . (4.28)

Then (4.1) has a solution.

*Proof.* For r > 0, assume  $K_r = \{y \in K : ||y|| \le r\}$ . Consider the problem: find  $x_r \in K \cap K_r$  such that

$$f(x_r, y) \ge 0, \quad \forall y \in K \cap K_r. \tag{4.29}$$

By Theorem 4.8 we know that the problem (4.29) has at least one solution  $x_r \in K \cap K_r$ . Choose  $||x_0|| < r$  with  $x_0$  as in condition (v). Then  $x_0 \in K \cap K_r$  and

$$f(x_r, x_0) \ge 0. \tag{4.30}$$

If  $||x_r|| = r$  for all r, we may choose r large enough so that by the assumption (v) imply that  $f(x_r, x_0) < 0$ , which contradicts (4.30).

Therefore there exists r such that  $||x_r|| < r$ . For any  $y \in K$ , we can choose 0 < t < 1 small enough such that  $x_r + t(y - x_r) \in K \cap K_r$ .

From (4.29) it follows that

$$0 \le f(x_r, x_r + t(y - x_r)) \le tf(x_r, y) + (1 - t)f(x_r, x_r) = tf(x_r, y).$$
(4.31)

Hence  $f(x_r, y) \ge 0$ , for all  $y \in K$ .

#### **5.** Conclusions

The present work has been aimed to theoretically study the existence of solutions for variational-like inequality problems under a new concept relaxed  $(\rho-\theta)-\eta$ -invariant pseudomonotone maps in reflexive Banach spaces. We have also obtained existence of solutions of equilibrium problems with  $(\rho-\theta)$ -pseudomonotone mappings. More research and development activities is therefore needed on generalized monotonicity to demonstrate the equilibrium problem and variational inequality problem.

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