## Research Article

# A General Iterative Method for Variational Inequality Problems, Mixed Equilibrium Problems, and Fixed Point Problems of Strictly Pseudocontractive Mappings in Hilbert Spaces

### Rattanaporn Wangkeeree and Rabian Wangkeeree

Department of Mathematics, Faculty of Science, Naresuan University, Phitsanulok 65000, Thailand

Correspondence should be addressed to Rabian Wangkeeree, rabianw@nu.ac.th

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We introduce an iterative scheme for finding a common element of the set of fixed points of a k-strictly pseudocontractive mapping, the set of solutions of the variational inequality for an inverse-strongly monotone mapping, and the set of solutions of the mixed equilibrium problem in a real Hilbert space. Under suitable conditions, some strong convergence theorems for approximating a common element of the above three sets are obtained. As applications, at the end of the paper we first apply our results to study the optimization problem and we next utilize our results to study the problem of finding a common element of the set of fixed points of two families of finitely k-strictly pseudocontractive mapping, the set of solutions of the variational inequality, and the set of solutions of the mixed equilibrium problem. The results presented in the paper improve some recent results of Kim and Xu (2005), Yao et al. (2008), Marino et al. (2009), Liu (2009), Plubtieng and Punpaeng (2007), and many others.

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#### 1. Introduction

Throughout this paper, we always assume that H is a real Hilbert space with inner product  $\langle \cdot, \cdot \rangle$  and norm  $\|\cdot\|$ , respectively, C is a nonempty closed convex subset of H. Let  $\varphi: C \to \mathbb{R}$  be a real-valued function and let  $\Theta: C \times C \to \mathbb{R}$  be an equilibrium bifunction, that is,  $\Theta(u, u) = 0$  for each  $u \in C$ . Ceng and Yao [1] considered the following mixed equilibrium problem:

Find 
$$x^* \in C$$
 such that  $\Theta(x^*, y) + \varphi(y) \ge \varphi(x^*)$ ,  $\forall y \in C$ . (1.1)

The set of solutions of (1.1) is denoted by MEP( $\Theta$ ,  $\varphi$ ). It is easy to see that  $x^*$  is a solution of problem (1.1) implies that  $x^* \in \text{dom } \varphi = \{x : \varphi(x) < +\infty\}$ .

In particular, if  $\varphi \equiv 0$ , the mixed equilibrium problem (1.1) becomes the following equilibrium problem:

Find 
$$x^* \in C$$
 such that  $\Theta(x^*, y) \ge 0$ ,  $\forall y \in C$ . (1.2)

The set of solutions of (1.2) is denoted by  $EP(\Theta)$ .

If  $\varphi \equiv 0$  and  $\Theta(x, y) = \langle Bx, y - x \rangle \ge 0$  for all  $x, y \in C$ , where B is a mapping form C into H, then the mixed equilibrium problem (1.1) becomes the following variational inequality:

Find 
$$x^* \in C$$
 such that  $\langle Bx^*, y - x^* \rangle \ge 0$ ,  $\forall y \in C$ . (1.3)

The set of solutions of (1.3) is denoted by VI(B,C). The variational inequality has been extensively studied in literature. See, for example, [2-13] and the references therein.

The problem (1.1) is very general in the sense that it includes, as special cases, optimization problems, variational inequalities, minimax problems, Nash equilibrium problem in noncooperative games and others; see for instance, [1, 2, 14, 15].

First we recall some relevant important results as follows.

In 1997, Combettes and Hirstoaga [14] introduced an iterative method of finding the best approximation to the initial data when  $EP(\Theta)$  is nonempty and proved a strong convergence theorem. Subsequently, S. Takahashi and W. Takahashi [16] introduced an iterative scheme by the viscosity approximation method for finding a common element of the set of solutions of  $EP(\Theta)$  and the set of fixed point points of a nonexpansive mapping. Using the idea of S. Takahashi and W. Takahashi [16], Plubtieng and Punpaeng [17] introduced an the general iterative method for finding a common element of the set of solutions of  $EP(\Theta)$  and the set of fixed points of a nonexpansive mapping which is the optimality condition for the minimization problem in a Hilbert space. Furthermore, Yao et al. [11] introduced some new iterative schemes for finding a common element of the set of solutions of  $EP(\Theta)$  and the set of common fixed points of finitely (infinitely) nonexpansive mappings. Very recently, Ceng and Yao [1] considered a new iterative scheme for finding a common element of the set of solutions of  $EP(\Theta)$  and the set of common fixed points of finitely many nonexpansive mappings in a Hilbert space and obtained a strong convergence theorem which used the following condition:

(E)  $K: C \to \mathbb{R}$  is  $\eta$ -strongly convex and its derivative K' is sequentially continuous from the weak topology to the strong topology.

Their results extend and improve the corresponding results in [6, 11, 14]. We note that the condition (E) for the function  $K:C\to\mathbb{R}$  is a very strong condition. We also note that the condition (E) does not cover the case  $K(x)=\|x\|^2/2$  and  $\eta(x,y)=x-y$ . Motivated by Ceng and Yao [1], Peng and Yao [18] introduced a new iterative scheme based on only the extragradient method for finding a common element of the set of solutions of a mixed equilibrium problem, the set of fixed points of a family of finitely nonexpansive mappings and the set of the variational inequality for a monotone Lipschitz continuous mapping. They obtained a strong convergence theorem without the condition (E) for the sequences generated by these processes.

We recall that a mapping  $B: C \to H$  is said to be:

- (i) monotone if  $\langle Bx By, x y \rangle \ge 0$ , for all  $x, y \in C$ ,
- (ii) *L*-Lipschitz if there exists a constant L>0 such that  $||Bx-By||\leq L||x-y||$ , for all  $x,y\in C$ ,
- (iii)  $\alpha$ -inverse-strongly monotone [19, 20] if there exists a positive real number  $\alpha$  such that

$$\langle Bx - By, x - y \rangle \ge \alpha \|Bx - By\|^2, \quad \forall x, y \in C. \tag{1.4}$$

It is obvious that any  $\alpha$ -inverse-strongly monotone mapping B is monotone and Lipschitz continuous. Recall that a mapping  $T:C\to C$  is called a k-strictly pseudocontractive mapping if there exists a constant  $0\leq k<1$  such that

$$||Tx - Ty||^2 \le ||x - y||^2 + k||(I - T)x - (I - T)y||^2, \quad \forall x, y \in C.$$
 (1.5)

Note that the class of k-strictly pseudocontractive mappings strictly includes the class of nonexpansive mappings which are mappings T on C such that

$$||Tx - Ty|| \le ||x - y||, \quad \forall x, y \in C.$$
 (1.6)

That is, T is nonexpansive if and only if T is 0-strictly pseudocontractive. We denote by  $F(T) := \{x \in C : Tx = x\}$  the set of fixed points of T.

Iterative methods for nonexpansive mappings have recently been applied to solve convex minimization problems; see, for example, [21–24] and the references therein. Convex minimization problems have a great impact and influence in the development of almost all branches of pure and applied sciences. A typical problem is to minimize a quadratic function over the set of the fixed points of nonexpansive mapping on a real Hilbert space:

$$\theta(x) = \min_{x \in C} \frac{1}{2} \langle Ax, x \rangle - \langle x, b \rangle, \tag{1.7}$$

where A is a linear bounded operator, C is the fixed point set of a nonexpansive mapping T, and b is a given point in H. Recall that a linear bounded operator A is strongly positive if there is a constant  $\overline{\gamma} > 0$  with property

$$\langle Ax, x \rangle \ge \overline{\gamma} ||x||^2 \quad \forall x \in H.$$
 (1.8)

Recently, Marino and Xu [25] introduced the following general iterative scheme based on the viscosity approximation method introduced by Moudafi [26]:

$$x_{n+1} = (I - \alpha_n A) T x_n + \alpha_n \gamma f(x_n), \quad n \ge 1, \tag{1.9}$$

where A is a strongly positive bounded linear operator on H. They proved that if the sequence  $\{\alpha_n\}$  of parameters satisfies appropriate conditions, then the sequence  $\{x_n\}$  generated by (1.9) converges strongly to the unique solution of the variational inequality

$$\langle (A - \gamma f) x^*, x - x^* \rangle \ge 0, \quad x \in C, \tag{1.10}$$

which is the optimality condition for the minimization problem

$$\min_{x \in C} \frac{1}{2} \langle Ax, x \rangle - h(x), \tag{1.11}$$

where *h* is a potential function for  $\gamma f$  (i.e.,  $h'(x) = \gamma f(x)$  for  $x \in H$ ).

Recall that the construction of fixed points of nonexpansive mappings via Manns algorithm [27] has extensively been investigated in literature; see, for example [27–32] and references therein. If T is a nonexpansive self-mapping of C, then Mann's algorithm generates, initializing with an arbitrary  $x_1 \in C$ , a sequence according to the recursive manner

$$x_{n+1} = \alpha_n x_n + (1 - \alpha_n) T x_n, \quad \forall n \ge 1,$$
 (1.12)

where  $\{\alpha_n\}$  is a real control sequence in the interval (0,1).

If  $T: C \to C$  is a nonexpansive mapping with a fixed point and if the control sequence  $\{\alpha_n\}$  is chosen so that  $\sum_{n=1}^{\infty} \alpha_n (1 - \alpha_n) = \infty$ , then the sequence  $\{x_n\}$  generated by Manns algorithm converges weakly to a fixed point of T. Reich [33] showed that the conclusion also holds good in the setting of uniformly convex Banach spaces with a Fréhet differentiable norm. It is well known that Reich's result is one of the fundamental convergence results. However, this scheme has only weak convergence even in a Hilbert space [34]. Therefore, many authors try to modify normal Mann's iteration process to have strong convergence; see, for example, [35–40] and the references therein.

Kim and Xu [36] introduced the following iteration process:

$$y_n = \beta_n x_n + (1 - \beta_n) T x_n,$$
  

$$x_{n+1} = \alpha_n u + (1 - \alpha_n) y_n, \quad n \ge 1,$$
(1.13)

where T is a nonexpansive mapping of C into itself and  $u \in C$  is a given point. They proved the sequence  $\{x_n\}$  defined by (1.13) strongly converges to a fixed point of T provided the control sequences  $\{\alpha_n\}$  and  $\{\beta_n\}$  satisfy appropriate conditions.

In [41], Yao et al. also modified iterative algorithm (1.13) to have strong convergence by using viscosity approximation method. To be more precisely, they considered the following iteration process:

$$y_n = \beta_n x_n + (1 - \beta_n) T x_n,$$
  

$$x_{n+1} = \alpha_n f(x_n) + (1 - \alpha_n) y_n, \quad n \ge 1,$$
(1.14)

where T is a nonexpansive mapping of C into itself and f is an  $\beta$ -contraction. They proved the sequence  $\{x_n\}$  defined by (1.14) strongly converges to a fixed point of T provided the control sequences  $\{\alpha_n\}$  and  $\{\beta_n\}$  satisfy appropriate conditions.

Very recently, motivated by Acedo and Xu [35], Kim and Xu [36], Marino and Xu [42], and Yao et al. [41], Marino et al. [43] introduced a composite iteration scheme as follows:

$$y_{n} = \beta_{n} x_{n} + (1 - \beta_{n}) T x_{n},$$

$$x_{n+1} = \alpha_{n} \gamma f(x_{n}) + (I - \alpha_{n} A) y_{n}, \quad n \ge 1,$$
(1.15)

where T is a k-strictly pseudocontractive mapping on H, f is an  $\beta$ -contraction, and A is a linear bounded strongly positive operator. They proved that the iterative scheme  $\{x_n\}$  defined by (1.15) converges to a fixed point of T, which is a unique solution of the variational inequality (1.10) and is also the optimality condition for the minimization problem provided  $\{\alpha_n\}$  and  $\{\beta_n\}$  are sequences in [0,1] satisfies the following control conditions:

(C1) 
$$\lim_{n\to\infty}\alpha_n=0$$
,  $\sum_{n=1}^{\infty}\alpha_n=\infty$ ,  $\sum_{n=1}^{\infty}|\alpha_{n+1}-\alpha_n|<\infty$ ,

(C2) 
$$0 \le k \le \beta_n < \varepsilon < 1$$
 for all  $n \ge 0$  and  $\sum_{n=1}^{\infty} |\beta_{n+1} - \beta_n| < \infty$ .

