Research Article

Periodicity in a Class of Systems of Delay Difference Equations

Zhijian Wei

College of Mathematics and Econometrics, Hunan University, Changsha, Hunan 410082, China

Correspondence should be addressed to Zhijian Wei, zhijwei@yahoo.com

Received 5 July 2011; Accepted 23 August 2011

Academic Editor: J. Biazar

Copyright © 2011 Zhijian Wei. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

We study a system of delay difference equations modeling four-dimensional discrete-time delayed neural networks with no internal decay. Such a discrete-time system can be regarded as the discrete analog of a differential equation with piecewise constant argument. By using semicycle analysis method, it is shown that every bounded solution of this discrete-time system is eventually periodic. The obtained results are new, and they complement previously known results.

1. Introduction

Over the past decades, there has been increasing interest in the potential applications of the dynamics of artificial neural networks in signal and image processing. Among the most popular models in the literature of artificial neural networks is the following well-known Hopfield's model [1, 2]:

$$\frac{\mathrm{d}u_i(t)}{\mathrm{d}t} = \mu_i u_i(t) + \sum_{j \neq i} T_{ij} f_j \left(u_j \left(t - \tau_{ij} \right) \right), \qquad 1 \le i \le n, \tag{1.1}$$

where $\mu_i \ge 0$ is the internal decay rate, $\tau_{ij} \ge 0$ is the delay incorporated by Marcus and Westervelt [3] to account for the finite switching speed of amplifiers (neurons), $f_j : \mathbf{R} \to \mathbf{R}$ (the set of all real numbers) is the signal functions, and T_{ij} represents the connection strengths between neurons and if the output from neuron *j* excites (resp., inhibits) neuron *i*, then $T_{ij} > 0$ (resp., < 0), $1 \le i, j \le n$.

Much work on Hopfield-type neural networks with constant time delays has been carried out. However, from the point of view of electronic implementation of neural networks

and control, the time-varying delay case is more suitable for practical neural networks, and we can achieve this by using piecewise constant arguments. Because of the wide application of differential equations with piecewise constant argument in certain biomedical models (see, e.g., [4]), much progress has been made in the study of differential equations with piecewise constant arguments since the pioneering work of Cooke and Wiener [5] and Shah and Wiener [6]. For more details and references on this subject, interested readers may refer to a survey of Cooke and Wiener [7]. Motivated by these discussions, we propose

$$\frac{du_i(t)}{dt} = \mu_i u_i(t) + \sum_{j \neq i} T_{ij} f_j (u_j ([t - \tau_{ij}])), \quad 1 \le i \le n,$$
(1.2)

as a new neural network model, where $[\cdot]$ denotes the greatest integer function and f_j ($1 \le j \le n$) are the McCulloch-Pitts nonlinear function given by

$$f(u) = \begin{cases} 1 & \text{if } u > \sigma, \\ -1 & \text{if } u \le \sigma. \end{cases}$$
(1.3)

Here, $\sigma \in R$ is referred as the threshold. The McCulloch-Pitts nonlinearity reflects the fact that the signal transmission is of digital nature: a neuron is either fully active or completely inactive.

Neural networks are complex and large-scale nonlinear dynamical systems, while the dynamics of the delayed neural networks is even richer and more complicated [8]. In order to obtain a deep and clear understanding of the dynamics of neural networks, the dynamics of delayed neural networks consisting of a few neurons has received increasing attention over the past years [9–14]. The studies on these neural networks of a few neurons are potentially useful because the complexities found in such models often provide promising information for the studies on more complicated neural networks with a large number of neurons [15]. So, we are inspired to consider a special case of (1.2),

$$\begin{aligned} x_1'(t) &= f(x_2([t-k])), \\ x_2'(t) &= f(x_3([t-k])), \\ x_3'(t) &= -f(x_4([t-k])), \\ x_4'(t) &= -f(x_1([t-k])), \end{aligned}$$
(1.4)

where f is the activation function with McCulloch-Pitts nonlinearity (1.3), k is a nonnegative integer and the negative (resp., positive) sign on the right indicates negative (resp., positive) feedback. (1.4) describes the dynamics of four interacting neurons with no internal decays.

To study (1.4), it is convenient to consider the following difference system:

$$x_{1}(n+1) = x_{1}(n) + f(x_{2}(n-k)),$$

$$x_{2}(n+1) = x_{2}(n) + f(x_{3}(n-k)),$$

$$x_{3}(n+1) = x_{3}(n) - f(x_{4}(n-k)),$$

$$x_{4}(n+1) = x_{4}(n) - f(x_{1}(n-k)),$$

(1.5)

where *k* is a nonnegative integer and *f* satisfies (1.3). In fact, integrate (1.4) from *n* to $t \in [n, n + 1)$ to get

$$x_{1}(t) = x_{1}(n) + \int_{n}^{t} f(x_{2}([s-k]))ds = x_{1}(n) + f(x_{2}(n-k))(t-n),$$

$$x_{2}(t) = x_{2}(n) + \int_{n}^{t} f(x_{3}([s-k]))ds = x_{2}(n) + f(x_{3}(n-k))(t-n),$$

$$x_{3}(t) = x_{3}(n) - \int_{n}^{t} f(x_{4}([s-k]]))ds = x_{3}(n) - f(x_{4}(n-k))(t-n),$$

$$x_{4}(t) = x_{4}(n) - \int_{n}^{t} f(x_{1}([s-k]]))ds = x_{4}(n) - f(x_{1}(n-k))(t-n).$$
(1.6)

Letting $t \rightarrow n+1$, we get a special case of (1.5) with k = 0. Hence, system (1.5) can be regarded as a more general neural network model of four neurons with transmission delay.

