# ON JORDAN IDEALS AND LEFT $(\theta, \theta)$-DERIVATIONS IN PRIME RINGS 

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#### Abstract

Let $R$ be a ring and $S$ a nonempty subset of $R$. Suppose that $\theta$ and $\phi$ are endomorphisms of $R$. An additive mapping $\delta: R \rightarrow R$ is called a left $(\theta, \phi)$-derivation (resp., Jordan left $(\theta, \phi)$ derivation) on $S$ if $\delta(x y)=\theta(x) \delta(y)+\phi(y) \delta(x)$ (resp., $\delta\left(x^{2}\right)=\theta(x) \delta(x)+\phi(x) \delta(x)$ ) holds for all $x, y \in S$. Suppose that $J$ is a Jordan ideal and a subring of a 2 -torsion-free prime ring $R$. In the present paper, it is shown that if $\theta$ is an automorphism of $R$ such that $\delta\left(x^{2}\right)=2 \theta(x) \delta(x)$ holds for all $x \in J$, then either $J \subseteq Z(R)$ or $\delta(J)=(0)$. Further, a study of left $(\theta, \theta)$-derivations of a prime ring $R$ has been made which acts either as a homomorphism or as an antihomomorphism of the ring $R$.


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1. Introduction. Throughout the present paper, $R$ will denote an associative ring with centre $Z(R)$. We will write for all $x, y \in R,[x, y]=x y-y x$ and $x \circ y=x y+y x$ for the Lie product and Jordan product, respectively. A ring $R$ is said to be prime if $a R b=(0)$ implies that $a=0$ or $b=0$. A ring $R$ is said to be 2 -torsion-free if whenever $2 a=0$, with $a \in R$, then $a=0$. An additive subgroup $J$ of $R$ is said to be a Jordan ideal of $R$ if $u \circ r \in J$, for all $u \in J$ and $r \in R$. An additive mapping $d: R \rightarrow R$ is called a derivation (resp., Jordan derivation) if $d(x y)=d(x) y+x d(y)$ (resp., $d\left(x^{2}\right)=d(x) x+x d(x)$ ) holds for all $x, y \in R$. Let $\theta, \phi$ be endomorphisms of $R$. An additive mapping $f: R \rightarrow R$ is called a $(\theta, \phi)$-derivation (resp., Jordan $(\theta, \phi)$ derivation) if $f(x y)=f(x) \theta(y)+\phi(x) f(y)$ (resp., $\left.f\left(x^{2}\right)=f(x) \theta(x)+\phi(x) f(x)\right)$ holds, for all $x, y \in R$. Of course a ( 1,1 )-derivation (resp., a Jordan (1,1)-derivation) is a derivation (resp., a Jordan derivation) on $R$, where 1 is the identity mapping on $R$. We will make use of the following basic commutator identities without any specific mention:

$$
\begin{equation*}
[x y, z]=x[y, z]+[x, z] y, \quad[x, y z]=y[x, z]+[x, y] z . \tag{1.1}
\end{equation*}
$$

An additive mapping $\delta: R \rightarrow R$ is called a left derivation (resp., Jordan left derivation) if $\delta(x y)=x \delta(y)+y \delta(x)$ (resp., $\left.\delta\left(x^{2}\right)=2 x \delta(x)\right)$ holds for all $x, y \in R$. In view of the definition of a $(\theta, \phi)$-derivation, the notion of left $(\theta, \phi)$-derivation can be extended as follows: let $\theta, \phi$ be endomorphisms of $R$ and let $S$ be a nonempty subset of $R$. An additive mapping $\delta: R \rightarrow R$ is called a left $(\theta, \phi)$-derivation (resp., Jordan left $(\theta, \phi)$-derivation) on $S$ if $\delta(x y)=\theta(x) \delta(y)+\phi(y) \delta(x)$ (resp., $\delta\left(x^{2}\right)=$ $\theta(x) \delta(x)+\phi(x) \delta(x))$ holds for all $x, y \in S$. Clearly, a left (1,1)-derivation (resp., a Jordan left (1,1)-derivation) is a left derivation (resp., a Jordan left derivation) on $R$,
where 1 is the identity mapping on $R$. In [5], Brešar and Vukman have proved that the existence of a nonzero Jordan left derivation on a prime ring $R$ of $\operatorname{char} R \neq 2$,3 forces $R$ to be commutative. It should be mentioned that the result obtained in [5] concerning Jordan left derivation has been improved by Deng [7]. Some more related results can be seen in $[1,3,5,7,9]$. It is easy to see that every left derivation on a ring $R$ is a Jordan left derivation. However, in general, a Jordan left derivation need not be a left derivation. The following example justifies this statement.

