Research Article

Existence Results of Nondensely Defined Fractional Evolution Differential Inclusions

Zufeng Zhang^{1,2} and Bin Liu¹

¹ School of Mathematics and Statistics, Huazhong University of Science and Technology, Hubei, Wuhan 430074, China

² School of Mathematics and Statistics, Suzhou University, Anhui, Suzhou 234000, China

Correspondence should be addressed to Bin Liu, binliu@mail.hust.edu.cn

Received 26 March 2012; Accepted 20 April 2012

Academic Editor: Yonghong Yao

Copyright © 2012 Z. Zhang and B. Liu. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

This paper deals with the existence results of integral solutions for nondensely defined fractional evolution differential inclusions. Our approach is based on integrated semigroup theory and a fixed point theorem for condensing map due to Martelli. An example is also given to illustrate our results.

1. Introduction

In the past decades, the theory of fractional differential equations and inclusions has become an important area of investigation because of its wide applicability in many branches of physics, economics, and technical sciences [1–10].

Our aim in this paper is to study the existence of the integral solutions for the fractional semilinear differential inclusions, of the form

$$D^{q}x(t) \in Ax(t) + F(t, x(t)), \quad t \in (0, b],$$

$$x(0) = x_{0},$$

(1.1)

where D^q is the Caputo fractional derivative of order 0 < q < 1, b > 0. $A : D(A) \subset X \to X$ is a nondensely closed linear operator on X, X is a real Banach space with the norm $|\cdot|$. $F : [0, \infty) \times X \to \mathcal{P}(X)$ is a nonempty, bounded, closed, and convex multivalued map, and $\mathcal{P}(X)$ denotes the family of all nonempty subsets of X.

It is well known that one important way to introduce the concepts of mild solutions for fractional evolution equations is based on some probability densities and Laplace transform. This method was initialed by El-Borai [11] and developed by Zhou and Jiao [12]. Since then, many interesting existence results of mild solutions for fractional evolution equations appeared [13–16]. We will point out that the unbounded operators *A* in their papers were assumed to be densely defined and generate a strongly continuous semigroup.

However, as indicated in [17], we sometimes need to deal with nondensely defined operators and there are extensive work on this subject when equations involve the integral-order derivative, see monograph [18–23] and references therein. Very recently, Wang and Zhou [24] considered problem (1.1) in the case when *A* is densely defined and generates a strongly continuous semigroup. As far as we know, there are few papers dealing with semilinear fractional differential systems with nondense domain. Motivated by this, we discuss the integral solution to problem (1.1) by using probability densities and integral semigroup. We turn the integral solutions of problem (1.1) to a new formula something like the mild solutions. This new formula of integral solutions is firstly introduced even in fractional evolution to this emerging field of fractional differential equations with nondense domain.

This paper will be organized as follows. In Section 2, we recall some basic definitions and preliminary facts for integrated semigroup, fractional calculus, and multivalued map which will be used later. Section 3 is devoted to the existence results of integral solutions for problem (1.1). We will present in Section 4 an example which illustrates our main theorem.

2. Preliminaries

In this section, we introduce notations, definitions, and preliminary results which are used in the rest of the paper.

We denote by C([0,b], X) the Banach space of all continuous functions from [0,b] into X with the norm

$$\|y\| = \sup\{|y(t)| : t \in [0,b]\}.$$
(2.1)

B(X) denotes the Banach space of bounded linear operators from X into X, with the norm

$$||N|| = \sup\{|N(y)| : |y| = 1\},$$
(2.2)

where $N \in B(X)$ and $y \in X$.

Assume that $J \subset \mathbf{R}$ and $1 \leq p \leq \infty$. For a measurable function $m : J \to \mathbf{R}$, define the norm

$$\|m\|_{L^{p}J} = \begin{cases} \left(\int_{J} |m(t)|^{p} dt \right)^{1/p}, & 1 \le p < \infty, \\ \\ \inf_{\mu(\overline{J})=0} \left\{ \sup_{t \in J - \overline{J}} |m(t)| \right\}, & p = \infty, \end{cases}$$
(2.3)

where $\mu(\overline{J})$ is the Lebesgue measure on \overline{J} . Let $L^p(J, \mathbf{R})$ be the Banach space of all Lebesgue measurable functions $m : J \to \mathbf{R}$ with $\|\cdot\|_{L^p I} < \infty$.

Lemma 2.1 (HöLder inequality). Assume that $r, p \ge 1$ and (1/r) + (1/p) = 1. If $l \in L^r(J, \mathbb{R})$, $m \in L^p(J, \mathbb{R})$, then for $1 \le p \le \infty$, $lm \in L^1(J, \mathbb{R})$ and

$$\|lm\|_{L^{1}J} \le \|l\|_{L^{r}J} \|m\|_{L^{p}J}.$$
(2.4)

Lemma 2.2 (Bochner theorem). A measurable function $H : [0,b] \rightarrow X$ is Bochner's integrable if |H| is Lebesgue integrable.