Our study is inspired by the work of Chen [16–18], who considered

$$x(n+1) = x(n) - f(x(n-k)),$$

$$x(n+1) = x(n) + f(x(n-k)),$$

$$x(n+1) = x(n) + f(y(n-k)),$$

$$y(n+1) = y(n) - f(x(n-k)),$$

(1.7)

where $f : \mathbf{R} \to \mathbf{R}$ is given by (1.3).

The main objective of this paper is to study (1.5) with f satisfying (1.3). The discontinuity of f makes it difficult to apply directly the theory of discrete dynamical systems to system (1.5). However, by using semicycle analysis method, we obtain some interesting results for the periodicity of (1.5). It is shown that every bounded solution of system (1.5) is eventually periodic.

The rest of the paper is organized as follows. In Section 2, we introduce some necessary notations and lemmas that will be used later. In Section 3, we state and prove our main result.

2. Notations and Preliminaries

For the sake of simplicity, we introduce some notations. Let *Z* denote the set of all integers. For $a, b \in Z$, define $Z(a) = \{a, a + 1, ...\}$ and $Z(a, b) = \{a, a + 1, ..., b\}$ whenever $a \le b$.

By a solution of (1.5), we mean a sequence $\{(x_1(n), x_2(n), x_3(n), x_4(n))\}_{n=-k}^{+\infty}$ that satisfies (1.5). Clearly, for given $(\overline{x}_1(-k), \overline{x}_2(-k), \overline{x}_3(-k), \overline{x}_4(-k)), (\overline{x}_1(-k+1), \overline{x}_2(-k+1), \overline{x}_3(-k+1), \overline{x}_4(-k+1)), \dots, (\overline{x}_1(0), \overline{x}_2(0), \overline{x}_3(0), \overline{x}_4(0)) \in \mathbb{R}^4$, system (1.5) has a unique solution $\{(x_1(n), x_2(n), x_3(n), x_4(n))\}_{n=-k}^{+\infty}$ satisfying the initial condition:

$$(x_1(i), x_2(i), x_3(i), x_4(i)) = (\overline{x}_1(i), \overline{x}_2(i), \overline{x}_3(i), \overline{x}_4(i)) \quad \text{for } i \in Z(-k, 0).$$
(2.1)

If all terms of the sequence $\{v_n\}_{n=-k}^{+\infty}$ are integers, we say that it is an integer sequence. If $\{x_i(n)\}_{n=-k}^{\infty}$ for all $i \in Z(1,4)$ are integer sequences and also satisfy (1.5) and (1.3), then $\{(x_1(n), x_2(n), x_3(n), x_4(n))\}_{n=-k}^{+\infty}$ is said to be an integer sequence solution of (1.5) and (1.3). Let $\{(x_1(n), x_2(n), x_3(n), x_4(n))\}_{n=-k}^{+\infty}$ be a solution of (1.5). Define

$$\tau(x) = \begin{cases} x - [x] & \text{for } x \neq 0, \\ 1 & \text{for } x = 0. \end{cases}$$
(2.2)

Clearly, $\tau(x) \ge 0$. From (1.5) and (1.3), we have $\tau(x_i(n) - \sigma) = \tau(x_i(0) - \sigma)$, $i \in Z(1, 4)$. Denote $\tilde{x}_i(n) = x_i(n) - \sigma - \tau(x_i(0) - \sigma) + 1$, $i \in Z(1, 4)$. Then $\tilde{x}_i(n) \in Z$ for all $n \in Z(-k)$, $i \in Z(1, 4)$. Moreover, if $x_i(n) > \sigma$, then $\tilde{x}_i(n) = x_i(n) - \sigma - \tau(x_i(0) - \sigma) + 1 \ge x_i(n) - \sigma > 0$, and if $x_i(n) \le \sigma$, then $\tilde{x}_i(n) = x_i(n) - \sigma - \tau(x_i(0) - \sigma) + 1 \le -1 + 1 = 0$, $i \in Z(1, 4)$. Hence, $\{(\tilde{x}_1(n), \ldots, \tilde{x}_4(n))\}_{n=-k}^{+\infty}$ is an integer sequence solution of (1.5) and (1.3) with $\sigma = 0$.

So, without loss of generality, in the paper we always assume that $\sigma = 0$, and a solution of (1.5) means an integer sequence solution.