Moreover, for finding a common element of the set of fixed points of a k-strictly pseudocontractive nonself mapping and the set of solutions of an equilibrium problem in a real Hilbert space, Liu [44] introduced the following iterative scheme:

 $x_1 = x \in C$  chosen arbitrarily,

$$\Theta(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge 0, \quad \forall y \in C,$$

$$y_n = \beta_n u_n + (1 - \beta_n) T u_n,$$

$$x_{n+1} = \alpha_n \gamma f(x_n) + (I - \alpha_n A) y_n, \quad n \ge 1,$$

$$(1.16)$$

where T is a k-strictly pseudocontractive mapping on H, f is an  $\alpha$ -contraction and, A is a linear bounded strongly positive operator. They proved that the iterative scheme  $\{x_n\}$  defined by (1.16) converges to a common element of  $F(T) \cap EP(\Theta)$ , which solves some variation inequality problems provided  $\{\alpha_n\}$ ,  $\{\beta_n\}$ , and  $\{r_n\}$  are sequences in [0,1] satisfies the control conditions (C1) and the following conditions:

(C'2) 
$$0 \le k \le \beta_n < \varepsilon < 1$$
 for all  $n \ge 1$ ,  $\lim_{n \to \infty} \beta_n = \varepsilon$ , and  $\sum_{n=1}^{\infty} |\beta_{n+1} - \beta_n| < \infty$ ;

(C3) 
$$\liminf_{n\to\infty} r_n > 0$$
,  $\sum_{n=1}^{\infty} |r_{n+1} - r_n| < 0$ .

All of the above bring us the following conjectures?

Question 1. (i) Could we weaken or remove the control condition  $\sum_{n=1}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty$  on parameter  $\{\alpha_n\}$  in (C1)?

- (ii) Could we weaken or remove the control condition  $\sum_{n=1}^{\infty} |\beta_{n+1} \beta_n| < \infty$  on parameter  $\{\beta_n\}$  in (C2) and (C'2)?
- (iii) Could we weaken or remove the control condition  $\lim_{n\to\infty}\beta_n = \varepsilon$  on the parameter  $\{\beta_n\}$  in (C'2)?
  - (iv) Could we weaken the control condition (C3) on parameters  $\{r_n\}$ ?

(v) Could we construct an iterative algorithm to approximate a common element of  $F(T) \cap VI(B, C) \cap MEP(\Theta, \varphi)$ ?

It is our purpose in this paper that we suggest and analyze an iterative scheme for finding a common element of the set of fixed points of a k-strictly pseudocontractive mapping, the set of solutions of a variational inequality and the set of solutions of a mixed equilibrium problem in the framework of a real Hilbert space. Then we modify our iterative scheme to finding a common element of the set of common fixed points of two finite families of k-strictly pseudocontractive mappings, the set of solutions of a variational inequality and the set of solutions of a mixed equilibrium problem. Application to optimization problems which is one of the motivation in this paper is also given. The results in this paper generalize and improve some well-known results in [17, 36, 41, 43, 44].

#### 2. Preliminaries

Let H be a real Hilbert space with norm  $\|\cdot\|$  and inner product  $\langle\cdot,\cdot\rangle$  and let C be a closed convex subset of H. We denote weak convergence and strong convergence by notations  $\rightharpoonup$  and  $\rightarrow$ , respectively. It is well known that for any  $\lambda \in [0,1]$ ,

$$\|\lambda x + (1 - \lambda)y\|^2 = \lambda \|x\|^2 + (1 - \lambda)\|y\|^2 - \lambda(1 - \lambda)\|x - y\|^2, \quad \forall x, y \in H.$$
 (2.1)

For every point  $x \in H$ , there exists a unique nearest point in C, denoted by  $P_C x$ , such that

$$||x - P_C x|| \le ||x - y|| \quad \forall y \in C. \tag{2.2}$$

 $P_C$  is called the metric projection of H onto C. It is well known that  $P_C$  is a nonexpansive mapping of H onto C and satisfies

$$\langle x - y, P_C x - P_C y \rangle \ge \|P_C x - P_C y\|^2$$
 (2.3)

for every  $x, y \in H$ . Moreover,  $P_C x$  is characterized by the following properties:  $P_C x \in C$  and

$$\langle x - P_C x, y - P_C x \rangle \le 0,$$
  
 $\|x - y\|^2 \ge \|x - P_C x\|^2 + \|y - P_C x\|^2,$  (2.4)

for all  $x \in H$ ,  $y \in C$ . It is easy to see that the following is true:

$$u \in VI(B, C) \iff u = P_C(u - \lambda Bu), \quad \lambda > 0.$$
 (2.5)

A set-valued mapping  $S: H \to 2^H$  is called monotone if for all  $x, y \in H$ ,  $f \in Sx$  and  $g \in Sy$  imply  $\langle x - y, f - g \rangle \ge 0$ . A monotone mapping  $S: H \to 2^H$  is maximal if the graph of G(S) of S is not properly contained in the graph of any other monotone mapping. It is known that a monotone mapping S is maximal if and only if for  $(x, f) \in H \times H$ ,  $\langle x - y, f - g \rangle \ge 0$  for

every  $(y,g) \in G(S)$  implies  $f \in Sx$ . Let B be a monotone map of C into H and let  $N_C v$  be the normal cone to C at  $v \in C$ , that is,  $N_C v = \{w \in H : \langle u - v, w \rangle \ge 0, \ \forall u \in C\}$  and define

$$Sv = \begin{cases} Bv + N_C v, & v \in C, \\ \emptyset, & v \notin C. \end{cases}$$
 (2.6)

Then *S* is the maximal monotone and  $0 \in Sv$  if and only if  $v \in VI(B, C)$ ; see [45]. The following lemmas will be useful for proving the convergence result of this paper.

**Lemma 2.1** ([46]). Assume  $\{a_n\}$  is a sequence of nonnegative real numbers such that

$$a_{n+1} \le (1 - \alpha_n)a_n + \sigma_n, \quad n \ge 1,$$
 (2.7)

where  $\{\alpha_n\}$  is a sequence in (0,1) and  $\{\sigma_n\}$  is a sequence in  $\mathbb{R}$  such that

- (1)  $\sum_{n=1}^{\infty} \alpha_n = \infty$
- (2)  $\limsup_{n\to\infty} (\sigma_n/\alpha_n) \le 0 \text{ or } \sum_{n=1}^{\infty} |\sigma_n| < \infty.$

Then  $\lim_{n\to\infty} a_n = 0$ .

**Lemma 2.2** ([47]). Let  $\{x_n\}$  and  $\{l_n\}$  be bounded sequences in a Banach space E and let  $\{\beta_n\}$  be a sequence in [0,1] with  $0 < \liminf_{n \to \infty} \beta_n \le \limsup_{n \to \infty} \beta_n < 1$ . Suppose  $x_{n+1} = (1-\beta_n)l_n + \beta_n x_n$  for all integers  $n \ge 1$  and  $\limsup_{n \to \infty} (\|l_{n+1} - l_n\| - \|x_{n+1} - x_n\|) \le 0$ . Then,  $\lim_{n \to \infty} \|l_n - x_n\| = 0$ .

**Lemma 2.3** ([42, Proposition 2.1]). Assume that C is a closed convex subset of Hilbert space H, and let  $T: C \to C$  be a self-mapping of C,

(i) if T is a k-strictly pseudocontractive mapping, then T satisfies the Lipscchitz condition

$$||Tx - Ty|| \le \frac{1+\kappa}{1-\kappa} ||x - y|| \quad \forall x, y \in C.$$
 (2.8)

- (ii) if T is a k-strictly pseudocontractive mapping, then the mapping I T is demiclosed(at 0). That is, if  $\{x_n\}$  is a sequence in C such that  $x_n \to \tilde{x}$  and  $(I T)x_n \to 0$ , then  $(I T)\tilde{x} = 0$ .
- (iii) if T is a k-strictly pseudocontractive mapping, then the fixed point set F(T) of T is closed and convex so that the projection  $P_{F(T)}$  is well defined.

**Lemma 2.4** ([25]). Assume A is a strongly positive linear bounded operator on a Hilbert space H with coefficient  $\overline{\gamma} > 0$  and  $0 < \rho \le ||A||^{-1}$ . Then  $||I - \rho A|| \le 1 - \rho \overline{\gamma}$ .

The following lemmas can be obtained from Acedo and Xu [35, Proposition 2.6] easily.

**Lemma 2.5.** Let H be a Hilbert space, C be a closed convex subset of H. For any integer  $N \ge 1$ , assume that, for each  $1 \le i \le N$ ,  $T_i : C \to H$  is a  $k_i$ -strictly pseudocontractive mapping for some  $0 \le k_i < 1$ . Assume that  $\{\xi_i\}_{i=1}^N$  is a positive sequence such that  $\sum_{i=1}^N \xi_i = 1$ . Then  $\sum_{i=1}^N \xi_i T_i$  is a k-strictly pseudocontractive mapping with  $k = \max\{k_i : 1 \le i \le N\}$ .

**Lemma 2.6.** Let  $\{T_i\}_{i=1}^N$  and  $\{\xi_i\}_{i=1}^N$  be as in Lemma 2.5. Suppose that  $\{T_i\}_{i=1}^N$  has a common fixed point in C. Then  $F(\sum_{i=1}^N \xi_i T_i) = \bigcap_{i=1}^N F(T_i)$ .

For solving the mixed equilibrium problem, let us give the following assumptions for a bifunction  $\Theta$ ,  $\varphi$  and the set C:

- (A1)  $\Theta(x, x) = 0$  for all  $x \in C$ ;
- (A2)  $\Theta$  is monotone, that is,  $\Theta(x, y) + \Theta(y, x) \le 0$  for all  $x, y \in C$ ;
- (A3) for each  $x, y, z \in C$ ,  $\lim_{t\to 0} \Theta(tz + (1-t)x, y) \le \Theta(x, y)$ ;
- (A4) for each  $x \in C$ ,  $y \mapsto \Theta(x, y)$  is convex and lower semicontinuous;
- (B1) For each  $x \in H$  and r > 0, there exists a bounded subset  $D_x \subset C$ , and  $y_x \in C$  such that for any  $z \in C \setminus D_x$ ,

$$\Theta(z,y) + \varphi(y_x) + \frac{1}{r} \langle y_x - z, z - x \rangle < \varphi(z), \tag{2.9}$$

(B2) C is a bounded set.

By similar argument as in [48, proof of Lemma 2.3], we have the following result.

**Lemma 2.7.** Let C be a nonempty closed convex subset of H. Let  $\Theta: C \times C \to \mathbb{R}$  be a bifunction satisfies (A1)–(A4) and let  $\varphi: C \to \mathbb{R} \cup \{+\infty\}$  be a proper lower semicontinuous and convex function. Assume that either (B1) or (B2) holds. For r > 0 and  $x \in H$ , define a mapping  $T_r: H \to C$  as follows:

$$T_r(x) = \left\{ z \in C : \Theta(z, y) + \varphi(y) + \frac{1}{r} \langle y - z, z - x \rangle \ge \varphi(z), \ \forall y \in C \right\}$$
 (2.10)

for all  $x \in H$ . Then, the following conditions hold:

- (i) for each  $x \in H$ ,  $T_r(x) \neq \emptyset$ ;
- (ii)  $T_r$  is single-valued;
- (iii)  $T_r$  is firmly nonexpansive, that is, for any  $x, y \in H$ ,  $||T_r x T_r y||^2 \le \langle T_r x T_r y, x y \rangle$ ;
- (iv)  $F(T_r) = MEP(\Theta, \varphi)$ ;
- (v)  $MEP(\Theta, \varphi)$  is closed and convex.