ExAmple 1.1. Let $R$ be a commutative ring and let $a \in R$ such that $x a x=0$ for all $x \in R$ but $x a y \neq 0$, for some $x$ and $y, x \neq y$. Define a map $\delta: R \rightarrow R$ as follows:

$$
\begin{equation*}
\delta(x)=x a+a x \tag{1.2}
\end{equation*}
$$

Then $\delta$ is a Jordan left derivation but not a left derivation.
In the present paper, first it is shown that every Jordan left $(\theta, \theta)$-derivation on a Jordan ideal $J$ of a 2-torsion-free prime ring is a left $(\theta, \theta)$-derivation on $J$. Finally, we will study the behaviour of left $(\theta, \theta)$-derivation on a prime ring which also acts either as a homomorphism or an antihomomorphism of the underlying ring.
2. Preliminary results. We begin with the following lemmas which are essential in developing the proof of our main result.

Lemma 2.1 [6, Lemma 4]. Let $G$ and $H$ be additive groups and let $R$ be a 2 -torsion-free ring. Let $f: G \times G \rightarrow H$ and $g: G \times G \rightarrow R$ be biadditive mappings. Suppose that for each pair $a, b \in G$ either $f(a, b)=0$ or $g(a, b)^{2}=0$. In this case, either $f=0$ or $g(a, b)^{2}=0$ for all $a, b \in G$.

If $J$ is assumed to be a Jordan ideal and a subring of a ring $R$, then using similar techniques as used in the proofs of Lemmas 2.2 and 2.3 of [1], one can easily obtain the following lemma.

Lemma 2.2. Let $R$ be a 2-torsion-free ring, let $J$ be a Jordan ideal and a subring of $R$. If $\theta$ is an endomorphism of $R$ and $\delta: R \rightarrow R$ is an additive mapping satisfying $\delta\left(u^{2}\right)=2 \theta(u) \delta(u)$, for all $u \in J$, then
(i) $\delta(u v+v u)=2 \theta(u) \delta(v)+2 \theta(v) \delta(u)$, for all $u, v \in J$,
(ii) $\delta(u v u)=\theta\left(u^{2}\right) \delta(v)+3 \theta(u) \theta(v) \delta(u)-\theta(v) \theta(u) \delta(u)$, for all $u, v \in J$,
(iii) $\delta(u v w+w v u)=(\theta(u) \theta(w)+\theta(w) \theta(u)) \delta(v)+3 \theta(u) \theta(v) \delta(w)+$ $3 \theta(w) \theta(v) \delta(u)-\theta(v) \theta(u) \delta(w)-\theta(v) \theta(w) \delta(u)$, for all $u, v, w \in J$,
(iv) $[\theta(u), \theta(v)] \theta(u) \delta(u)=\theta(u)[\theta(u), \theta(v)] \delta(u)$, for all $u, v \in J$,
(v) $[\theta(u), \theta(v)](\delta(u v)-\theta(u) \delta(v)-\theta(v) \delta(u))=0$, for all $u, v \in J$.

Lemma 2.3. Let $R$ be a 2-torsion-free ring, J a Jordan ideal and a subring of R. If $\theta$ is an endomorphism of $R$ and $\delta: R \rightarrow R$ is an additive mapping satisfying $\delta\left(u^{2}\right)=2 \theta(u) \delta(u)$ for all $u \in J$, then
(i) $[\theta(u), \theta(v)] \delta([u, v])=0$, for all $u, v \in J$;
(ii) $\left(\theta\left(u^{2}\right) \theta(v)-2 \theta(u) \theta(v) \theta(u)+\theta(v) \theta\left(u^{2}\right)\right) \delta(v)=0$, for all $u, v \in J$.

We begin with the following lemma.
Lemma 2.4. If $R$ is a ring and $J$ a nonzero Jordan ideal of $R$, then $2[R, R] J \subseteq J$ and $2 J[R, R] \subseteq J$.