A solution $\{(x_1(n), x_2(n), x_3(n), x_4(n))\}_{n=-k}^{+\infty}$ is said to be eventually periodic if there exist $n_0 \in \{-k, -k+1, -k+2, ...\}$ and $\omega \in \{1, 2, 3, ...\}$ such that

$$(x_1(n+n_0+\omega), x_2(n+n_0+\omega), \dots, x_4(n+n_0+\omega)) = (x_1(n+n_0), x_2(n+n_0), \dots, x_4(n+n_0)),$$
(2.3)

for n = 0, 1, 2, ..., and ω is called a period. The smallest such ω is called the minimal period of $\{(x_1(n), x_2(n), x_3(n), x_4(n))\}_{n=-k}^{+\infty}$.

Definition 2.1. For a sequence $\{u_n\}_{n=-k}^{+\infty}$, we say that $\{u_{n_1}, u_{n_1+1}, \ldots, u_{n_1+l-1}\}$ with $l \ge 1$ is a positive semicycle with the length l if $u_n > 0$ for $n \in Z(n_1, n_1 + l - 1)$, and n_1 and l satisfy

either
$$n_1 = -k$$
 or $u_{n_1-1} \le 0$,
either $l = +\infty$ or $u_{n_1+l} \le 0$. (2.4)

We call *l* the length of the positive semicycle. A negative semicycle is defined similarly (replace > by \leq and vice versa).

To simplify the following arguments, for an integer sequence, we denote A_r^+ the positive semicycle $\{v_{n_1}, \ldots, v_{n_1+2r}\}$ with $v_{n_1+r\pm m} = r-m+1$ for $m \in Z(0, r)$ and A_r^- the negative semicycle $\{v_{n_1}, \ldots, v_{n_1+2r}\}$ with $v_{n_1+r\pm m} = m-r$ for $m \in Z(0, r)$.

Journal of Applied Mathematics

Definition 2.2. An integer sequence $\{v_n\}_{n=n_1}^{n_1+L-1}$ (may be infinite terms) is said to be an *r*-normal cycle if it possesses one of the representations as follows: $\{A_r^+, A_r^-, \dots, A_r^+, A_r^-\}$, $\{A_r^+, A_r^-, \dots, A_r^-, A_r^+\}$, $\{A_r^-, A_r^-, A_r^+\}$, $\{A_r^-, A_r^-, A_r^+\}$, and $\{A_r^-, A_r^+, \dots, A_r^-, A_r^-\}$. In addition, if $L = +\infty$, then it is said to be a total *r*-normal cycle.

Remark 2.3. For a *r*-normal cycle $\{v_n\}_{n=n_1}^{n_1+L-1}$, from Definition 2.2, it is easy to see that there must exist $i \in Z(0)$ such that L = (2r + 1)i. If $L = +\infty$, that is, $\{v_n\}_{n=n_1}^{n_1+L-1}$ is a total *r*-normal cycle, then $i = +\infty$.

Throughout this section, we tacitly assume that $(S) = \{(x_1(n), x_2(n), x_3(n), x_4(n))\}_{n=-k}^{+\infty}$ is a periodic solution of system (1.5) satisfying the initial values:

$$(x_1(i), x_2(i), x_3(i), x_4(i)) \in \mathbb{Z}^4$$
 for $i \in \mathbb{Z}(-k, 0)$. (2.5)

In view of (1.5) and (1.3), it is easy to see that all terms $x_1(n)$, $x_2(n)$, $x_3(n)$, and $x_4(n)$ of (*S*) are integers, that is, (*S*) is an integer sequence solution of (1.5).

For a periodic solution (S) of (1.5), denote

$$P_{x_i}^+ = \sup\{x_i(n) : n \in Z(-k)\} - 1, P_{x_i}^- = -\inf\{x_i(n) : n \in Z(-k)\},$$
(2.6)

and let $L_{x_i}^+$ and $L_{x_i}^-$ be the length of the longest positive semicycle of $\{x_i(n)\}_{n=-k}^{+\infty}$ and the length of the longest negative semicycle of $\{x_i(n)\}_{n=-k}^{+\infty}$, respectively, where i = 1, 2, ..., 4. Note that $L_{x_i}^+, L_{x_i}^- \in Z(1)$ for i = 1, 2, ..., 4.

The following several lemmas will be useful to the proof of the main result in this paper.

Lemma 2.4.

(a) Either $L_{x_i}^+ > L_{x_j}^+$ or $L_{x_i}^- > L_{x_j}^+$ or $\min\{L_{x_i}^+, L_{x_i}^-\} \ge L_{x_j}^+$ for i, j = 1, 2, ..., 4 and $i \neq j$. (b) Either $L_{x_i}^+ > L_{x_j}^-$ or $L_{x_i}^- > L_{x_j}^-$ or $\min\{L_{x_i}^+, L_{x_i}^-\} \ge L_{x_j}^-$ for i, j = 1, 2, ..., 4 and $i \neq j$.

Proof. We only prove the conclusion: either $L_{x_1}^+ > L_{x_2}^+$ or $L_{x_1}^- > L_{x_2}^+$ or min $\{L_{x_1}^+, L_{x_1}^-\} \ge L_{x_2}^+$. The other conclusions can be proved similarly. Now, we distinguish two cases to finish the proof.