#### 3. Main Results

In this section, we derive a strong convergence of an iterative algorithm which solves the problem of finding a common element of the set of solutions of a mixed equilibrium problem, the set of fixed points of a k-strictly pseudocontractive mapping of C into itself and the set of the variational inequality for an  $\alpha$ -inverse-strongly monotone mapping of C into H in a Hilbert space.

**Theorem 3.1.** Let C be a nonempty closed convex subset of a Hilbert space H. Let  $\Theta$  be a bifunction from  $C \times C$  to  $\mathbb{R}$  satisfies (A1)–(A4) and  $\varphi : C \to \mathbb{R} \cup \{+\infty\}$  be a proper lower semicontinuous and

convex function. Let T be a k-strictly pseudocontractive mapping of C into itself. Let f be a contraction of C into itself with coefficient  $\beta \in (0,1)$ , B an  $\alpha$ -inverse-strongly monotone mapping of C into H such that  $\Omega := F(T) \cap VI(B,C) \cap MEP(\Theta,\varphi) \neq \emptyset$ . Let A be a strongly bounded linear self-adjoint operator with coefficient  $\overline{\gamma} > 0$  and  $0 < \gamma < \overline{\gamma}/\beta$ . Assume that either (B1) or (B2) holds. Given the sequences  $\{\alpha_n\}$ ,  $\{\beta_n\}$ ,  $\{\delta_n\}$ ,  $\{\delta_n\}$ , and  $\{r_n\}$  in [0,1] satisfyies the following conditions

- (D1)  $\lim_{n\to\infty}\alpha_n=0$ ,  $\sum_{n=1}^{\infty}\alpha_n=\infty$ ;
- (D2)  $0 < \liminf_{n \to \infty} \delta_n \le \limsup_{n \to \infty} \delta_n < 1$ ;
- (D3)  $0 \le k \le \beta_n < \varepsilon < 1$  for all  $n \ge 0$ , and  $\lim_{n \to \infty} |\beta_{n+1} \beta_n| = 0$ ;
- (D4)  $\{\lambda_n\} \subset [a,b]$  for some a,b with  $0 < a < b < 2\alpha$ , and  $\lim_{n \to \infty} |\lambda_{n+1} \lambda_n| = 0$ ;
- (D5)  $\liminf_{n\to\infty} r_n > 0$ ,  $\lim_{n\to\infty} |r_{n+1} r_n| = 0$ .

Let  $\{x_n\}$ ,  $\{u_n\}$ , and  $\{y_n\}$  be sequences generated by

 $x_1 = x \in C$  chosen arbitrarily,

$$\Theta(u_n, y) + \varphi(y) - \varphi(u_n) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge 0, \quad \forall y \in C,$$

$$y_n = \beta_n u_n + (1 - \beta_n) T u_n,$$

$$x_{n+1} = \alpha_n \gamma f(x_n) + \delta_n x_n + ((1 - \delta_n) I - \alpha_n A) P_C(y_n - \lambda_n B y_n), \quad n \ge 1.$$
(3.1)

Then  $\{x_n\}$ ,  $\{u_n\}$ , and  $\{y_n\}$  converge strongly to a point  $z \in \Omega$  which is the unique solution of the variational inequality

$$\langle (A - \gamma f)z, z - x \rangle \le 0, \quad \forall x \in \Omega.$$
 (3.2)

Equivalently, one has  $z = P_{\Omega}(I - A + \gamma f)(z)$ .

*Proof.* Since  $\lim_{n\to\infty}\alpha_n=0$ , we may assume, without loss of generality, that  $\alpha_n<\|A\|^{-1}$  for all n. By Lemma 2.4, we have  $\|I-\alpha_nA\|\leq 1-\alpha_n\overline{\gamma}$ . We will assume that  $\|I-A\|\leq 1-\overline{\gamma}$ . Observe that  $P_\Omega(I-A+\gamma f)$  is a contraction. Indeed, for all  $x,y\in C$ , we have

$$||P_{\Omega}(I - A + \gamma f)(x) - P_{\Omega}(I - A + \gamma f)(y)|| \le ||(I - A + \gamma f)(x) - (I - A + \gamma f)(y)||$$

$$\le ||I - A|| ||x - y|| + \gamma ||f(x) - f(y)||$$

$$\le (1 - \overline{\gamma}) ||x - y|| + \gamma \beta ||x - y||$$

$$= (1 - (\overline{\gamma} - \gamma \beta)) ||x - y||.$$
(3.3)

Since H is complete, there exists a unique element  $z \in C$  such that  $z = P_{\Omega}(I - A + \gamma f)(z)$ . On the other hand, since A is a linear bounded self-adjoint operator, one has

$$||A|| = \sup\{|\langle Ax, x \rangle| : x \in H, ||x|| = 1\}. \tag{3.4}$$

Observing that

$$\langle ((1 - \delta_n)I - \alpha_n A)x, x \rangle = 1 - \delta_n - \alpha_n \langle Ax, x \rangle$$

$$\geq 1 - \delta_n - \alpha_n ||A||$$

$$\geq 0,$$
(3.5)

we obtain  $(1 - \delta_n)I - \alpha_n A$  is positive. It follows that

$$\|(1 - \delta_n)I - \alpha_n A\| = \sup\{\langle ((1 - \delta_n)I - \alpha_n A)x, x\rangle : x \in H, \|x\| = 1\}$$

$$= \sup\{1 - \delta_n - \alpha_n \langle Ax, x\rangle : x \in H, \|x\| = 1\}$$

$$\leq 1 - \delta_n - \alpha_n \overline{\gamma}.$$
(3.6)

Next, we divide the proof into six steps as follows.

Step 1. First we prove that  $I - \lambda_n B$  is nonexpansive. For all  $x, y \in C$  and  $\lambda_n \in [0, 2\alpha]$ ,

$$\|(I - \lambda_n B)x - (I - \lambda_n B)y\|^2 = \|(x - y) - \lambda_n (Bx - By)\|^2$$

$$= \|x - y\|^2 - 2\lambda_n \langle x - y, Bx - By \rangle + \lambda_n^2 \|Bx - By\|^2$$

$$\leq \|x - y\|^2 + \lambda_n (\lambda_n - 2\alpha) \|Bx - By\|^2,$$
(3.7)

which implies that  $I - \lambda_n B$  is nonexpansive.

Step 2. Next we prove that  $\{x_n\}$ ,  $\{y_n\}$ ,  $\{u_n\}$ ,  $\{Bx_n\}$ ,  $\{By_n\}$  and  $\{Bu_n\}$  are bounded. Indeed, pick any  $p \in \Omega$ . From (2.5), we have  $p = P_C(p - \lambda_n Bp)$ . Setting  $v_n = P_C(y_n - \lambda_n By_n)$ , we obtain from the nonexpansivity of  $I - \lambda_n B$  that

$$||v_{n} - p|| = ||P_{C}(y_{n} - \lambda_{n}By_{n}) - P_{C}(p - \lambda_{n}Bp)||$$

$$\leq ||(y_{n} - \lambda_{n}By_{n}) - (p - \lambda_{n}Bp)|| \leq ||y_{n} - p||.$$
(3.8)

From (2.1), we have

$$\|y_{n} - p\|^{2} = \|\beta_{n}(u_{n} - p) + (1 - \beta_{n})(Tu_{n} - p)\|^{2}$$

$$\leq \beta_{n}\|u_{n} - p\|^{2} - (1 - \beta_{n})\beta_{n}\|u_{n} - Tu_{n}\|^{2} + (1 - \beta_{n})\|Tu_{n} - p\|^{2}$$
(3.9)

so, by (3.9) and the k-strict pseudocontractivity of T, it follows that

$$||y_n - p||^2 \le ||u_n - p||^2 - (1 - \beta_n)(\beta_n - k)||u_n - Tu_n||^2$$

$$\le ||u_n - p||^2,$$
(3.10)

that is,

$$||y_n - p|| \le ||u_n - p||. \tag{3.11}$$

Observe that

$$||u_n - p|| = ||T_{r_n} x_n - T_{r_n} p|| \le ||x_n - p||.$$
(3.12)

From (3.8), (3.11) and the last inequality, we have

$$||v_n - p|| \le ||x_n - p||. \tag{3.13}$$

It follows that

$$\|x_{n+1} - p\| = \|\alpha_n \gamma f(x_n) + \delta_n x_n + ((1 - \delta_n)I - \alpha_n A)v_n - p\|$$

$$= \|\alpha_n (\gamma f(x_n) - Ap) + \delta_n (x_n - p) + ((1 - \delta_n)I - \alpha_n A)(v_n - p)\|$$

$$\leq \alpha_n \|\gamma f(x_n) - Ap\| + \delta_n \|x_n - p\| + (1 - \delta_n - \alpha_n \overline{\gamma}) \|v_n - p\|$$

$$\leq \alpha_n \gamma \|f(x_n) - f(p)\| + \alpha_n \|\gamma f(p) - Ap\| + (1 - \alpha_n \overline{\gamma}) \|x_n - p\|$$

$$= [1 - \alpha_n (\overline{\gamma} - \gamma \beta)] \|x_n - p\| + \alpha_n \|\gamma f(p) - Ap\|$$

$$= [1 - \alpha_n (\overline{\gamma} - \gamma \beta)] \|x_n - p\| + \alpha_n (\overline{\gamma} - \gamma \beta) \frac{\|\gamma f(p) - Ap\|}{\overline{\gamma} - \gamma \beta}.$$
(3.14)

By simple induction, we have

$$||x_n - p|| \le \max\left\{||x_1 - p||, \frac{||Ap - \gamma f(p)||}{\overline{\gamma} - \gamma \beta}\right\},\tag{3.15}$$

which gives that the sequence  $\{x_n\}$  is bounded, so are  $\{y_n\}$ ,  $\{u_n\}$ ,  $\{Bx_n\}$ ,  $\{By_n\}$ , and  $\{Bu_n\}$ . Step 3. Next we claim that

$$\lim_{n \to \infty} ||x_{n+1} - x_n|| = 0. \tag{3.16}$$

Notice that

$$||v_{n} - v_{n-1}|| = ||P_{C}(y_{n} - \lambda_{n}By_{n}) - P_{C}(y_{n-1} - \lambda_{n-1}By_{n-1})||$$

$$\leq ||(y_{n} - \lambda_{n}By_{n}) - (y_{n-1} - \lambda_{n-1}By_{n-1})||$$

$$= ||(y_{n} - \lambda_{n}By_{n}) - (y_{n-1} - \lambda_{n}By_{n-1}) + (\lambda_{n-1} - \lambda_{n})By_{n-1}||$$

$$\leq ||(y_{n} - \lambda_{n}By_{n}) - (y_{n-1} - \lambda_{n}By_{n-1})|| + |\lambda_{n-1} - \lambda_{n}|||By_{n-1}||$$

$$\leq ||y_{n} - y_{n-1}|| + |\lambda_{n-1} - \lambda_{n}|||By_{n-1}||.$$
(3.17)

Next, we define

$$V_n = (1 - \beta_n)T + \beta_n I. (3.18)$$

As shown in [19], from the k-strict pseudocontractivity of T and the conditions (D4), it follows that  $V_n$  is a nonexpansive maping for which  $F(T) = F(V_n)$ .