Proof. Let $x, y \in R$ and $u \in J$. Then $u \circ[x, y]-(u \circ x) \circ y+(u \circ y) \circ x \in J$. This implies that $u x y-u y x+x y u-y x u-u x y-x u y-y u x-y x u+u y x+y u x+$ $x u y+x y u \in J$ and hence $2[x, y] u \in J$, for all $x, y \in R$, and $u \in J$, that is, $2[R, R] J \subseteq J$.

Similarly, it is easy to see that $2 u[x, y]=(u \circ y) \circ x-u \circ[x, y]-(u \circ x) \circ y \in J$, for all $x, y \in R$ and $u \in J$, and hence $2 J[R, R] \subseteq J$.

Lemma 2.5. Let $R$ be a prime ring and $J$ a nonzero Jordan ideal of $R$. If $a \in R$ and $a J=(0)($ or $J a=(0))$, then $a=0$.

Proof. Since $J$ is a Jordan ideal of $R, u \circ x \in J$, for all $x \in R$ and $u \in J$. By hypotheses, we have $a(u \circ x)=0$, for all $x \in R, u \in J$, and hence we get $a x u=0$, for all $x \in R$, $u \in J$, that is, $a R J=(0)$. Since $J$ is a nonzero Jordan ideal and $R$ is prime, the above relation yields that $a=0$.

If $J a=(0)$, then using similar arguments with necessary variations, we get the required result.

Lemma 2.6. Let $R$ be a 2-torsion-free prime ring and $J$ a nonzero Jordan ideal of $R$. If $a J b=(0)$, then $a=0$ or $b=0$.

Proof. By Lemma 2.4, we find that $2[R, R] J \subseteq J$. Thus, for any $x, y \in R$ and $u \in J$, we have $2 a[x, y] u b=0$. This implies that

$$
\begin{equation*}
a[x, y] u b=0, \quad \forall x, y \in R, u \in J \tag{2.1}
\end{equation*}
$$

Replacing $y$ by $y a$ in the above expression, we get $a[x, y a] u b=0$, for all $x, y \in R$ and $u \in J$ or $a y[x, a] u b+a[x, y] a u b=0$. Now, using the fact that $a J b=(0)$, we find that $a y[x, a] u b=0$, for all $x, y \in R$ and $u \in J$ and hence $a R[x, a] u b=(0)$. Thus, primeness of $R$ forces that either $a=0$ or $[x, a] u b=0$. If $[x, a] u b=0$, for all $x \in R, u \in J$, then by our hypotheses we have $a x u b=0$, for all $x \in R, u \in J$, that is, $a R u b=(0)$. Again, primeness of $R$ gives that either $a=0$ or $u b=0$. If $u b=0$, for all $u \in J$, then by Lemma 2.5 , we get $b=0$.

Lemma 2.7. Let $R$ be a 2 -torsion-free prime ring and $J$ a nonzero Jordan ideal of $R$. If $J$ is a commutative Jordan ideal, then $J \subseteq Z(R)$.

Proof. By Lemma 2.4, we have $2[R, R] J \subseteq J$. Thus, for any $x, y \in R$ and $u, v \in J$, we find that $[2[x, y] u, v]=0$ and hence $2[[x, y], v] u+2[x, y][u, v]=0$, for all $x, y \in R$ and $u, v \in J$. By hypotheses, we obtain $[[x, y], v] u=0$, for all $x, y \in R$ and $u, v \in J$. Using Lemma 2.5, we get $[[x, y], v]=0$, for all $x, y \in R$ and $v \in J$. Now, replace $y$ by $x y$ to get $[x, v][x, y]=0$, for all $x, y \in R$ and $v \in J$. Further replacing $y$ by $y v$, we have $[x, v] y[x, v]=0$, for all $x, y \in R$ and $v \in J$. This implies that $[x, v] R[x, v]=(0)$, for all $x \in R, v \in J$. Now, primeness of $R$ forces that $v \in Z(R)$, for all $v \in J$. Hence, $J \subseteq Z(R)$.

The next lemma can be regarded as a generalization of a lemma due to Smiley [8] for Jordan ideals of a prime ring.

Lemma 2.8. Let $R$ be a 2 -torsion-free prime ring and let $J$ be a Jordan ideal and a subring of $R$ such that $[u, v]^{2}=0$, for all $u, v \in J$. Then $J$ is commutative and hence central.