Case 1. $L_{x_2}^+ = 2r$ for some r > 0. Without loss of generality, we assume that $x_2(0) \le 0$, $x_2(1) > 0$, $x_2(2) > 0$, ..., $x_2(2r) > 0$, $x_2(2r + 1) \le 0$, Then, from (1.5) and (1.3), we have

$$x_1(2r+k+1) = x_1(r+k+1) + \sum_{i=r+1}^{2r} f(x_2(i)) = x_1(r+k+1) + r,$$
(2.7)

$$x_1(r+k+1) = x_1(k+1) + \sum_{i=1}^r f(x_2(i)) = x_1(k+1) + r.$$
 (2.8)

- (i) If $x_1(r+k+1) \ge 1$, it follows from (2.7) that $x_1(2r+k+1) \ge r+1$. Since the distance between consecutive elements of $\{x_1(n)\}_{n=0}^{\infty}$ is 1, we have $L_{x_1}^+ \ge 2r+1 > L_{x_2}^+$.
- (ii) If $x_1(r+k+1) \le 0$, it follows from (2.8) that $x_1(k+1) \le -r$. Thus, $L_{x_1}^- \ge 2r+1 > L_{x_2}^+$.

Case 2. $L_{x_2}^+ = 2r+1$ for some r > 0. Without loss of generality, we assume that $x_2(0) \le 0, x_2(1) > 0, x_2(2) > 0, \dots, x_2(2r+1) > 0$, and $x_2(2r+2) \le 0, \dots$ Then, from (1.5) and (1.3), we have

$$x_1(k+2r+2) = x_1(r+k+1) + \sum_{i=1+r}^{2r+1} f(x_2(i)) = x_1(r+k+1) + (r+1),$$
(2.9)

$$x_1(r+k+1) = x_1(k+1) + \sum_{i=1}^r f(x_2(i)) = x_1(k+1) + r.$$
 (2.10)

- (i) If $x_1(r+k+1) > 0$, it follows from (2.9) that $x_1(k+2r+2) > r+1$. Thus, $L_{x_1}^+ > 2r+1 = L_{x_2}^+$.
- (ii) If $x_1(r+k+1) < 0$, it follows from (2.10) that $x_1(k+1) < -r$. Thus, $L_{x_1}^- > 2r+1 = L_{x_2}^+$.
- (iii) If $x_1(r + k + 1) = 0$, it follows from (2.9) and (2.10) that $x_1(k + 2r + 2) = r + 1$ and $x_1(k + 1) = -r$. Thus, $\min\{L_{x_1}^+, L_{x_1}^-\} \ge 2r + 1 = L_{x_2}^+$.

Therefore, we have either $L_{x_1}^+ > L_{x_2}^+$ or $L_{x_1}^- > L_{x_2}^+$ or min $\{L_{x_1}^+, L_{x_1}^-\} \ge L_{x_2}^+$. This completes the proof.

Lemma 2.5.
$$L_{x_i}^+ = L_{x_i}^-$$
 for $i, j = 1, ..., 4$. Moreover, $L_{x_1}^+$ is odd.

Proof. The lemma follows immediately from Lemma 2.4 together with its proof.

Lemma 2.6. $P_{x_i}^+ = P_{x_i}^-$ for i, j = 1, ..., 4.

Proof. First, we claim that $P_{x_2}^+ \leq P_{x_1}^+$. Otherwise, $P_{x_2}^+ > P_{x_1}^+$. Since the distance between consecutive elements of $\{x_2(n)\}_{n=0}^{\infty}$ is 1, it follows easily from the definitions of $P_{x_2}^+$ and $L_{x_2}^+$ that $L_{x_2}^+ \geq 2P_{x_2}^+ + 1$. By Lemma 2.5, there exists $r \geq 0$ such that $L_{x_2}^+ = 2r + 1 \geq 2P_{x_2}^+ + 1$, which implies that $r \geq P_{x_2}^+$. Without loss of generality, we assume that $x_2(0) \leq 0$, $x_2(1) > 0$, $x_2(2) > 0, \ldots, x_2(2r+1) > 0$, and $x_2(2r+2) \leq 0, \ldots$. Note that $r \geq P_{x_2}^+$ and $P_{x_2}^+ > P_{x_1}^+$. It follows from (2.9) and the definition of $P_{x_1}^+$ that

$$x_{1}(k+1+r) = x_{1}(k+2r+2) - (r+1)$$

$$\leq x_{1}(k+2r+2) - P_{x_{2}}^{+} - 1$$

$$< x_{1}(k+2r+2) - P_{x_{1}}^{+} - 1$$

$$\leq 0.$$
(2.11)

Thus, $x_1(k + 1 + r) \leq -1$, which, together with (2.10), implies that

$$x_1(k+1) = x_1(k+1+r) - r \le -(r+1).$$
(2.12)

It follows that $P_{x_1}^- \ge r + 1$ and hence, $L_{x_1}^- \ge 2r + 3 > L_{x_2}^+$, a contradiction to Lemma 2.5. This proves the claim. Repeating the same argument as that in the proof of the above claim, we have $P_{x_i}^+ \le P_{x_j}^+$, $P_{x_i}^- \le P_{x_j}^-$, and $P_{x_i}^+ \le P_{x_j}^-$ for i, j = 1, ..., 4 and $i \ne j$. Thus, we get $P_{x_i}^+ = P_{x_j}^-$ for i, j = 1, ..., 4. This completes the proof.

