

## ON THE EXISTENCE OF EQUATIONS OF EVOLUTION

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ABSTRACT. A time-independent, non-autonomous non-linear system governed by a principle of determinism (the state at a given time is determined by the initial state and by the control history during the intervening closed interval) is shown to obey a generalized evolution equation (1.2), where  $n$  is such that the state is continuously differentiable with respect to time whenever the control is of class  $C^n$ .

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### 1. INTRODUCTION.

The equations of evolution of time-independent, non-autonomous non-linear systems are almost universally taken as

$$u' = f(u, x) \tag{1.1}$$

where  $u$  is the output (or state) and  $x$  is the input (or control), both functions of time  $t$  with values in finite-dimensional vector spaces (say  $U$  and  $X$ , respectively), and the prime denotes differentiation with respect to time.

However, equation (1.1) is not the most general evolution equation. It may be regarded as a special case (corresponding to  $n=0$ ) of

$$u' = f(u, x, x', \dots, x^{(n)}). \tag{1.2}$$

An example of the need for an equation of the form (2) occurs in the mechanics of inelastic continua. Here  $u$  is the vector whose components are the internal variables (or the inelastic strain), while  $x$  is stress or strain. Viscoelastic and viscoplastic materials are described by equation (1.1). Plastic materials, on the other hand, require equation (1.2) with  $n=1$ . In particular, for a rate-independent material the function  $f$  must be first-degree homogeneous in  $x'$ .

The difference between systems described by equations (1.1) and (1.2) (or, more generally, by equations (1.2) with different values of  $n$ ) lies in the character of the solutions  $u(t)$ . If  $f$  is continuous, then the solution of (1.1) is continuously differentiable whenever  $x$  is a continuous function of time. On the other hand, solution

of (1.2) will not in general be continuously differentiable unless  $x$  is of class  $C^n$ . In other words, the choice of  $n$  in equation (1.2) depends on the way in which the system smooths the input: the greater the smoothing, the lower the value of  $n$ .

However, the existence of an equation of evolution cannot be assumed a priori for an arbitrary system. In this note we shall try to find sufficient conditions for the existence of an equation of evolution, and to relate the value of  $n$  to the smoothing property of the system.

2. MAIN RESULTS

We shall assume the system to be governed by a principle of determinism as follows: the value of  $u$  at time  $t + \tau$  is determined by its value at time  $t$  and by the history of  $x$  during the interval  $[t, t + \tau]$ . We shall express this mathematically as follows. Let  $x^t$  be defined by  $x^t(s) = x(t + s)$ , and let  $x^t_\tau$  denote the restriction of  $x^t$  to  $[0, \tau]$ . The pair  $(u(t), x^t_\tau)$  may be regarded as determining a process of duration  $\tau$  in the system; let  $P_\tau$  denote the set of all such pairs determining possible processes in the system. Then there exists a mapping  $\phi_\tau: P_\tau \rightarrow U$  such that

$$u(t + \tau) = \phi_\tau(u(t), x^t_\tau) \tag{2.1}$$

Furthermore, let  $C^n_\tau$  denote the Banach space  $C^n([0, \tau]; X)$ , let  $P^n_\tau = P_\tau \cap (U \times C^n_\tau)$ . Then the smoothing property of the system may be expressed by saying that the left-hand side of (2.1) is differentiable with respect to  $\tau$  whenever  $(u(t), x^t_\tau) \in P^n_\tau$ , that is, that the limit

$$\lim_{\tau \rightarrow 0+} \frac{1}{\tau} [\phi_\tau(u(t), x^t_\tau) - u(t)] \tag{2.2}$$

exists and is continuous in  $t$  under that condition. It is clear that this limit is determined by  $u(t)$  and by the behavior of  $x$  in a neighborhood of  $t$ . It is not immediately clear that it should take the form of the right-hand side of (1.2). In fact, in order to derive this result we need to assume some properties of the restriction to  $P^n_\tau$  of the mapping  $\phi_\tau$ , as given in the following theorem.

**THEOREM.** Let  $\phi_\tau: P^n_\tau \rightarrow U$  be such that  $\phi_\tau(a, \cdot)$  is locally Lipschitz (with respect to the  $C^n_\tau$  norm), the local Lipschitz norm  $F_\tau$  being  $O(\tau)$  as  $\tau \rightarrow 0+$ . Then the limit

$$\lim_{\tau \rightarrow 0+} \frac{1}{\tau} [\phi_\tau(a, y) - a],$$

when it exists, depends only on  $a, y, y', \dots, y^{(n)}$ .