Proof. By hypothesis, we have $[u, v]^{2}=0$, for all $u, v \in J$. On linearizing, we get $[u, v][u, w]+[u, w][u, v]=0$, for all $u, v, w \in J$. Replacing $v$ by $v u$ in the above expression and using it, we obtain $[u, v][u,[u, w]]=0$, for all $u, v, w \in J$. Again, replac$\operatorname{ing} v$ by $v v_{1}$ in latter relation, we find that $[u, v] v_{1}[u,[u, w]]=0$, that is, $[u, v] J[u,[u$, $w]]=(0)$, for all $u, v, w \in J$. Thus by Lemma 2.6, we have for each $u \in J$ either $[u, v]=0$ or $[u,[u, w]]=0$, for all $u, v, w \in J$. If $[u,[u, w]]=0$, for all $u, w \in J$, then on replacing $w$ by $w v$, we get $[u, w][u, v]=0$, for all $u, v, w \in J$. Again, replacing $v$ by $v w$, we have $[u, w] v[u, w]=0$, for all $u, v, w \in J$ and hence $[u, w] J[u, w]=(0)$, for all $w \in J$. Again, by Lemma 2.6, we obtain $[u, w]=0$. Thus in both cases we find that $[u, w]=0$, for all $u, w \in J$. Thus, $J$ is commutative, and by Lemma $2.7, J$ is central, that is, $J \subseteq Z(R)$.

LemmA 2.9. Let $R$ be a 2 -torsion-free ring, $J$ a Jordan ideal and a subring of $R$. If $\delta: R \rightarrow R$ is an additive mapping satisfying $\delta\left(u^{2}\right)=2 \theta(u) \delta(u)$, for all $u \in U$, then
(i) $\delta\left(u^{2} v\right)=\theta\left(u^{2}\right) \delta(v)+(\theta(u) \theta(v)+\theta(v) \theta(u)) \delta(u)+\theta(u) \delta([u, v])$, for all $u, v \in J$,
(ii) $\delta\left(v u^{2}\right)=\theta\left(u^{2}\right) \delta(v)+(3 \theta(v) \theta(u)-\theta(u) \theta(v)) \delta(u)-\theta(u) \delta([u, v])$, for all $u, v \in J$.

Proof. (i) Replacing $v$ by $v u$ and $u v$ in Lemma 2.2(i), we find that

$$
\begin{array}{ll}
\delta\left(u v u+v u^{2}\right)=2(\theta(u) \delta(v u)+\theta(v) \theta(u) \delta(u)), & \forall u, v \in J, \\
\delta\left(u^{2} v+u v u\right)=2(\theta(u) \delta(u v)+\theta(u) \theta(v) \delta(u)), & \forall u, v \in J . \tag{2.3}
\end{array}
$$

Now, subtracting (2.2) from (2.3), we get

$$
\begin{equation*}
\delta\left(u^{2} v-v u^{2}\right)=2(\theta(u) \delta([u, v])+[\theta(u), \theta(v)] \delta(u)), \quad \forall u, v \in J \tag{2.4}
\end{equation*}
$$

Replacing $u$ by $u^{2}$ in Lemma 2.2(i), we have

$$
\begin{align*}
\delta\left(u^{2} v+v u^{2}\right) & =2 \theta\left(u^{2}\right) \delta(v)+2 \theta(v) u \delta\left(u^{2}\right) \\
& =2 \theta\left(u^{2}\right) \delta(v)+4 \theta(v) \theta(u) \delta(u), \quad \forall u, v \in J \tag{2.5}
\end{align*}
$$

Hence adding (2.4), (2.5) and using the fact that char $R \neq 2$, we obtain

$$
\begin{align*}
\delta\left(u^{2} v\right)= & \theta\left(u^{2}\right) \delta(v)+(\theta(u) \theta(v)+\theta(v) \theta(u)) \delta(u) \\
& +\theta(u) \delta([u, v]), \quad \forall u, v \in J . \tag{2.6}
\end{align*}
$$

(ii) As in the proof of the case (i), subtracting (2.4) from (2.5), we find that

$$
\begin{align*}
\delta\left(v u^{2}\right)= & \theta\left(u^{2}\right) \delta(v)+(3 \theta(v) \theta(u)-\theta(u) \theta(v)) \delta(u) \\
& -\theta(u) \delta([u, v]), \quad \forall u, v \in J . \tag{2.7}
\end{align*}
$$

3. Left derivation on Jordan ideal of a prime ring. In [3], there is a more general result which implies that in a 2 -torsion-free prime ring $R$, the existence of a nonzero Jordan left derivation on a Lie ideal $U$ of $R$ forces that either $U \subseteq Z(R)$ or $\delta(U)=(0)$. In the present section, we attempt to generalize the above-mentioned result for Jordan left $(\theta, \theta)$-derivation which acts on a Jordan ideal of the ring.