Journal of Applied Mathematics

Lemma 2.7. $L_{x_1}^+ = 2P_{x_1}^+ + 1$.

Proof. It follows from the definitions of $P_{x_1}^+$ and $L_{x_1}^+$ that $L_{x_1}^+ \ge 2P_{x_1}^+ + 1$. We show $L_{x_1}^+ = 2P_{x_1}^+ + 1$ by way of contradiction. Assume that $L_{x_1}^+ > 2P_{x_1}^+ + 1$. By Lemma 2.5, there exists $r \ge 0$ such that $L_{x_1}^+ = 2r + 1 \ge 2P_{x_1}^+ + 1$, which implies that $r \ge P_{x_1}^+$. Without loss of generality, we assume that $x_1(0) \le 0$, $x_1(1) > 0$, $x_1(2) > 0$, ..., $x_1(2r + 1) > 0$, and $x_1(2r + 2) \le 0$, Now, we distinguish two cases to finish the proof.

Case 1. $x_4(r + k + 1) \ge 1$. For this case, from (1.5) and (1.3), we have

$$x_{4}(k+1) = x_{4}(k+r+1) + \sum_{i=1}^{r} f(x_{1}(i))$$

$$\geq 1+r$$

$$> 1+P_{x_{1}}^{+},$$
(2.13)

which implies that $P_{x_4}^+ > P_{x_1}^+$, a contradiction to Lemma 2.6.

Case 2. $x_4(r + k + 1) \le 0$. For this case, from (1.5) and (1.3), we have

$$x_4(k+2r+2) = x_4(r+k+1) - \sum_{i=1+r}^{2r+1} f(x_1(i))$$

$$\leq -(1+r),$$
(2.14)

which implies that $P_{x_4}^- \ge 1 + r > P_{x_1}^+$, a contradiction to Lemma 2.6. This completes the proof.

Throughout the remaining part of this paper, we denote $P_{x_1}^+ = p$.

Lemma 2.8.

(a) x₁(n₁) = p+1 for some n₁ ∈ Z(-k). Moreover, x₄(n₁+k) = 1 and x₄(n₁+k+p+1) = -p.
(b) x₄(n₂) = p+1 for some n₂ ∈ Z(-k). Moreover, x₃(n₂+k) = 1 and x₃(n₂+k+p+1) = -p.
(c) x₂(n₃) = p+1 for some n₃ ∈ Z(-k). Moreover, x₁(n₃+k) = 0 and x₁(n₃+k+p+1) = p+1.
(d) x₃(n₄) = p+1 for some n₄ ∈ Z(-k). Moreover, x₂(n₄+k) = 0 and x₂(n₄+k+p+1) = p+1.

Proof. We only give the proof of the conclusion (c). The other conclusions can be proved similarly. By the definition of $P_{x_2}^+$, there must exist $n_3 \in Z(-k)$ such that $x_2(n_3) = P_{x_2}^+ + 1 = p+1$. Since the distance between consecutive elements of $\{x_2(n)\}_{n=0}^{\infty}$ is 1, it follows that $x_2(n_3 \pm j) > 0$ for all $j \in Z(1, p)$. We claim that $x_1(n_3 + k) = 0$. Otherwise, $x_1(n_3 + k) \leq -1$ or $x_1(n_3 + k) \geq 1$. If $x_1(n_3 + k) \geq 1$, it follows from (1.5) and (1.3) that

$$x_1(n_3 + k + p + 1) = x_1(n_3 + k) + \sum_{j=n_3}^{n_3+p} f(x_2(j)) = x_1(n_3 + k) + (p+1).$$
(2.15)

Thus, $x_1(n_3 + k + p + 1) \ge p + 2$, which implies that $P_{x_1}^+ \ge p + 2 > P_{x_2}^+$, a contradiction to Lemma 2.6. If $x_1(n_3 + k) \le -1$, it follows from (1.5) and (1.3) that

$$x_1(n_3+k) = x_1(n_3+k-p) + \sum_{j=n_3-p}^{n_3-1} f(x_2(j)) = x_1(n_3+k-p) + p.$$
(2.16)

Thus, $x_1(n_3+k-p) = x_1(n_3+k)-p \le -1-p$, which implies that $P_{x_1}^- \ge p+1 > P_{x_2}^+$, a contradiction to Lemma 2.6. This proves the claim. By (1.5) and (1.3), we must have

$$x_1(n_3 + k + p + 1) = x_1(n_3 + k) + \sum_{j=n_3}^{n_3+p} f(x_2(j)) = p + 1.$$
(2.17)

This completes the proof.