Observing that

$$y_n = V_n u_n,$$
  

$$y_{n-1} = V_{n-1} u_{n-1},$$
(3.19)

we have

$$||y_{n} - y_{n-1}|| = ||V_{n}u_{n} - V_{n-1}u_{n-1}||$$

$$\leq ||V_{n}u_{n} - V_{n}u_{n-1}|| + ||V_{n}u_{n-1} - V_{n-1}u_{n-1}||$$

$$\leq ||u_{n} - u_{n-1}|| + ||V_{n}u_{n-1} - V_{n-1}u_{n-1}||$$

$$= ||u_{n} - u_{n-1}|| + ||(\beta_{n}u_{n-1} + (1 - \beta_{n})Tu_{n-1}) - (\beta_{n-1}u_{n-1} + (1 - \beta_{n-1})Tu_{n-1})||$$

$$\leq ||u_{n} - u_{n-1}|| + M_{1}|\beta_{n} - \beta_{n-1}|,$$
(3.20)

where  $M_1$  is an appropriate constant such that  $M_1 \ge \sup_{n\ge 1} \{\|u_n\|, \|Tu_n\|\}$ . Substituting (3.20) into (3.17), we obtain

$$||v_{n} - v_{n-1}|| \le ||y_{n} - y_{n-1}|| + |\lambda_{n-1} - \lambda_{n}||By_{n-1}|| \le ||u_{n} - u_{n-1}|| + M_{1}|\beta_{n} - \beta_{n-1}| + |\lambda_{n-1} - \lambda_{n}||By_{n-1}||.$$
(3.21)

On the other hand, from  $u_n = T_{r_n} x_n \in \text{dom } \varphi$  and  $u_{n+1} = T_{r_{n+1}} x_{n+1} \in \text{dom } \varphi$ , we note that

$$\Theta(u_n, y) + \varphi(y) - \varphi(u_n) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge 0 \quad \forall y \in C,$$
(3.22)

$$\Theta(u_{n+1}, y) + \varphi(y) - \varphi(u_{n+1}) + \frac{1}{r_{n+1}} \langle y - u_{n+1}, u_{n+1} - x_{n+1} \rangle \ge 0 \quad \forall y \in C.$$
 (3.23)

Putting  $y = u_{n+1}$  in (3.22) and  $y = u_n$  in (3.23), we have

$$\Theta(u_{n}, u_{n+1}) + \varphi(u_{n+1}) - \varphi(u_{n}) + \frac{1}{r_{n}} \langle u_{n+1} - u_{n}, u_{n} - x_{n} \rangle \ge 0, 
\Theta(u_{n+1}, u_{n}) + \varphi(u_{n}) - \varphi(u_{n+1}) + \frac{1}{r_{n+1}} \langle u_{n} - u_{n+1}, u_{n+1} - x_{n+1} \rangle \ge 0.$$
(3.24)

So, from (A2) we have

$$\left\langle u_{n+1} - u_n, \frac{u_n - x_n}{r_n} - \frac{u_{n+1} - x_{n+1}}{r_{n+1}} \right\rangle \ge 0,$$
 (3.25)

and hence

$$\left\langle u_{n+1} - u_n, u_n - u_{n+1} + u_{n+1} - x_n - \frac{r_n}{r_{n+1}} (u_{n+1} - x_{n+1}) \right\rangle \ge 0.$$
 (3.26)

Without loss of generality, let us assume that there exists a real number c such that  $r_n > c > 0$  for all  $n \in \mathbb{N}$ . Then, we have

$$||u_{n+1} - u_n||^2 \le \left\langle u_{n+1} - u_n, x_{n+1} - x_n + \left(1 - \frac{r_n}{r_{n+1}}\right) (u_{n+1} - x_{n+1}) \right\rangle$$

$$\le ||u_{n+1} - u_n|| \left\{ ||x_{n+1} - x_n|| + \left|1 - \frac{r_n}{r_{n+1}}\right| ||u_{n+1} - x_{n+1}|| \right\},$$
(3.27)

and hence

$$||u_{n+1} - u_n|| \le ||x_{n+1} - x_n|| + \frac{1}{r_{n+1}} |r_{n+1} - r_n| ||u_{n+1} - x_{n+1}||$$

$$\le ||x_{n+1} - x_n|| + \frac{1}{c} |r_{n+1} - r_n| M_2,$$
(3.28)

where  $M_2 = \sup\{\|u_n - x_n\| : n \in \mathbb{N}\}$ . It follows from (3.21) and the last inequality that

$$||v_{n}-v_{n-1}|| \leq ||x_{n+1}-x_{n}|| + M\left(\frac{1}{c}|r_{n+1}-r_{n}| + \left|\beta_{n}-\beta_{n-1}\right|\right) + |\lambda_{n-1}-\lambda_{n}||By_{n-1}||, \quad (3.29)$$

where  $M = \max\{M_1, M_2\}.$ 

Define a sequence  $\{l_n\}$  such that

$$x_{n+1} = (1 - \delta_n)l_n + \delta_n x_n, \quad \forall n \ge 1.$$
 (3.30)

Then, we have

$$l_{n+1} - l_n = \frac{x_{n+2} - \delta_{n+1} x_{n+1}}{1 - \delta_{n+1}} - \frac{x_{n+1} - \delta_n x_n}{1 - \delta_n}$$

$$= \frac{\alpha_{n+1} \gamma f(x_{n+1}) + ((1 - \delta_{n+1})I - \alpha_{n+1}A)v_{n+1}}{1 - \delta_{n+1}}$$

$$- \frac{\alpha_n \gamma f(x_n) + ((1 - \delta_n)I - \alpha_n A)v_n}{1 - \delta_n}$$

$$= \frac{\alpha_{n+1}}{1 - \delta_{n+1}} (\gamma f(x_{n+1}) - Av_{n+1}) + \frac{\alpha_n}{1 - \delta_n} (Av_n - \gamma f(x_n))$$

$$+ v_{n+1} - v_n.$$
(3.31)

It follows from (3.29) that

$$||l_{n+1} - l_n|| - ||x_n - x_{n+1}|| \le \frac{\alpha_{n+1}}{1 - \delta_{n+1}} ||\gamma f(x_{n+1}) - Av_{n+1}|| + \frac{\alpha_n}{1 - \delta_n} ||Av_n - \gamma f(x_n)|| + ||v_{n+1} - v_n|| - ||x_n - x_{n+1}|| \le \frac{\alpha_{n+1}}{1 - \delta_{n+1}} ||\gamma f(x_{n+1}) - Av_{n+1}|| + \frac{\alpha_n}{1 - \delta_n} ||Av_n - \gamma f(x_n)|| + M \left(\frac{1}{c} |r_{n+1} - r_n| + |\beta_n - \beta_{n-1}|\right) + |\lambda_{n-1} - \lambda_n| ||By_{n-1}||.$$
(3.32)

Observing the conditions (D1), (D3), (D4), (D5), and taking the superior limit as  $n \to \infty$ , we get

$$\lim_{n \to \infty} \sup (\|l_{n+1} - l_n\| - \|x_n - x_{n+1}\|) \le 0.$$
(3.33)

We can obtain  $\lim_{n\to\infty} ||l_n - x_n|| = 0$  easily by Lemma 2.2. Observing that

$$x_{n+1} - x_n = (1 - \delta_n)(l_n - x_n), \tag{3.34}$$

we obtain

$$\lim_{n \to \infty} \|x_{n+1} - x_n\| = 0. \tag{3.35}$$

Hence (3.16) is proved.

Step 4. Next we prove that

$$\lim_{n \to \infty} ||Tv_n - v_n|| = 0.$$
 (3.36)

(a) First we prove that  $\lim_{n\to\infty} ||x_n - v_n|| = 0$ . Observing that

$$x_{n} - v_{n} = x_{n} - x_{n+1} + x_{n+1} - v_{n}$$

$$= x_{n} - x_{n+1} + \alpha_{n} \gamma f(x_{n}) + \delta_{n} x_{n} + ((1 - \delta_{n})I - \alpha_{n} A)v_{n} - v_{n}$$

$$= x_{n} - x_{n+1} + \alpha_{n} (\gamma f(x_{n}) - Av_{n}) + \delta_{n} (x_{n} - v_{n}),$$
(3.37)

we arrive at

$$(1 - \delta_n)(x_n - v_n) = x_n - x_{n+1} + \alpha_n (\gamma f(x_n) - Av_n), \tag{3.38}$$

which implies that

$$(1 - \delta_n) \|x_n - v_n\| \le \|x_n - x_{n+1}\| + \alpha_n \|\gamma f(x_n) - Av_n\|. \tag{3.39}$$

Therefore, it follows from (3.16), (D1), and (D2) that

$$\lim_{n \to \infty} ||x_n - v_n|| = 0. \tag{3.40}$$

(b) Next, we will show that  $\lim_{n\to\infty} ||By_n - Bp|| = 0$  for any  $p \in \Omega$ . Observe that

$$\begin{aligned} \left\| x_{n+1} - p \right\|^2 &= \left\| \left( (1 - \delta_n) I - \alpha_n A \right) (v_n - p) + \delta_n (x_n - p) + \alpha_n (\gamma f(x_n) - Ap) \right\|^2 \\ &= \left\| \left( (1 - \delta_n) I - \alpha_n A \right) (v_n - p) + \delta_n (x_n - p) \right\|^2 + \alpha_n^2 \left\| \gamma f(x_n) - Ap \right\|^2 \\ &+ 2 \delta_n \alpha_n \left\langle x_n - p, \gamma f(x_n) - Ap \right\rangle + 2 \alpha_n \left\langle \left( (1 - \delta_n) I - \alpha_n A \right) (v_n - p), \gamma f(x_n) - Ap \right\rangle \\ &\leq \left( \left( (1 - \delta_n - \alpha_n \overline{\gamma}) \right) \|v_n - p\| + \delta_n \|x_n - p\| \right)^2 + \alpha_n^2 \|\gamma f(x_n) - Ap\|^2 \\ &+ 2 \delta_n \alpha_n \left\langle x_n - p, \gamma f(x_n) - Ap \right\rangle + 2 \alpha_n \left\langle \left( (1 - \delta_n) I - \alpha_n A \right) (v_n - p), \gamma f(x_n) - Ap \right\rangle \\ &= \left( (1 - \delta_n - \alpha_n \overline{\gamma})^2 \|v_n - p\|^2 + \delta_n^2 \|x_n - p\|^2 \right. \\ &+ 2 \left( (1 - \delta_n - \alpha_n \overline{\gamma}) \delta_n \|v_n - p\| \|x_n - p\| + c_n \right. \\ &\leq \left( (1 - \delta_n - \alpha_n \overline{\gamma})^2 \|v_n - p\|^2 + \delta_n^2 \|x_n - p\|^2 \right. \\ &+ \left. \left( (1 - \alpha_n \overline{\gamma})^2 - 2 (1 - \alpha_n \overline{\gamma}) \delta_n + \delta_n^2 \right] \|v_n - p\|^2 + \delta_n^2 \|x_n - p\|^2 \right. \\ &+ \left. \left( (1 - \alpha_n \overline{\gamma}) \delta_n - \delta_n^2 \right) \left( \|v_n - p\|^2 + \|x_n - p\|^2 \right) + c_n \end{aligned}$$

$$= (1 - \alpha_{n}\overline{\gamma})^{2} \|v_{n} - p\|^{2} - (1 - \alpha_{n}\overline{\gamma})\delta_{n}\|v_{n} - p\|^{2} + (1 - \alpha_{n}\overline{\gamma})\delta_{n}\|x_{n} - p\|^{2} + c_{n}$$

$$= (1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})\|v_{n} - p\|^{2} + (1 - \alpha_{n}\overline{\gamma})\delta_{n}\|x_{n} - p\|^{2} + c_{n}$$

$$\leq (1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})[\|(y_{n} - \lambda_{n}By_{n}) - (p - \lambda_{n}Bp)\|^{2}]$$

$$+ (1 - \alpha_{n}\overline{\gamma})\delta_{n}\|x_{n} - p\|^{2} + c_{n}$$

$$\leq (1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})[\|y_{n} - p\|^{2} + \lambda_{n}(\lambda_{n} - 2\alpha)\|By_{n} - Bp\|^{2}]$$

$$+ (1 - \alpha_{n}\overline{\gamma})\delta_{n}\|x_{n} - p\|^{2} + c_{n}$$

$$\leq \|x_{n} - p\|^{2} + b(b - 2\alpha)\|By_{n} - Bp\|^{2} + c_{n},$$

$$(3.41)$$

where

$$c_{n} = \alpha_{n}^{2} \| \gamma f(x_{n}) - Ap \|^{2} + 2\delta_{n}\alpha_{n} \| x_{n} - p \| \| \gamma f(x_{n}) - Ap \|$$

$$+ 2\alpha_{n} \| ((1 - \delta_{n})I - \alpha_{n}A)(v_{n} - p) \| \| \gamma f(x_{n}) - Ap \|.$$
(3.42)