Theorem 3.1. Let $R$ be a 2-torsion-free prime ring and let $J$ be a Jordan ideal and a subring of $R$. If $\theta$ is an automorphism of $R$ and $\delta: R \rightarrow R$ is an additive mapping satisfying $\delta\left(u^{2}\right)=2 \theta(u) \delta(u)$, for all $u \in J$, then either $J \subseteq Z(R)$ or $\delta(J)=(0)$.

Proof. Suppose that $J \nsubseteq Z(R)$. By Lemma 2.2(iv), we have

$$
\begin{equation*}
[\theta(u), \theta(v)] \theta(u) \delta(u)=\theta(u)[\theta(u), \theta(v)] \delta(u), \quad \forall u, v \in J . \tag{3.1}
\end{equation*}
$$

This implies that

$$
\begin{equation*}
\left(\theta\left(u^{2}\right) \theta(v)-2 \theta(u) \theta(v) \theta(u)+\theta(v) \theta\left(u^{2}\right)\right) \delta(u)=0, \quad \forall u, v \in J \tag{3.2}
\end{equation*}
$$

Replacing $u$ by $[u, w]$ in (3.2), we get

$$
\begin{align*}
& \theta\left([u, w]^{2}\right) \theta(v) \delta([u, w])-2 \theta([u, w]) \theta(v) \theta([u, w]) \delta([u, w]) \\
& \quad+\theta(v) \theta\left([u, w]^{2}\right) \delta([u, w])=0 \tag{3.3}
\end{align*}
$$

for all $u, v, w \in J$. Now, application of Lemma 2.3(i) yields that $\theta\left([u, w]^{2}\right) \theta(v) \delta([u, w])$ $=(0)$, for all $u, v, w \in J$. Since $\theta$ is an automorphism of $R$, the latter expression gives $[u, w]^{2} J \theta^{-1}(\delta([u, w]))=(0)$. Hence, by Lemma 2.6, we find that for each pair $u, w \in J$, either $[u, w]^{2}=0$ or $\theta^{-1}(\delta([u, w]))=0$. Note that the mappings $(u, w) \mapsto[u, w]$ and $(u, w) \mapsto \theta^{-1}(\delta([u, w]))$ satisfy the requirements of Lemma 2.1. Hence, either $[u, w]^{2}=0$, for all $u, w \in J$, or $\theta^{-1}(\delta([u, w]))=0$, for all $u, w \in J$. If $[u, w]^{2}=0$, for all $u, w \in J$, then by application of Lemma 2.8, $J$ is commutative and hence central, that is, $J \subseteq Z(R)$, a contradiction. Now, we consider the case $\theta^{-1}(\delta([u, w]))=0$, then $\delta([u, w])=0$, that is, $\delta(u w)=\delta(w u)$, for all $u, w \in J$. In view of Lemma 2.2(i), we have

$$
\begin{align*}
2 \delta((w u) u) & =\delta((w u) u+u(w u)) \\
& =2 \theta(w) \theta(u) \delta(u)+2 \theta(u) \delta(w u+u w)  \tag{3.4}\\
& =2\left\{\theta\left(u^{2}\right) \delta(w)+\theta(u) \theta(w) \delta(u)+\theta(w) \theta(u) \delta(u)\right\}, \quad \forall u, w \in J .
\end{align*}
$$