**PROOF.** Define  $\bar{y} \in C^n_\tau$  by

$$\bar{y}(s) = y(0) + y'(0)s + \dots + y^{(n)}(0) \frac{s^n}{n!}$$

Let  $\|\cdot\|_\tau$  denote the  $C^n_\tau$  norm and  $|\cdot|$  any finite-dimensional norm. Then

$$\begin{aligned} \|y - \bar{y}\|_\tau = \max\{ & \sup_{s \in [0, \tau]} |y(s) - y(0) - \dots - y^{(n)}(0) \frac{s^n}{n!}|, \\ & \sup_{s \in [0, \tau]} |y'(s) - y'(0) - \dots - y^{(n)}(0) \frac{s^{n-1}}{(n-1)!}|, \dots, \sup_{s \in [0, \tau]} |y^{(n)}(s) - y^{(n)}(0)| \}. \end{aligned}$$

Since the argument of each  $|\cdot|$  is a continuous function of  $s$  that vanishes at 0, each supremum goes to zero as  $\tau \rightarrow 0$ , so that  $\|y - \bar{y}\|_\tau \rightarrow 0$  as  $\tau \rightarrow 0$ . Now

$$\frac{1}{\tau} [\phi_\tau(a, y) - a] = \frac{1}{\tau} [\phi_\tau(a, y) - \phi_\tau(a, \bar{y})] + \frac{1}{\tau} [\phi_\tau(a, \bar{y}) - a];$$

but for the first term on the right-hand side we have

$$\frac{1}{\tau} \left| \phi_\tau(a, y) - \phi_\tau(a, \bar{y}) \right| \leq \frac{F_\tau}{\tau} \|y - \bar{y}\|_\tau,$$

so that this term goes to zero as  $\tau \rightarrow 0$ . Consequently,

$$\lim_{\tau \rightarrow 0^+} \frac{1}{\tau} [\phi_\tau(a, y) - a] = \lim_{\tau \rightarrow 0^+} \frac{1}{\tau} [\phi_\tau(a, \bar{y}) - a],$$

and this last limit, whenever it exists, depends only on  $a$  and on the parameters defining  $\bar{y}$ , that is,  $y(0), y'(0), \dots, y^{(n)}(0)$ . Q.E.D.

By the assumed smoothing property of the system the limit exists and is a continuous function of its arguments,  $f(a, y(0), y'(0), \dots, y^{(n)}(0))$ ; it is this  $f$  that furnishes the right-hand side of equation (2).

As a very simple example, consider  $\phi_\tau$  given by

$$\phi_\tau(a, y) = a + y(\tau) - y(0).$$

This  $\phi_\tau(a, \cdot)$  is Lipschitz (since it is a continuous linear mapping) on  $C_\tau^0$ , but the Lipschitz norm over this space is 2. On the other hand, we may rewrite it as

$$\phi_\tau(a, y) = a + \int_0^\tau y'(s) ds,$$

so that it is clearly a continuous linear mapping of  $C_\tau^1$ , and its (Lipschitz) norm is  $\tau$ . Consequently,  $n=1$ , and indeed we have  $f(a, y, y') = y'$ .

A more sophisticated example, relevant to plasticity theory, is

$$\phi_\tau(a, y) = a + \int_0^\tau |y'(s)| ds.$$

This  $\phi_\tau(a, \cdot)$  is not Lipschitz on  $C_\tau^0$  but it is Lipschitz on  $C_\tau^1$ :

$$|\phi_\tau(a, y) - \phi_\tau(a, \bar{y})| = \left| \int_0^\tau (|y'(s)| - |\bar{y}'(s)|) ds \right| \leq \int_0^\tau \left| |y'(s)| - |\bar{y}'(s)| \right| ds$$

$$\leq \tau \sup_{s \in [0, \tau]} \left| |y'(s)| - |\bar{y}'(s)| \right| \leq \tau \sup_{s \in [0, \tau]} |y'(s) - \bar{y}'(s)| \leq \tau \|y - \bar{y}\|_\tau,$$

so that once again  $F_\tau = \tau$ .