This implies that

$$-b(b-2\alpha)\|By_{n}-Bp\|^{2} \leq \|x_{n}-p\|^{2} - \|x_{n+1}-p\|^{2} + c_{n}$$

$$\leq \|x_{n}-x_{n+1}\|(\|x_{n}-p\| + \|x_{n+1}-p\|) + c_{n}.$$
(3.43)

It is easy to see that  $\lim_{n\to\infty} c_n = 0$  and then from (3.16), we obtain

$$\lim_{n \to \infty} ||By_n - Bp|| = 0. {(3.44)}$$

(c) Next we prove that  $\lim_{n\to\infty} ||x_n - u_n|| = 0$ . From (2.3), we have

$$\|v_{n} - p\|^{2} = \|P_{C}(y_{n} - \lambda_{n}By_{n}) - P_{C}(p - \lambda_{n}Bp)\|^{2}$$

$$\leq \langle (y_{n} - \lambda_{n}By_{n}) - (p - \lambda_{n}Bp), v_{n} - p \rangle$$

$$= \frac{1}{2} \{ \|(y_{n} - \lambda_{n}By_{n}) - (p - \lambda_{n}Bp)\|^{2} + \|v_{n} - p\|^{2}$$

$$- \|(y_{n} - \lambda_{n}By_{n}) - (p - \lambda_{n}Bp) - (v_{n} - p)\|^{2} \}$$

$$\leq \frac{1}{2} \{ \|y_{n} - p\|^{2} + \|v_{n} - p\|^{2} - \|(y_{n} - v_{n}) - \lambda_{n}(By_{n} - Bp)\|^{2} \}$$

$$= \frac{1}{2} \{ \|y_{n} - p\|^{2} + \|v_{n} - p\|^{2} - \|y_{n} - v_{n}\|^{2} + 2\lambda_{n} \langle y_{n} - v_{n}, By_{n} - Bp \rangle - \lambda_{n}^{2} \|By_{n} - Bp\|^{2} \},$$
(3.45)

so, we obtain

$$\|v_n - p\|^2 \le \|y_n - p\|^2 - \|y_n - v_n\|^2 + 2\lambda_n \langle y_n - v_n, By_n - Bp \rangle - \lambda_n^2 \|By_n - Bp\|^2.$$
 (3.46)

It follows that

$$||x_{n+1} - p||^{2} \leq (1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})||v_{n} - p||^{2} + (1 - \alpha_{n}\overline{\gamma})\delta_{n}||x_{n} - p||^{2} + c_{n}$$

$$\leq (1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})$$

$$\times \left[||y_{n} - p||^{2} - ||y_{n} - v_{n}||^{2} + 2\lambda_{n}\langle y_{n} - v_{n}, By_{n} - Bp\rangle - \lambda_{n}^{2}||By_{n} - Bp||^{2}\right]$$

$$+ (1 - \alpha_{n}\overline{\gamma})\delta_{n}||x_{n} - p||^{2} + c_{n}$$

$$\leq (1 - \alpha_{n}\overline{\gamma})||x_{n} - p||^{2} - (1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})||y_{n} - v_{n}||^{2}$$

$$+ 2\lambda_{n}(1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})||y_{n} - v_{n}|||By_{n} - Bp||$$

$$- \lambda_{n}^{2}(1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})||By_{n} - Bp||^{2} + c_{n},$$
(3.47)

which implies that

$$(1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})\|y_{n} - v_{n}\|^{2} \leq \|x_{n} - p\|^{2} - \|x_{n+1} - p\|^{2} + 2\lambda_{n}(1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})\|y_{n} - v_{n}\|\|By_{n} - Bp\| - \lambda_{n}^{2}(1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})\|By_{n} - Bp\|^{2} + c_{n}$$

$$\leq \|x_{n} - x_{n+1}\|(\|x_{n} - p\| + \|x_{n+1} - p\|) + 2\lambda_{n}(1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})\|y_{n} - v_{n}\|\|By_{n} - Bp\| - \lambda_{n}^{2}(1 - \alpha_{n}\overline{\gamma})(1 - \delta_{n} - \alpha_{n}\overline{\gamma})\|By_{n} - Bp\|^{2} + c_{n}.$$

$$(3.48)$$

Applying (3.16), (3.44),  $\limsup_{n\to\infty} \delta_n < 1$ , and  $\lim_{n\to\infty} c_n = 0$  to the last inequality, we obtain that

$$\lim_{n \to \infty} \|y_n - v_n\| = 0. \tag{3.49}$$

It follows from (3.40) and (3.49) that

$$||x_n - y_n|| \le ||x_n - v_n|| + ||v_n - y_n|| \longrightarrow 0 \text{ as } n \longrightarrow \infty.$$
 (3.50)

Then it follows from (D1), (3.49) and (3.50) that

$$||x_{n+1} - y_n|| = ||\alpha_n(\gamma f(x_n) - Ay_n) + \delta_n(x_n - y_n) + ((1 - \delta_n)I - \alpha_n A)(v_n - y_n)||$$

$$\leq \alpha_n||\gamma f(x_n) - Ay_n|| + \delta_n||x_n - y_n|| + (1 - \delta_n - \alpha_n \overline{\gamma})||v_n - y_n|| \longrightarrow 0.$$
(3.51)

For any  $p \in \Omega$ , we have from Lemma 2.7,

$$\|u_{n} - p\|^{2} = \|T_{r_{n}}x_{n} - T_{r_{n}}p\|^{2} \le \langle T_{r_{n}}x_{n} - T_{r_{n}}p, x_{n} - p \rangle$$

$$= \langle u_{n} - p, x_{n} - p \rangle = \frac{1}{2} (\|u_{n} - p\|^{2} + \|x_{n} - p\|^{2} - \|x_{n} - u_{n}\|^{2}).$$
(3.52)

Hence

$$||u_n - p||^2 \le ||x_n - p||^2 - ||x_n - u_n||^2.$$
(3.53)

From (3.41) we observe that

$$\begin{aligned} \|x_{n+1} - p\|^2 &\leq \left(1 - \delta_n - \alpha_n \overline{\gamma}\right)^2 \|v_n - p\|^2 + \delta_n^2 \|x_n - p\|^2 \\ &+ 2\left(1 - \delta_n - \alpha_n \overline{\gamma}\right) \delta_n \|v_n - p\| \|x_n - p\| + c_n \end{aligned} \\ &\leq \left(1 - \delta_n - \alpha_n \overline{\gamma}\right)^2 \|u_n - p\|^2 + \delta_n^2 \|x_n - p\|^2 \\ &+ 2\left(1 - \delta_n - \alpha_n \overline{\gamma}\right) \delta_n \|u_n - p\|x_n - p\| + c_n \end{aligned} \\ &\leq \left(1 - \delta_n - \alpha_n \overline{\gamma}\right) \delta_n \|u_n - p\|^2 + \delta_n^2 \|x_n - p\|^2 \\ &+ \left(1 - \delta_n - \alpha_n \overline{\gamma}\right) \delta_n \left(\|u_n - p\|^2 + \|x_n - p\|^2\right) + c_n \end{aligned} \\ &= \left(\left(1 - \alpha_n \overline{\gamma}\right)^2 - 2\delta_n \left(1 - \alpha_n \overline{\gamma}\right) + \delta_n^2\right) \|u_n - p\|^2 + \delta_n^2 \|x_n - p\|^2 \\ &+ \left(1 - \alpha_n \overline{\gamma}\right) \delta_n \left(\|u_n - p\|^2 + \|x_n - p\|^2\right) - \delta_n^2 \left(\|u_n - p\|^2 + \|x_n - p\|^2\right) + c_n \end{aligned} \\ &= \left(\left(1 - \alpha_n \overline{\gamma}\right)^2 - 2\delta_n \left(1 - \alpha_n \overline{\gamma}\right) + \delta_n^2 + \left(1 - \alpha_n \overline{\gamma}\right) \delta_n - \delta_n^2\right) \|u_n - p\|^2 + \delta_n^2 \|x_n - p\|^2 \\ &+ \left(1 - \alpha_n \overline{\gamma}\right) \delta_n \|x_n - p\|^2 - \delta_n^2 \|x_n - p\|^2 + c_n \end{aligned} \\ &= \left(\left(1 - \alpha_n \overline{\gamma}\right)^2 - \delta_n \left(1 - \alpha_n \overline{\gamma}\right)\right) \|u_n - p\|^2 + \left(1 - \alpha_n \overline{\gamma}\right) \delta_n \|x_n - p\|^2 + c_n \end{aligned} \\ &\leq \left(1 - \alpha_n \overline{\gamma}\right) \left(1 - \alpha_n \overline{\gamma} - \delta_n\right) \left(\|x_n - p\|^2 - \|x_n - u_n\|^2\right) + \left(1 - \alpha_n \overline{\gamma}\right) \delta_n \|x_n - p\|^2 + c_n \end{aligned} \\ &= \left(1 - \alpha_n \overline{\gamma}\right)^2 \|x_n - p\|^2 - \left(1 - \alpha_n \overline{\gamma}\right) \left(1 - \alpha_n \overline{\gamma} - \delta_n\right) \|x_n - u_n\|^2 + c_n \end{aligned} \\ &= \left(1 - 2\alpha_n \overline{\gamma} + (\alpha_n \overline{\gamma})^2\right) \|x_n - p\|^2 - \left(1 - \alpha_n \overline{\gamma}\right) \left(1 - \alpha_n \overline{\gamma} - \delta_n\right) \|x_n - u_n\|^2 + c_n \end{aligned} \\ &\leq \|x_n - p\|^2 + \left(\alpha_n \overline{\gamma}\right)^2 \|x_n - p\|^2 - \left(1 - \alpha_n \overline{\gamma}\right) \left(1 - \alpha_n \overline{\gamma} - \delta_n\right) \|x_n - u_n\|^2 + c_n \end{aligned}$$

Hence

$$(1 - \alpha_{n}\overline{\gamma})(1 - \alpha_{n}\overline{\gamma} - \delta_{n})\|x_{n} - u_{n}\|^{2} \leq \|x_{n} - p\|^{2} - \|x_{n+1} - p\|^{2} + (\alpha_{n}\overline{\gamma})^{2}\|x_{n} - p\|^{2} + c_{n}$$

$$= (\|x_{n} - p\| - \|x_{n+1} - p\|)(\|x_{n} - p\| + \|x_{n+1} - p\|)$$

$$+ (\alpha_{n}\overline{\gamma})^{2}\|x_{n} - p\|^{2} + c_{n}$$

$$\leq \|x_{n} - x_{n+1}\|(\|x_{n} - p\| + \|x_{n+1} - p\|)$$

$$+ (\alpha_{n}\overline{\gamma})^{2}\|x_{n} - p\|^{2} + c_{n}.$$

$$(3.55)$$

Using (D1), (D2) and (3.16), we obtain

$$\lim_{n \to \infty} ||u_n - x_n|| = 0. \tag{3.56}$$

(d) Next we prove that  $\lim_{n\to\infty} ||x_n - Tx_n|| = 0$ . Using Lemma 2.3 (i), we have

$$||Tx_{n} - x_{n}|| \leq ||x_{n} - x_{n+1}|| + ||x_{n+1} - y_{n}|| + ||y_{n} - Tx_{n}||$$

$$\leq ||x_{n} - x_{n+1}|| + ||x_{n+1} - y_{n}|| + \beta_{n}||u_{n} - Tx_{n}|| + (1 - \beta_{n})||Tu_{n} - Tx_{n}||$$

$$\leq ||x_{n} - x_{n+1}|| + ||x_{n+1} - y_{n}|| + \beta_{n}||u_{n} - x_{n}|| + \beta_{n}||x_{n} - Tx_{n}||$$

$$+ (1 - \beta_{n}) \frac{1 + k}{1 - k}||u_{n} - x_{n}||,$$

$$(3.57)$$

which implies that

$$(1 - \beta_n) \|Tx_n - x_n\| \le \|x_n - x_{n+1}\| + \|x_{n+1} - y_n\|$$

$$+ \left(\frac{1+k}{1-k} + \beta_n \left(1 - \frac{1+k}{1-k}\right)\right) \|u_n - x_n\| \longrightarrow 0 \quad \text{as } n \longrightarrow \infty.$$
(3.58)