Arguing as in the proof of Lemma 2.8, we can get the following result.

Lemma 2.9.

Lemma 2.10. $p \le 2k$.

Proof. Without loss of generality, we assume that $x_1(0) = 0$, $x_1(1) = 1, ..., x_1(p) = p$, $x_1(p + 1) = p + 1$, $x_1(p + 2) = p$, ..., $x_1(2p) = 2$, $x_1(2p + 1) = 1$, and $x_1(2p + 2) = 0$. It follows from Lemma 2.8 that $x_4(p + k + 1) = 1$. By (1.5) and (1.3), we have

$$x_4(p+k+1) = x_4(k+1) - \sum_{i=1}^p f(x_1(i)).$$
(2.18)

Thus, $x_4(k + 1) = p + 1$. It follows from Lemma 2.8 that $x_3(p + 2k + 2) = -p$, and hence, by Lemma 2.9, we have $x_2(p + 3k + 2) = 1$. From (1.5) and (1.3), we get

$$x_2(p+3k+2) = x_2(3k+2) + \sum_{i=2k+2}^{p+2k+1} f(x_3(i)) = x_2(3k+2) - p.$$
(2.19)

Thus, $x_2(3k+2) = p+1$. Therefore, by Lemma 2.8, we have $x_1(4k+2) = 0$. Since $x_1(2p+2) = 0$, it follows that $4k+2 \ge 2p+2$, and hence $2k \ge p$. This completes the proof.

We hereafter use M_{x_i} to denote the length of the longest normal cycle of $\{x_i(n)\}_{n=-k}^{+\infty}$, where i = 1, ..., 4.

Journal of Applied Mathematics

Lemma 2.11. $M_{x_i} = +\infty, i = 1, ..., 4.$

Proof. We show that $M_{x_i} = +\infty$ for $i \in Z(1,4)$ by way of contradiction. Without loss of generality, we assume that $M_{x_1} < +\infty$. We will distinguish several cases to finish the proof.

Case 1. $M_{x_i} = +\infty$, i = 2, 3, 4. Without loss of generality, we assume that $\{x_2(i)\}_{n=1}^{+\infty}$ is a total *p*-normal cycle and $x_2(1) = 1$. Then, $x_2(2i(2p + 1) + p + 1) = p + 1$ for $i \in Z(0)$, and $x_2(2i(2p + 1) + 3p + 2) = -p$ for $i \in Z(0)$. By Lemmas 2.8 and 2.9, we have

$$x_1(2i(2p+1)+(p+1)+(k+p+1)) = p+1, \qquad x_1(2i(2p+1)+(3p+2)+(k+p+1)) = -p,$$
(2.20)

for $i \in Z(0)$. Therefore, $\{x_1(n)\}_{n=p+k+2}^{+\infty}$ is a total *p*-normal cycle, which is a contradiction to $M_{x_1} < +\infty$.

Case 2. $M_{x_i} < +\infty$, i = 2, 3, 4. Without loss of generality, we assume that $M_{x_2} \ge \max\{M_{x_1}, M_{x_3}, M_{x_4}\}$. Then, by the definition of M_{x_2} , there exists $L \ge 1$ such that $M_{x_2} = (2p + 1)L$ is the length of the longest normal cycle of $\{x_2(n)\}_{n=-k}^{+\infty}$. Without loss of generality, we assume that $\{x_2(n)\}_{n=1}^{M_{x_2}}$ is a *p*-normal cycle and $x_{M_{x_2}-p} = p + 1, x_{M_{x_2}-p+1} = p, \ldots, x_{M_{x_2}-1} = 2, x_{M_{x_2}} = 1$. To finish the proof of Case 2, we will distinguish two subcases.

Subcase 1. $x_2(1) = 1$. Then there exists $q \ge 0$ such that L = 2q + 1. Thus,

$$x_2(2i(2p+1) + p + 1) = p + 1 \quad \text{for } i \in Z(0,q),$$

$$x_2(2i(2p+1) + 3p + 2) = -p \quad \text{for } i \in Z(0,q-1).$$
(2.21)

By Lemmas 2.8 and 2.9, we have $x_1(2i(2p+1) + (p+1) + (k+p+1)) = p+1$ for $i \in Z(0,q)$ and $x_1(2i(2p+1) + (3p+2) + (k+p+1)) = -p$ for $i \in Z(0,q-1)$. It follows from $x_2(p+1) = p+1$ that $x_1(p+k+1) = 0$. This, combined with

$$x_1(p+k+1) = x_1(k+1) + \sum_{i=1}^p f(x_2(i)) = x_1(k+1) + p,$$
(2.22)

gives $x_1(k + 1) = -p$. By Lemma 2.10, we have $k - p + 1 \ge k - 2k + 1 > -k$. Therefore, the total number of p + 1 and -p contained in $\{x_1(i)\}_{i=k+1-p}^{(2q+1)(2p+1)+k+1+p}$ is 2q + 2. Since

$$(2q+1)(2p+1) + k + 1 + p - (k - p + 1) + 1 = (2q+1)(2p+1) + 2p + 1,$$
(2.23)

it follows that $\{x_1(i)\}_{i=k+1-p}^{(2q+1)(2p+1)+k+1+p}$ is a normal cycle with the length of $M_{x_2} + 2p + 1$, and hence $M_{x_1} > M_{x_2}$, which leads to a contradiction.