Since $R$ is 2-torsion-free, we get $\delta((w u) u)=\theta\left(u^{2}\right) \delta(w)+\theta(u) \theta(w) \delta(u)+\theta(w) \theta(u) \delta(u)$, for all $u, w \in J$. By Lemma 2.9(ii), we obtain $[\theta(u), \theta(w)] \delta(u)=0$, for all $u, w \in J$. Replacing $w$ by $w v$ in the latter expression, we get $[\theta(u), \theta(w)] \theta(v) \delta(u)=0$, that is, $[u, w] J \theta^{-1}(\delta(u))=(0)$. Thus, by Lemma 2.6, we find that for each $u \in J$ either
$[u, w]=0$ or $\theta^{-1}(\delta(u))=0$. Since $\theta$ is an automorphism, we have either $[u, w]=0$ or $\delta(u)=0$, for all $w \in J$. Now let $J_{1}=\{u \in J \mid[u, w]=0$, for all $w \in J\}$ and $J_{2}=\{u \in J \mid \delta(u)=0\}$. Clearly, $J_{1}$ and $J_{2}$ are additive subgroups of $J$ whose union is $J$. Hence, by Brauer's trick, either $J=J_{1}$ or $J=J_{2}$. If $J=J_{1}$, then $[u, w]=0$, for all $u, w \in J$, that is, $J$ is commutative, and hence by Lemma $2.7, J \subseteq Z(R)$, again a contradiction. Hence, we have the remaining possibility that $\delta(u)=0$, for all $u \in J$, that is, $\delta(J)=(0)$. This completes the proof of the theorem.

Remark 3.2. In the hypotheses of the above theorem, if we assume only that $J$ is a subring of $R$, then neither $J$ is central nor $\delta(J)=(0)$. This is shown by the following example.

Example 3.3. Let $S$ be a ring such that the square of each element in $S$ is zero, but the product of some elements in $S$ is nonzero. Further, suppose that $R=\left\{\left.\left(\begin{array}{cc}x & y \\ 0 & 0\end{array}\right) \right\rvert\, x, y \in S\right\}$. Consider $J=\left\{\left.\left(\begin{array}{ll}0 & y \\ 0 & 0\end{array}\right) \right\rvert\, y \in S\right\}$, then $J$ is a subring of $R$. Define mappings $\delta: R \rightarrow R$ and $\theta: R \rightarrow R$ as follows:

$$
\delta\left(\begin{array}{cc}
x & y  \tag{3.5}\\
0 & 0
\end{array}\right)=\left(\begin{array}{ll}
0 & y \\
0 & 0
\end{array}\right), \quad \theta\left(\begin{array}{cc}
x & y \\
0 & 0
\end{array}\right)=\left(\begin{array}{cc}
x & -y \\
0 & 0
\end{array}\right)
$$

It is easy to verify that $\delta$ is a Jordan left $(\theta, \theta)$-derivation, but neither $J \subseteq Z(R)$ nor $\delta(J)=(0)$.

Corollary 3.4. Let $R$ be a 2 -torsion-free prime ring. If $\delta: R \rightarrow R$ is a nonzero additive mapping satisfying $\delta\left(x^{2}\right)=2 x \delta(x)$, for all $x \in R$, then $R$ is commutative.

The following example demonstrates that to have $R$ prime is essential in the hypothesis of the above result.

Example 3.5. Consider a ring $R$, as in Example 3.3, and define mappings $\delta: R \rightarrow R$ and $\theta: R \rightarrow R$ as follows:

$$
\delta\left(\begin{array}{cc}
x & y  \tag{3.6}\\
0 & 0
\end{array}\right)=\left(\begin{array}{cc}
0 & -x \\
0 & 0
\end{array}\right), \quad \theta\left(\begin{array}{cc}
x & y \\
0 & 0
\end{array}\right)=\left(\begin{array}{cc}
x & -y \\
0 & 0
\end{array}\right)
$$

Then, with $J=R$, it can be easily seen that $\delta\left(x^{2}\right)=2 \theta(x) \delta(x)$, for all $x \in R$, but $R$ is not commutative.
4. Left derivation as a homomorphism or as antihomomorphism. Let $S$ be a nonempty subset of a ring $R$ and $d$ a derivation of $R$. If $d(x y)=d(x) d(y)$ (resp., $d(x y)=d(y) d(x))$ holds for all $x, y \in S$, then we say that $d$ acts as a homomorphism (resp., antihomomorphism) on $S$.

In 1989, Bell and Kappe [4] proved that if $d$ is a derivation of a prime ring $R$ which acts as a homomorphism or as an antihomomorphism on a nonzero right ideal $I$ of $R$, then $d=0$ on $R$. Further, this result was extended for $(\theta, \phi)$-derivation in [2] as follows.