By (3.16), (3.51), and (3.56), we have

$$\lim_{n \to \infty} ||Tx_n - x_n|| = 0. {(3.59)}$$

Observing that

$$\|x_{n+1} - v_n\| \le \|\alpha_n (\gamma f(x_n) - Av_n) + \delta_n (x_n - v_n)\|$$

$$\le \alpha_n \|\gamma f(x_n) - Av_n\| + \delta_n \|x_n - v_n\| \longrightarrow 0 \quad \text{as } n \longrightarrow \infty.$$
(3.60)

Using (3.40) and the last inequality, we obtain that

$$||x_n - v_n|| \le ||x_n - x_{n+1}|| + ||x_{n+1} - v_n|| \longrightarrow 0 \text{ as } n \longrightarrow \infty$$
 (3.61)

From Lemma 2.3(i), (3.59), and (3.61), we have

$$||Tv_{n} - v_{n}|| \le ||Tv_{n} - Tx_{n}|| + ||Tx_{n} - x_{n}|| + ||x_{n} - v_{n}||$$

$$\le \left(1 + \frac{1+k}{1-k}\right)||v_{n} - x_{n}|| + ||Tx_{n} - x_{n}|| \longrightarrow 0 \quad \text{as } n \longrightarrow \infty.$$
(3.62)

Hence (3.36) is proved.

Step 5. We claim that

$$\limsup_{n \to \infty} \langle (A - \gamma f) z, z - v_n \rangle \le 0. \tag{3.63}$$

We choose a subsequence  $\{v_{n_i}\}$  of  $\{v_n\}$  such that

$$\lim_{i \to \infty} \langle (A - \gamma f)z, z - v_{n_i} \rangle = \limsup_{n \to \infty} \langle (A - \gamma f)z, z - v_n \rangle.$$
(3.64)

Since  $\{v_{n_i}\}$  is bounded, there exists a subsequence  $\{v_{n_{i_j}}\}$  of  $\{v_{n_i}\}$  which converges weakly to  $q \in C$ .

Next, we show that  $q \in \Omega := F(T) \cap VI(B, C) \cap MEP(\Theta, \varphi)$ .

- (a) We first show  $q \in F(T)$ . In fact, using Lemma 2.3(ii) and (3.36), we obtain that  $q \in F(T)$ .
- (b) Next, we prove  $q \in VI(B, C)$ . For this purpose, let S be the maximal monotone mapping defined by (2.6):

$$Sv = \begin{cases} Bv + N_C v, & v \in C; \\ \emptyset, & v \notin C. \end{cases}$$
 (3.65)

For any given  $(v, w) \in G(S)$ , hence  $w - Bv \in N_C(v)$ . Since  $v_n \in C$ , we have

$$\langle v - v_n, w - Bv \rangle \ge 0. \tag{3.66}$$

On the other hand, from  $v_n = P_C(y_n - \lambda_n B y_n)$ , we have

$$\langle v - v_n, v_n - (y_n - \lambda_n B y_n) \rangle \ge 0$$
 (3.67)

that is,

$$\left\langle v - v_n, \frac{v_n - y_n}{\lambda_n} + By_n \right\rangle \ge 0.$$
 (3.68)

Therefore, we obtian

$$\langle v - v_{n_{i}}, w \rangle \geq \langle v - v_{n_{i}}, Bv \rangle \geq \langle v - v_{n_{i}}, Bv \rangle - \left\langle v - v_{n_{i}}, \frac{v_{n_{i}} - y_{n_{i}}}{\lambda_{n_{i}}} + By_{n_{i}} \right\rangle$$

$$= \left\langle v - v_{n_{i}}, Bv - By_{n_{i}} - \frac{v_{n_{i}} - y_{n_{i}}}{\lambda_{n_{i}}} \right\rangle$$

$$= \left\langle v - v_{n_{i}}, Bv - Bv_{n_{i}} \right\rangle + \left\langle v - v_{n_{i}}, Bv_{n_{i}} - By_{n_{i}} \right\rangle - \left\langle v - v_{n_{i}}, \frac{v_{n_{i}} - y_{n_{i}}}{\lambda_{n_{i}}} \right\rangle$$

$$\geq \left\langle v - v_{n_{i}}, Bv_{n_{i}} \right\rangle - \left\langle v - v_{n_{i}}, \frac{v_{n_{i}} - y_{n_{i}}}{\lambda_{n_{i}}} + By_{n_{i}} \right\rangle$$

$$= \left\langle v - v_{n_{i}}, Bv_{n_{i}} - By_{n_{i}} \right\rangle - \left\langle v - v_{n_{i}}, \frac{v_{n_{i}} - y_{n_{i}}}{\lambda_{n_{i}}} \right\rangle.$$
(3.69)

Noting that  $||v_{n_i} - y_{n_i}|| \to 0$  as  $i \to \infty$  and B is Lipschitz continuous, hence from (3.69), we obtain

$$\langle v - q, w \rangle \ge 0. \tag{3.70}$$

Since *S* is maximal monotone, we have  $q \in S^{-1}0$ , and hence  $q \in VI(B, C)$ .

(c) We show  $q \in \text{MEP}(\Theta, \varphi)$ . In fact, by  $u_n = T_{r_n} x_n \in \text{dom } \varphi$ , and we have,

$$\Theta(u_n, y) + \varphi(y) - \varphi(u_n) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge 0, \quad \forall y \in C.$$
 (3.71)

From (A2), we also have

$$\varphi(y) - \varphi(u_n) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge \Theta(y, u_n), \quad \forall y \in C,$$
 (3.72)

and hence

$$\varphi(y) - \varphi(u_n) + \left\langle y - u_{n_i}, \frac{u_{n_i} - x_{n_i}}{r_{n_i}} \right\rangle \ge \Theta(y, u_{n_i}), \quad \forall y \in C.$$
 (3.73)

From  $||u_n - x_n|| \to 0$ ,  $||x_n - Tv_n|| \to 0$ , and  $||Tv_n - v_n|| \to 0$ , we get  $u_{n_i} \rightharpoonup q$ . It follows from (A4),  $(u_{n_i} - x_{n_i})/r_{n_i} \to 0$ , and the lower semicontinuous of  $\varphi$  that

$$\Theta(y,z) + \varphi(q) - \varphi(y) \le 0 \quad \forall y \in C. \tag{3.74}$$

For t with  $0 < t \le 1$  and  $y \in C$ , let  $y_t = ty + (1-t)q$ . Since  $y \in C$  and  $q \in C$ , we have  $y_t \in C$  and hence  $\Theta(y_t, q) + \varphi(q) - \varphi(y_t) \le 0$ . So, from (A1) and (A4) and the convexity of  $\varphi$ , we have

$$0 = \Theta(y_t, y_t) + \varphi(y_t) - \varphi(y_t)$$

$$\leq t\Theta(y_t, y) + (1 - t)\Theta(y_t, q) + t\varphi(y) + (1 - t)\varphi(q) - \varphi(y_t)$$

$$\leq t[\Theta(y_t, y) + \varphi(y) - \varphi(y_t)].$$
(3.75)

Dividing by t, we have

$$\Theta(y_t, y) + \varphi(y) - \varphi(y_t) \ge 0, \quad \forall y \in C. \tag{3.76}$$

Letting  $t \to 0$ , it follows from the weakly semicontinuity of  $\varphi$  that

$$\Theta(q, y) + \varphi(y) - \varphi(q) \ge 0, \quad \forall y \in C. \tag{3.77}$$

Hence  $q \in \text{MEP}(\Theta, \varphi)$ . Therefore, the conclusion  $q \in \Omega := F(T) \cap \text{VI}(B, C) \cap \text{MEP}(\Theta, \varphi)$  is proved.

Consequently

$$\limsup_{n\to\infty} \langle (A-\gamma f)z, z-v_n \rangle = \lim_{i\to\infty} \langle (A-\gamma f)z, z-v_{n_i} \rangle = \langle (A-\gamma f)z, z-q \rangle \le 0$$
 (3.78)

as required. This together with (3.40) implies that

$$\limsup_{n \to \infty} \langle \gamma f(z) - Az, x_n - z \rangle = \limsup_{n \to \infty} \langle \gamma f(z) - Az, (x_n - v_n) + (v_n - z) \rangle$$

$$\leq \limsup_{n \to \infty} \langle \gamma f(z) - Az, v_n - z \rangle$$

$$\leq 0. \tag{3.79}$$

Step 6. Finally, we show that  $x_n \to z$ ,  $y_n \to z$ ,  $u_n \to z$ . Indeed, we note that

$$\begin{aligned} \|x_{n+1} - z\|^2 &= \|\alpha_n \gamma f(x_n) + \delta_n x_n + ((1 - \delta_n)I - \alpha_n A)v_n - z\|^2 \\ &= \|((1 - \delta_n)I - \alpha_n A)(v_n - z) + \delta_n (x_n - z) + \alpha_n (\gamma f(x_n) - Az)\|^2 \\ &= \|((1 - \delta_n)I - \alpha_n A)(v_n - z) + \delta_n (x_n - z)\|^2 + \alpha_n^2 \|\gamma f(x_n) - Az\|^2 \\ &+ 2\delta_n \alpha_n (x_n - z, \gamma f(x_n) - Az) \\ &+ 2\alpha_n (((1 - \delta_n)I - \alpha_n A)(v_n - z), \gamma f(x_n) - Az) \\ &\leq ((1 - \delta_n - \alpha_n \overline{\gamma})\|v_n - z\| + \delta_n \|x_n - z\|^2 + \alpha_n^2 \|\gamma f(x_n) - Az\|^2 \\ &+ 2\delta_n \alpha_n \gamma (x_n - z, f(x_n) - f(z)) + 2\delta_n \alpha_n (x_n - z, \gamma f(z) - A(z)) \\ &+ 2(1 - \delta_n)\gamma \alpha_n (v_n - z, f(x_n) - f(z)) + 2(1 - \delta_n)\alpha_n (v_n - z, \gamma f(z) - Az) \\ &- 2\alpha_n^2 (A(v_n - z), \gamma f(z) - Az) \\ &\leq ((1 - \delta_n - \alpha_n \overline{\gamma})\|x_n - z\| + \delta_n \|x_n - z\|^2 + \alpha_n^2 \|\gamma f(x_n) - Az)\|^2 \\ &+ 2\delta_n \alpha_n \gamma \alpha \|x_n - z\|^2 + 2\delta_n \alpha_n (x_n - z, \gamma f(q) - Az) \\ &+ 2(1 - \delta_n)\gamma \alpha_n \alpha \|x_n - z\|^2 + 2(1 - \delta_n)\alpha_n (v_n - z, \gamma f(z) - Az) \\ &- 2\alpha_n^2 (A(v_n - z), \gamma f(q) - Az) \\ &= \left[ (1 - \alpha_n \overline{\gamma})^2 + 2\delta_n \alpha_n \gamma \alpha + 2(1 - \delta_n)\gamma \alpha_n \alpha \right] \|x_n - z\|^2 + \alpha_n^2 \|\gamma f(x_n) - Az\|^2 \\ &+ 2\delta_n \alpha_n (x_n - z, \gamma f(z) - Az) + 2(1 - \delta_n)\alpha_n (v_n - z, \gamma f(z) - Az) \\ &- 2\alpha_n^2 (A(v_n - z), \gamma f(z) - Az) \\ &\leq \left[ 1 - 2(\overline{\gamma} - \alpha_n \gamma)\alpha_n \right] \|x_n - z\|^2 + \overline{\gamma}^2 \alpha_n^2 \|x_n - z\|^2 + \alpha_n^2 \|\gamma f(x_n) - Az\|^2 \\ &+ 2\delta_n \alpha_n (x_n - z, \gamma f(z) - Az) + 2(1 - \delta_n)\alpha_n (v_n - z, \gamma f(z) - Az) \\ &+ 2\alpha_n^2 \|A(v_n - z)\|\|\gamma f(z) - Az\| \\ &= \left[ 1 - 2(\overline{\gamma} - \alpha_n \gamma)\alpha_n \right] \|x_n - z\|^2 + \overline{\gamma}^2 \alpha_n^2 \|x_n - z\|^2 + \alpha_n^2 \|\gamma f(x_n) - Az\|^2 \\ &+ 2(1 - \delta_n)\gamma (v_n - z, \gamma f(z) - Az) \right] \\ &+ 2(1 - \delta_n)(v_n - z, \gamma f(z) - Az) \right\}. \end{aligned}$$