Subcase 2. $x_2(1) = 0$. Then, using a similar argument to that in the proof of Subcase 1, we can show that this is also a contradiction.

If $M_{x_2} < +\infty$, $M_{x_3} = +\infty$, $M_{x_4} = +\infty$ or $M_{x_2} < +\infty$, $M_{x_3} < +\infty$, $M_{x_4} = +\infty$, then we have the same contradiction by similar arguments. This completes the proof.

3. Main Result and Proof

Theorem 3.1. For $k \in Z(0)$, every bounded solution of (1.5) is eventually periodic with the minimal period 4r + 2 for some $r \in \Omega(k)$, where $\Omega(k) = \{r \in Z(0) : (2k + 1)/(2r + 1) \in Z(0)\}$.

Proof. Let $\{(x_1(n), x_2(n), x_3(n), x_4(n))\}_{n=-k}^{+\infty}$ be a bounded solution of (1.5). Then there exists a positive integer $M_0 > 0$ such that $|x_1(n)| + \cdots + |x_4(n)| < M_0$ for all $n \in Z(-k)$. Denote $x_i^n(i) = x_i(n-i)$ for $i \in Z(0,k)$ and $j \in Z(1, \ldots, 4)$, and

$$X_n = (x_1^n(0), x_1^n(1), \dots, x_1^n(k), x_2^n(0), x_2^n(1), \dots, x_2^n(k), \dots, x_4^n(0), \dots, x_4^n(k)).$$
(3.1)

Define $P_i : Z^{4k+4} \to Z$ by setting $P_i(v_1, v_2, ..., v_{4k+4}) = v_i$ for $v_i \in Z$ and $i \in Z(1, 4k+4)$, and define $F = (F_1, F_2, ..., F_{4k+4})$ as

$$F_{i}(X) = \begin{cases} P_{1}X + f(P_{2k+2}X) & \text{for } i = 1, \\ P_{i-1}X & \text{for } 2 \le i \le k+1, \\ P_{k+2}X + f(P_{3k+3}X) & \text{for } i = k+2, \\ P_{i-1}X & \text{for } k+3 \le i \le 2k+2, \\ P_{2k+3}X - f(P_{4k+4}X) & \text{for } i = 2k+3, \\ P_{i-1}X & \text{for } 2k+4 \le i \le 3k+3, \\ P_{3k+4}X - f(P_{k+1}X) & \text{for } i = 3k+4, \\ P_{i-1}X & \text{for } 3k+5 \le i \le 4k+4. \end{cases}$$
(3.2)

Then, $X_{n+1} = F(X_n)$. Since $|x_1(n)| + \cdots + |x_4(n)| < M_0$ for all $n \in Z(-k)$ and $x_j(n) \in Z$ for all $n \in Z(-k)$ and $j \in Z(1,...,4)$, it follows that $\{X_n\}_{n=-k}^{+\infty}$ is a finite set. Therefore, there exist $n_1 > n_2 \ge 1$ such that $X_{n_2} = X_{n_1} = X_{n_2+n_1-n_2}$. This, combined with $X_{n+1} = F(X_n)$, gives $X_n = X_{n+n_1-n_2}$ for $n \ge n_2 + 1$. Hence, $\{X_n\}_{n=-k}^{+\infty}$ is eventually periodic with the period $(n_1 - n_2)$. It follows that $\{P_j X_n\}_{n=-k}^{+\infty}$ are also eventually periodic, j = 1, k+2, 2k+3, 3k+4. Therefore, $\{(x_1(n), \dots, x_4(n))\}_{n=-k}^{+\infty}$ is eventually periodic with the minimal period $T \in Z(1)$. By Lemma 2.11, there exists some $r \in Z(0)$ such that T = 4r + 2. Without loss of generality, we assume that $\{x_1(n)\}_{n=1}^{+\infty}$ is a total *r*-normal cycle, and $x_1(1) = 1$. Then, $x_1(r+1) = r+1$. By Lemma 2.8, we can get that $x_4(r+k+1) = 1$ and $x_4(2r+2+k) = -r$. It follows from Lemma 2.9 that $x_3(2r+2k+2) = 0$ and $x_3(3r+2k+3) = r+1$, and so, again by Lemma 2.8, $x_2(3r+3k+3) = 0$ and $x_2(4r+3k+4) = r+1$. By Lemma 2.8, we have $x_1(4r+4k+4) = 0$ and $x_1(5r+4k+5) = r+1$. From (1.5) and (1.3), we can get $x_1(4r + 4k + 5) = x_1(4r + 4k + 4) + f(x_2(4r + 3k + 4))$. Thus, $x_1(4r+4k+5) = 0+1 = 1$. Therefore, $\{x_1(i)\}_{i=1}^{4r+4k+4}$ consists of $A_r^+, A_r^-, \dots, A_r^+, A_r^-$, consecutively, in total of N semicycles, in which N is a positive even integer. Consequently, there exists an integer $M \ge 0$ such that $4r + 4k + 4 = (2r + 1) \cdot (2M + 2)$, that is, (2k + 1)/(2r + 1) = M, which implies that $r \in \Omega(k)$. This completes the proof.