Theorem 4.1. Let $R$ be a prime ring, $I$ a nonzero right ideal of $R$, and let $\theta, \phi$ be automorphisms of $R$. Suppose that $\delta: R \rightarrow R$ is a $(\theta, \phi)$-derivation of $R$.
(i) If $\delta$ acts as a homomorphism on I, then $\delta=0$ on R.
(ii) If $\delta$ acts as an antihomomorphism on $I$, then $\delta=0$ on $R$.

In the present section, our objective is to extend the above result for left ( $\theta, \theta$ )-derivation of a prime ring $R$ which acts as a homomorphism or as an antihomomorphism on a Jordan ideal $J$ of $R$. In fact, we prove the following theorem.

Theorem 4.2. Let $R$ be a 2-torsion-free prime ring and $J$ a nonzero Jordan ideal and a subring of $R$. Suppose that $\theta$ is an automorphism of $R$ and $\delta: R \rightarrow R$ is a left $(\theta, \theta)$-derivation of $R$.
(i) If $\delta$ acts as a homomorphism on $J$, then $\delta=0$ on $R$.
(ii) If $\delta$ acts as an antihomomorphism on $J$, then $\delta=0$ on $R$.

Proof. (i) By our hypotheses, we have

$$
\begin{equation*}
\delta(u) \delta(v)=\delta(u v)=\theta(u) \delta(v)+\theta(v) \delta(u), \quad \forall u, v \in J . \tag{4.1}
\end{equation*}
$$

Replacing $u$ by $u v$ in (4.1), we find that

$$
\begin{equation*}
\delta(u v) \delta(v)=\theta(u v) \delta(v)+\theta(v) \delta(u v), \quad \forall u, v \in J . \tag{4.2}
\end{equation*}
$$

Now, application of (4.1) yields that $\theta(u) \delta(v) \delta(v)=\theta(u v) \delta(v)$, for all $u, v \in J$. This implies that

$$
\begin{equation*}
\theta(u)(\delta(v)-\theta(v)) \delta(v)=0, \quad \forall u, v \in J . \tag{4.3}
\end{equation*}
$$

Thus, $\theta(J)(\delta(v)-\theta(v)) \delta(v)=(0)$, for all $v \in J$. Since $\theta$ is an automorphism and $J$ is a nonzero Jordan ideal of $R, \theta(J)$ is also a nonzero Jordan ideal of $R$. Application of Lemma 2.6 yields that $(\delta(v)-\theta(v)) \delta(v)=0$, for all $v \in J$ and hence $\delta\left(v^{2}\right)=\theta(v) \delta(v)$, for all $v \in J$. Since $\delta$ is a left $(\theta, \theta)$-derivation, we have $\theta(v) \delta(v)=0$, for all $v \in J$. On linearizing the latter relation, we find that

$$
\begin{equation*}
\theta(v) \delta(u)+\theta(u) \delta(v)=0, \quad \forall u, v \in J . \tag{4.4}
\end{equation*}
$$

Again, replacing $u$ by $v u$ in (4.4), we get $\theta(v) \theta(u) \delta(v)=0$, for all $u, v \in J$, that is, $v J \theta^{-1}(\delta(v))=(0)$, for all $v \in J$. Application of Lemma 2.6 yields that either $v=0$ or $\theta^{-1}(\delta(v))=0$. But $v=0$ also gives that $\theta^{-1}(\delta(v))=0$, that is, $\delta(v)=0$, for all $v \in J$. Further, replace $v$ by $v \circ r$ to get $2 \theta(v) \delta(r)=0$, for all $v \in J$ and $r \in R$. Since $R$ is 2-torsion-free and $\theta(J)$ is a nonzero Jordan ideal of $R$, application of Lemma 2.6 yields the required result.
(ii) If $d$ acts as an antihomomorphism on $J$, then

$$
\begin{align*}
\delta(u) \delta(v) & =\delta(v u)=\theta(v) \delta(u)+\theta(u) \delta(v) \\
& =\theta(u) \delta(v)+\theta(v) \delta(u)=\delta(u v)=\delta(v) \delta(u), \tag{4.5}
\end{align*}
$$

and hence $\delta$ also acts as a homomorphism on $J$. Therefore, in view of (i) we get the required result.

REmARK 4.3. We feel that Theorem 3.1 (resp., Theorem 4.2) could be proved for Jordan left $(\theta, \phi)$-derivation (resp., left $(\theta, \phi)$-derivation) of a prime ring. However, we did not succeed to settle it.

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