Since  $\{x_n\}$ ,  $\{f(x_n)\}$ , and  $\{v_n\}$  are bounded, we can take a constant K > 0 such that

$$\overline{\gamma}^{2} \|x_{n} - z\|^{2} + \|\gamma f(x_{n}) - Az\|^{2} + 2\|A(v_{n} - z)\| \|\gamma f(z) - Az\| \le K$$
(3.81)

for all  $n \ge 0$ . It then follows that

$$||x_{n+1} - z||^2 \le \left[1 - 2(\overline{\gamma} - \alpha_n \gamma)\alpha_n\right] ||x_n - z||^2 + \alpha_n \sigma_n, \tag{3.82}$$

where

$$\sigma_n = 2\delta_n \langle x_n - z, \gamma f(z) - Az \rangle + 2(1 - \delta_n) \langle v_n - z, \gamma f(z) - Az \rangle + \alpha_n K \tag{3.83}$$

Using (D1), and (3.79), we get  $\limsup_{n\to\infty} \delta_n \le 0$ . Now applying Lemma 2.1 to (3.82), we conclude that  $x_n\to z$ . From  $\|x_n-y_n\|\to 0$  and  $\|x_n-u_n\|\to 0$ , we obtain  $y_n\to z$ ,  $u_n\to z$ . The proof is now complete.

By Theorem 3.1, we can obtain some new and interesting strong convergence theorems. Now we give some examples as follows.

Setting  $\varphi = 0$  in Theorem 3.1, we have the following result.

**Corollary 3.2.** Let C be a nonempty closed convex subset of a Hilbert space H. Let  $\Theta$  be a bifunction from  $C \times C$  to  $\mathbb{R}$  satisfies (A1)–(A4). Let T be a k-strictly pseudocontractive mapping of C into itself. Let f be a contraction of C into itself with coefficient  $\beta \in (0,1)$ , B an  $\alpha$ -inverse-strongly monotone mapping of C into H such that  $\Omega := F(T) \cap VI(B,C) \cap EP(\Theta) \neq \emptyset$ . Let A be a strongly bounded linear self-adjoint operator with coefficient  $\overline{\gamma} > 0$  and  $0 < \gamma < \overline{\gamma}/\beta$ . Given the sequences  $\{\alpha_n\}$ ,  $\{\beta_n\}$ ,  $\{\delta_n\}$ ,  $\{\delta_n\}$ , and  $\{r_n\}$  in [0,1] satisfies the following conditions

- (D1)  $\lim_{n\to\infty}\alpha_n=0$ ,  $\sum_{n=1}^{\infty}\alpha_n=\infty$ ;
- (D2)  $0 < \liminf_{n \to \infty} \delta_n \le \limsup_{n \to \infty} \delta_n < 1$ ;
- (D3)  $0 \le k \le \beta_n < \varepsilon < 1$  for all  $n \ge 0$ , and  $\lim_{n \to \infty} |\beta_{n+1} \beta_n| = 0$ ;
- (D4)  $\{\lambda_n\} \subset [a,b]$  for some a, b with  $0 < a < b < 2\alpha$ , and  $\lim_{n \to \infty} |\lambda_{n+1} \lambda_n| = 0$
- (D5)  $\liminf_{n\to\infty} r_n > 0$ ,  $\lim_{n\to\infty} |r_{n+1} r_n| = 0$ .

Let  $\{x_n\}$ ,  $\{u_n\}$ , and  $\{y_n\}$  be sequences generated by

 $x_1 = x \in C$  chosen arbitrarily,

$$\Theta(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge 0, \quad \forall y \in C,$$

$$y_n = \beta_n u_n + (1 - \beta_n) T u_n,$$

$$x_{n+1} = \alpha_n \gamma f(x_n) + \delta_n x_n + ((1 - \delta_n) I - \alpha_n A) P_C(y_n - \lambda_n B y_n), \quad n \ge 1.$$
(3.84)

Then  $\{x_n\}$ ,  $\{u_n\}$  and  $\{y_n\}$  converge strongly to a point  $z \in \Omega$  which is the unique solution of the variational inequality

$$\langle (A - \gamma f)z, z - x \rangle \le 0, \quad \forall x \in \Omega.$$
 (3.85)

Equivalently, one has  $z = P_{\Omega}(I - A + \gamma f)(z)$ .

Setting  $\Theta = 0$ ,  $r_n = 1$  and  $\varphi = 0$  in Theorem 3.1, we have  $x_n = u_n$ , then the following result is obtained.

**Corollary 3.3.** Let C be a nonempty closed convex subset of a Hilbert space H. Let T be a k-strictly pseudocontractive mapping of C into itself. Let f be a contraction of C into itself with coefficient  $\beta \in (0,1)$ , B an  $\alpha$ -inverse-strongly monotone mapping of C into H such that  $\Omega := F(T) \cap VI(B,C) \neq \emptyset$ . Let A be a strongly bounded linear self-adjoint operator with coefficient  $\overline{\gamma} > 0$  and  $0 < \gamma < \overline{\gamma}/\beta$ . Given the sequences  $\{\alpha_n\}$ ,  $\{\beta_n\}$ ,  $\{\delta_n\}$  and  $\{\lambda_n\}$  in [0,1] satisfies the following conditions

- (D1)  $\lim_{n\to\infty} \alpha_n = 0$ ,  $\sum_{n=1}^{\infty} \alpha_n = \infty$ ;
- (D2)  $0 < \liminf_{n \to \infty} \delta_n \le \limsup_{n \to \infty} \delta_n < 1$ ;
- (D3)  $0 \le k \le \beta_n < \varepsilon < 1$  for all  $n \ge 0$ , and  $\lim_{n \to \infty} |\beta_{n+1} \beta_n| = 0$ ;
- (D4)  $\{\lambda_n\} \subset [a,b]$  for some a,b with  $0 < a < b < 2\alpha$  and  $\lim_{n \to \infty} |\lambda_{n+1} \lambda_n| = 0$ .

Let  $\{x_n\}$  and  $\{y_n\}$  be sequences generated by

$$x_1 = x \in C \text{ chosen arbitrarily,}$$
 
$$y_n = \beta_n x_n + (1 - \beta_n) T x_n,$$
 
$$(3.86)$$
 
$$x_{n+1} = \alpha_n \gamma f(x_n) + \delta_n x_n + ((1 - \delta_n) I - \alpha_n A) P_C(y_n - \lambda_n B y_n), \quad n \ge 1.$$

Then  $\{x_n\}$  and  $\{y_n\}$  converge strongly to a point  $z \in \Omega$  which is the unique solution of the variational inequality

$$\langle (A - \gamma f)z, z - x \rangle \le 0, \quad \forall x \in \Omega.$$
 (3.87)

Equivalently, one has  $z = P_{\Omega}(I - A + \gamma f)(z)$ .

*Remark 3.4.* (i) Since the conditions (C1) and (C2) have been weakened by the conditions (D1) and (D3) respectively. Theorem 3.1 and Corollary 3.2 generalize and improve [44, Theorem 3.2].

- (ii) We can remove the control condition  $\lim_{n\to\infty}\beta_n=\varepsilon$  on the parameter  $\{\beta_n\}$  in (C'2).
- (iii) Since the conditions (C1) and (C2) have been weakened by the conditions (D1) and (D3) respectively. Theorem 3.1 and Corollary 3.3 generalize and improve [43, Theorem 2.1].

Setting  $\varphi = 0$ ,  $\beta_n = 0$ , B = 0 and T is nonexpansive in Theorem 3.1, we have the following result.

**Corollary 3.5.** Let C be a nonempty closed convex subset of a Hilbert space H. Let  $\Theta$  be a bifunction from  $C \times C$  to  $\mathbb{R}$  satisfies (A1)–(A4). Let T be a nonexpansive mapping of C into itself. Let f be a contraction of C into itself with coefficient  $\beta \in (0,1)$  such that  $\Omega := F(T) \cap EP(\Theta) \neq \emptyset$ . Let A be a strongly bounded linear self-adjoint operator with coefficient  $\overline{\gamma} > 0$  and  $0 < \gamma < \overline{\gamma}/\beta$ . Given the sequences  $\{\alpha_n\}$ ,  $\{\delta_n\}$ , and  $\{r_n\}$  in [0,1] satisfies the following conditions

- (D1)  $\lim_{n\to\infty}\alpha_n=0$ ,  $\sum_{n=1}^{\infty}\alpha_n=\infty$ ;
- (D2)  $0 < \liminf_{n \to \infty} \delta_n \le \limsup_{n \to \infty} \delta_n < 1$ ;
- (D3)  $\liminf_{n\to\infty} r_n > 0$ ,  $\lim_{n\to\infty} |r_{n+1} r_n| = 0$ .

Let  $\{x_n\}$ ,  $\{u_n\}$ , and  $\{y_n\}$  be sequences generated by

 $x_1 = x \in C$  chosen arbitrarily,

$$\Theta(u_n, y) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge 0, \quad \forall y \in C,$$
(3.88)

$$x_{n+1} = \alpha_n \gamma f(x_n) + \delta_n x_n + ((1 - \delta_n)I - \alpha_n A)Tu_n, \quad n \ge 1.$$

Then  $\{x_n\}$ ,  $\{u_n\}$  and  $\{y_n\}$  converge strongly to a point  $z \in \Omega$  which is the unique solution of the variational inequality

$$\langle (A - \gamma f)z, z - x \rangle \le 0, \quad \forall x \in \Omega.$$
 (3.89)

Equivalently, one has  $z = P_{\Omega}(I - A + \gamma f)(z)$ .

Remark 3.6. Since the conditions  $\sum_{n=1}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty$  and  $\sum_{n=1}^{\infty} |r_{n+1} - r_n| < \infty$  have been weakened by the conditions  $\lim_{n\to\infty} |\alpha_{n+1} - \alpha_n| = 0$  and  $\lim_{n\to\infty} |r_{n+1} - r_n| = 0$ , respectively. Hence Corollary 3.5 generalize, extend and improve [17, Theorem 3.3].

## 4. Applications

First, we will utilize the results presented in this paper to study the following optimization problem:

$$\min_{y \in C} \varphi(y), \tag{4.1}$$

where C is a nonempty bounded closed convex subset of a Hilbert space and  $\varphi: C \to \mathbb{R} \cup \{+\infty\}$  is a proper convex and lower semicontinuous function. We denote by  $\operatorname{Argmin}(\varphi)$  the set of solutions in (4.1). Let  $\Theta(x,y)=0$  for all  $x,y\in C$ ,  $\gamma\equiv 1$ ,  $A\equiv I$ , T=I and f:=x in Theorem 3.1, then  $\operatorname{MEP}(\Theta,\varphi)=\operatorname{Argmin}(\varphi)$ . It follows from Theorem 3.1 that the iterative sequence  $\{x_n\}$  is defined by

 $x_1 = x \in C$  chosen arbitrarily,

$$u_n = \underset{y \in C}{\operatorname{argmin}} \left\{ \varphi(y) + \frac{1}{2r_n} \|y - x_n\|^2 \right\},$$
 (4.2)

$$x_{n+1} = \alpha_n x + \delta_n x_n + (1 - \delta_n - \alpha_n) P_C(u_n - \lambda_n B u_n), \quad n \ge 1,$$

where  $\{\alpha_n\}$ ,  $\{\delta_n\} \subseteq [0,1]$ ,  $\{\lambda_n\}$ ,  $\{r_n\} \subseteq (0,1)$  satisfy the conditions (D1)–(D5) in Theorem 3.1. Then the sequence  $\{x_n\}$  converges strongly to a solution  $z = P_{VI(A,C) \cap Argmin(\phi)}x$ .