Acknowledgment

This paper is supported by the Fundamental Research Funds for the Central Universities of Hunan University (Grant no. 531107040013).

References

- J. J. Hopfield, "Neural networks and physical systems with emergent collective computational abilities," *Proceedings of the National Academy of Sciences of the United States of America*, vol. 79, no. 8, pp. 2554–2558, 1982.
- [2] J. J. Hopfield, "Neurons with graded response have collective computational properties like those of two-state neurons," *Proceedings of the National Academy of Sciences*, vol. 81, pp. 3088–3092, 1984.
- [3] C. M. Marcus and R. M. Westervelt, "Stability of analog neural networks with delay," *Physical Review A*, vol. 39, no. 1, pp. 347–359, 1989.
- [4] S. Busenberg and K. L. Cooke, "Models of vertically transmitted diseases with sequential-continuous dynamics," in *Nonlinear Phenomena in Mathematical Science*, V. Lakshmikanthan, Ed., pp. 179–187, Academic Press, New York, NY, USA, 1982.
- [5] K. L. Cooke and J. Wiener, "Retarded differential equations with piecewise constant delays," *Journal of Mathematical Analysis and Applications*, vol. 99, no. 1, pp. 265–297, 1984.
- [6] S. M. Shah and J. Wiener, "Advanced differential equations with piecewise constant argument deviations," *International Journal of Mathematics and Mathematical Sciences*, vol. 6, no. 4, pp. 671–703, 1983.
- [7] K. L. Cooke and J. Wiener, "A survey of differential equations with piecewise continuous arguments," in *Delay Differential Equations and Dynamical systems*, vol. 1475 of *Lecture Notes in Mathematics*, pp. 1–15, Springer, Berlin, Germany, 1991.
- [8] J. Wu, Introduction to Neural Dynamics and Signal Transmission Delay, vol. 6 of de Gruyter Series in Nonlinear Analysis and Applications, Walter de Gruyter, Berlin, Germany, 2001.
- [9] H. Bin, L. Huang, and G. Zhang, "Convergence and periodicity of solutions for a class of difference systems," Advances in Difference Equations, vol. 2006, Article ID 70461, 10 pages, 2006.
- [10] S. J. Guo, L. Huang, and J. Wu, "Regular dynamics in a delayed network of two neurons with all-or-none activation functions," *Physica D*, vol. 206, no. 1-2, pp. 32–48, 2005.
 [11] X. C. Mao and H. Y. Hu, "Hopf bifurcation analysis of a four-neuron network with multiple time
- [11] X. C. Mao and H. Y. Hu, "Hopf bifurcation analysis of a four-neuron network with multiple time delays," *Nonlinear Dynamics*, vol. 55, no. 1-2, pp. 95–112, 2009.
- [12] J. Milton, Dynamics of Small Neural Populations, vol. 7 of CRM Monograph Series, American Mathematical Society, Providence, RI, USA, 1996.
- [13] Z. Wei, L. Huang, and Y. Meng, "Unboundedness and periodicity of solutions for a discrete-time network model of three neurons," *Applied Mathematical Modelling. Simulation and Computation for Engineering and Environmental Systems*, vol. 32, no. 7, pp. 1463–1474, 2008.
- [14] Z. Zhou and J. Wu, "Attractive periodic orbits in nonlinear discrete-time neural networks with delayed feedback," *Journal of Difference Equations and Applications*, vol. 8, no. 5, pp. 467–483, 2002.
- [15] J. Wei and S. Ruan, "Stability and bifurcation in a neural network model with two delays," *Physica D*, vol. 130, no. 3-4, pp. 255–272, 1999.
- [16] Y. Chen, "All solutions of a class of difference equations are truncated periodic," Applied Mathematics Letters, vol. 15, no. 8, pp. 975–979, 2002.
- [17] Y. M. Chen, "Limiting behavior of a class of delay difference equations," Dynamics of Continuous, Discrete and Impulsive Systems: Series A, vol. 10, no. 1–3, pp. 75–80, 2003.
- [18] Y. M. Chen, "Unboundedness and periodicity of a system of delay difference equations," Mitteilungen aus dem Mathematischen Seminar Giessen, no. 248, pp. 1–19, 2002.



Advances in **Operations Research**

The Scientific

World Journal





Mathematical Problems in Engineering

Hindawi

Submit your manuscripts at http://www.hindawi.com



Algebra



Journal of Probability and Statistics



International Journal of Differential Equations





International Journal of Combinatorics

Complex Analysis









Journal of Function Spaces



Abstract and Applied Analysis





Discrete Dynamics in Nature and Society