Let  $\Theta(x,y)=0$  for all  $x,y\in C$ , T=I,  $\gamma\equiv 1$ ,  $A\equiv I$ , f:=x and  $B\equiv 0$  in Theorem 3.1, then  $\text{MEP}(\Theta,\varphi)=\text{Argmin}(\varphi)$ . It follows from Theorem 3.1 that the iterative sequence  $\{x_n\}$  defined by

 $x_1 = x \in C$  chosen arbitrarily,

$$u_n = \underset{y \in C}{\operatorname{argmin}} \left\{ \varphi(y) + \frac{1}{2r_n} \|y - x_n\|^2 \right\},$$
 (4.3)

$$x_{n+1} = \alpha_n x + \delta_n x_n + (1 - \delta_n - \alpha_n) u_n, \quad \forall n \ge 1,$$

where  $\{\alpha_n\}$ ,  $\{\delta_n\} \subseteq [0,1]$ , and  $\{r_n\} \subseteq (0,\infty)$  satisfy the conditions (D1), (D2) and (D5), respectively in Theorem 3.1. Then the sequence  $\{x_n\}$  converges strongly to a solution  $z = P_{\operatorname{Argmin}(\varphi)}x$ .

We remark that the algorithms (4.2) and (4.3) are variants of the proximal method for optimization problems introduced and studied by Martinet [49], Rockafellar [45], Ferris [50] and many others.

Next, we give the strong convergence theorem for finding a common element of the set of common fixed point of a finite family of strictly pseudocontractive mappings, the set of solutions of the variational inequality problem and the set of solutions of the mixed equilibrium problem in a Hilbert space.

**Theorem 4.1.** Let C be a nonempty closed convex subset of a Hilbert space H. Let  $\Theta$  be a bifunction from  $C \times C$  to  $\mathbb{R}$  satisfies (A1)–(A4) and  $\varphi: C \to \mathbb{R} \cup \{+\infty\}$  be a proper lower semicontinuous and convex function. For each  $i=1,2,\ldots,N$ , let  $T_i$  be a  $k_i$ -strictly pseudocontractive mapping of C into itself for some  $0 \le k_i < 1$ . Let f be a contraction of C into itself with coefficient  $\beta \in (0,1)$ , B an  $\alpha$ -inverse-strongly monotone mapping of C into C

- (D1)  $\lim_{n\to\infty} \alpha_n = 0$ ,  $\sum_{n=1}^{\infty} \alpha_n = \infty$ ;
- (D2)  $0 < \liminf_{n \to \infty} \delta_n \le \limsup_{n \to \infty} \delta_n < 1$ ;
- (D3)  $0 \le \max\{k_i : i = 1, 2, ..., N\} \le \beta_n < \beta < 1 \text{ for all } n \ge 0, \text{ and } \lim_{n \to \infty} |\beta_{n+1} \beta_n| = 0;$
- (D4)  $\{\lambda_n\} \subset [a,b]$  for some a,b with  $0 < a < b < 2\alpha$  and  $\lim_{n\to\infty} |\lambda_{n+1} \lambda_n| = 0$ ;
- (D5)  $\liminf_{n\to\infty} r_n > 0$ ,  $\lim_{n\to\infty} |r_{n+1} r_n| = 0$ .

Let  $\{x_n\}$ ,  $\{u_n\}$  and  $\{y_n\}$  be sequences generated by

 $x_0 = x \in C$  chosen arbitrarily,

$$\Theta(u_n, y) + \varphi(y) - \varphi(u_n) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge 0, \quad \forall y \in C,$$

$$y_n = \beta_n u_n + (1 - \beta_n) \sum_{i=1}^N \eta_i T_i u_n,$$

$$(4.4)$$

$$x_{n+1} = \alpha_n \gamma f(x_n) + \delta_n x_n + ((1 - \delta_n)I - \alpha_n A) P_C(y_n - \lambda_n B y_n), \quad n \ge 1,$$

where  $\eta_i$  is a positive constant such that  $\eta_1 + \eta_2 + \cdots + \eta_N = 1$ . Then both  $\{x_n\}, \{u_n\}$  and  $\{y_n\}$  converge strongly to a point  $z \in \Omega$  which is the unique solution of the variational inequality

$$\langle (A - \gamma f)z, z - x \rangle \le 0, \quad x \in \Omega. \tag{4.5}$$

Equivalently, one has  $z = P_{\Omega}(I - A + \gamma f)(z)$ .

*Proof.* Let  $\{\eta_i\}_{i=1}^N \subset (0,1)$  such that  $\sum_{i=1}^N \eta_i = 1$  and define  $Tx = \sum_{i=1}^N \eta_i T_i x$ . By Lemmas 2.5 and 2.6, we conclude that  $T: C \to C$  is a k-strictly pseudocontractive mapping with  $k = \max\{k_i: 1 \le i \le N\}$  and  $F(T) = F(\sum_{i=1}^N \eta_i T_i) = \bigcap_{i=1}^N F(T_i)$ . From Theorem 3.1, we can obtain the desired conclusion easily.

Finally, we will apply the main results to the problem for finding a common element of the set of fixed points of two finite families of *k*-strictly pseudocontractive mappings, the set of solutions of the variational inequality and the set of solutions of the mixed equilibrium problem.

Let  $S_i: C \to H$  be a  $k_i$ -strictly pseudocontractive mapping for some  $0 \le k_i < 1$ . We define a mapping  $B = I - \sum_{i=1}^N \xi_i S_i : C \to H$  where  $\{\xi_i\}_{i=1}^N$  is a positive sequence such that  $\sum_{i=1}^N \xi_i = 1$ , then B is a (1-k)/2-inverse-strongly monotone mapping with  $k = \max\{k_i : 1 \le i \le N\}$ . In fact, from Lemma 2.5, we have

$$\left\| \sum_{i=1}^{N} \xi_{i} S_{i} x - \sum_{i=1}^{N} \xi_{i} S_{i} y \right\|^{2} \leq \|x - y\|^{2} + k \left\| \left( I - \sum_{i=1}^{N} \xi_{i} S_{i} \right) x - \left( I - \sum_{i=1}^{N} \xi_{i} S_{i} \right) y \right\|^{2}, \quad \forall x, \ y \in C.$$
(4.6)

That is

$$\|(I - B)x - (I - B)y\|^{2} \le \|x - y\|^{2} + k\|Bx - By\|^{2}.$$
(4.7)

On the other hand

$$\|(I - B)x - (I - B)y\|^2 = \|x - y\|^2 - 2\langle x - y, Bx - By \rangle + \|Bx - By\|^2.$$
 (4.8)

Hence we have

$$\langle x - y, Bx - By \rangle \ge \frac{1 - k}{2} \|Bx - By\|^2. \tag{4.9}$$

This shows that *B* is (1 - k)/2-inverse-strongly monotone.

**Theorem 4.2.** Let C be a nonempty closed convex subset of a Hilbert space H. Let  $\Theta$  be a bifunction from  $C \times C$  to  $\mathbb{R}$  satisfies (A1)–(A4) and  $\varphi: C \to \mathbb{R} \cup \{+\infty\}$  be a proper lower semicontinuous and convex function. Let  $\{T_1, T_2, \ldots, T_N\}$  be a finite family of  $k_i^T$ -strictly pseudocontractive mapping of C into itself and  $\{S_1, S_2, \ldots, S_N\}$  be a finite family of  $k_i^S$ -strictly pseudocontractive mapping of C into C into C into itself with coefficient C into C in

operator with coefficient  $\overline{\gamma} > 0$  and  $0 < \gamma < \overline{\gamma}/\beta$ . Assume that either (B1) or (B2) holds. Given the sequences  $\{\alpha_n\}$ ,  $\{\beta_n\}$ ,  $\{\delta_n\}$ ,  $\{\lambda_n\}$  and  $\{r_n\}$  in [0,1] satisfies the following conditions

- (D1)  $\lim_{n\to\infty}\alpha_n=0$ ,  $\sum_{n=1}^{\infty}\alpha_n=\infty$ ;
- (D2)  $0 < \liminf_{n \to \infty} \delta_n \le \limsup_{n \to \infty} \delta_n < 1$ ;
- (D3)  $0 \le \max_{1 \le i \le N} k_i^T \le \beta_n < \beta < 1 \text{ and } 0 \le \max_{1 \le i \le N} k_i^S \le \beta_n < \beta < 1 \text{ for all } n \ge 0, \text{ and } \lim_{n \to \infty} |\beta_{n+1} \beta_n| = 0;$
- (D4)  $\{\lambda_n\} \subset [a,b]$  for some a,b with  $0 < a < b < 2\alpha$  and  $\lim_{n\to\infty} |\lambda_{n+1} \lambda_n| = 0$ ;
- (D5)  $\lim \inf_{n \to \infty} r_n > 0$ ,  $\lim_{n \to \infty} |r_{n+1} r_n| = 0$ .

Let  $\{x_n\}$ ,  $\{u_n\}$  and  $\{y_n\}$  be sequences generated by

 $x_1 = x \in C$  chosen arbitrarily,

$$\Theta(u_n, y) + \varphi(y) - \varphi(u_n) + \frac{1}{r_n} \langle y - u_n, u_n - x_n \rangle \ge 0, \quad \forall y \in C,$$

$$y_n = \beta_n u_n + (1 - \beta_n) \sum_{i=1}^N \eta_i T_i u_n,$$
(4.10)

$$x_{n+1} = \alpha_n \gamma f(x_n) + \delta_n x_n + ((1 - \delta_n)I - \alpha_n A) P_C \left( (1 - \lambda_n) y_n - \lambda_n \sum_{i=1}^N \xi_i S_i y_n \right), \quad n \ge 1,$$

where  $\eta_i$  and  $\xi_i$  are positive constants such that  $\sum_{i=1}^N \eta_i = 1$  and  $\sum_{i=1}^N \xi_i = 1$ , respectively. Then  $\{x_n\}$ ,  $\{u_n\}$  and  $\{y_n\}$  converge strongly to a point  $z \in \Omega$  which is the unique solution of the variational inequality

$$\langle (A - \gamma f)z, z - x \rangle \le 0, \quad x \in \Omega.$$
 (4.11)

Equivalently, we have  $z = P_{\Omega}(I - A + \gamma f)(z)$ .

*Proof.* Taking  $B = I - \sum_{i=1}^N \xi_i S_i : C \to H$  in Theorem 4.1, we know that  $B : C \to H$  is  $\alpha$ -inverse strongly monotone with  $\alpha = (1-k)/2$ . Hence, B is a monotone L-Lipschitz continuous mapping with  $L = 2/(1-k^T)$ . From Lemma 2.6, we know that  $\sum_{i=1}^N \xi_i S_i$  is a  $k^T$ -strictly pseudocontractive mapping with  $k^T = \max\{k_i^T : 1 \le i \le N\}$  and then  $F(\sum_{i=1}^N \xi_i S_i) = VI(B,C)$  by Lemma 2.6. Observe that

$$P_C(y_n - \lambda_n B y_n) = P_C\left((1 - \lambda_n)y_n - \lambda_n \sum_{i=1}^N \xi_i S_i y_n\right). \tag{4.12}$$

The conclusion can be obtained from Theorem 4.1.

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