Definition 2.3 (see [25]). Let *X* be a Banach space; an integrated semigroup is a family of operators $(S(t))_{t>0}$ of bounded linear operators S(t) on *X* with the following properties:

- (i) S(0) = 0;
- (ii) $t \to S(t)$ is strongly continuous;
- (iii) $S(s)S(t) = \int_0^s (S(t+r) S(r))dr$ for all $t, s \ge 0$.

Definition 2.4 (see [26]). An operator A is called a generator of an integrated semigroup, if there exists $\omega \in \mathbf{R}$ such that $(\omega, +\infty) \subset \rho(A)$ and there exists a strongly continuous exponentially bounded family $(S(t))_{t\geq 0}$ of linear bounded operators such that S(0) = 0 and $(\lambda I - A)^{-1} = \lambda \int_0^\infty e^{-\lambda t} S(t) dt$ for all $\lambda > \omega$.

Proposition 2.5 (see [25]). Let A be the generator of an integrated semigroup $(S(t))_{t\geq 0}$. Then for all $x \in X$ and $t \geq 0$,

$$\int_0^t S(s)xds \in D(A), \qquad S(t)x = A \int_0^t S(s)xds + tx.$$
(2.5)

Definition 2.6 (see [26]). We say that linear operator *A* satisfies the Hille-Yosida condition if there exist $M \ge 0$ and $\omega \in \mathbf{R}$ such that $(\omega, +\infty) \subset \rho(A)$ and

$$\sup\{(\lambda - \omega)^n \| R(\lambda, A)^n \|, n \in \mathbf{N}, \lambda > \omega\} \le M.$$
(2.6)

Here and hereafter, we assume that *A* satisfies the Hille-Yosida condition. Let us introduce the part A_0 of A in $\overline{D(A)} : A_0 = A$ on $D(A_0) = \{x \in D(A); Ax \in \overline{D(A)}\}$. Let $(S(t))_{t\geq 0}$ be the integrated semigroup generated by *A*. We note that $(S'(t))_{t\geq 0}$ is a C_0 -semigroup on $\overline{D(A)}$ generated by A_0 and $||S'(t)|| \le Me^{\omega t}$, $t \ge 0$, where *M* and ω are the constants considered in the Hille-Yosida condition ([19, 27]).

Let $B_{\lambda} = \lambda R(\lambda, A) := \lambda (\lambda I - A)^{-1}$; then for all $x \in \overline{D(A)}$, $B_{\lambda}x \to x$ as $\lambda \to \infty$. Also from the Hille-Yosida condition it is easy to see that $\lim_{\lambda \to \infty} |B_{\lambda}x| \le M|x|$.

For more properties on integral semigroup theory the interested readers may refer to [18, 27].

Definition 2.7 (see [3]). The Riemann-Liouville fractional integral of order $\alpha \in \mathbf{R}^+$ of a function $f : \mathbf{R}^+ \to X$ is defined by

$$I_0^{\alpha} f(t) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s) ds, \quad t > 0,$$
(2.7)

provided the right-hand side is pointwise defined on \mathbf{R}^+ , where Γ is the gamma function.

Remark 2.8. According to [3], $I_0^q I_0^\beta = I_0^{q+\beta}$ holds for all $q, \beta \ge 0$.

Definition 2.9 (see [3]). The Caputo fractional derivative of order $0 < \alpha < 1$ of a function $f \in C^1([0, \infty), X)$ is defined by

$$D^{\alpha}f(t) = \frac{1}{\Gamma(1-\alpha)} \int_0^t (t-s)^{-\alpha} f'(s) ds, \quad t > 0.$$
 (2.8)

We will remark that integrals which appear in Definitions 2.7 and 2.9 are taken in Bochner's sense.

Lemma 2.10 (see [28]). Suppose $\beta > 0$, a(t) is a nonnegative, function locally integrable on $0 \le t < T$ and g(t) is a nonnegative, nondecreasing continuous function defined on $0 \le t < T$, $g(t) \le M$ (constant), and suppose u(t) is nonnegative and locally integrable on $0 \le t < T$ with

$$u(t) \le a(t) + g(t) \int_0^t (t-s)^{\beta-1} u(s) ds$$
(2.9)

on this interval. Then

$$u(t) \le a(t) + \int_0^t \left[\sum_{n=1}^\infty \frac{(g(t)\Gamma(\beta))^n}{\Gamma(n\beta)} (t-s)^{n\beta-1} a(s) \right] ds, \quad 0 \le t < T.$$
(2.10)

Corollary 2.11 (see [28]). Under the hypothesis of Lemma 2.10, let a(t) be a nondecreasing function on [0, T). Then

$$u(t) \le a(t) E_{\beta} \Big(g(t) \Gamma(\beta) t^{\beta} \Big), \tag{2.11}$$

where E_{β} is the Mittag-Leffler function defined by $E_{\beta}(z) = \sum_{k=0}^{\infty} (z^k / \Gamma(k\beta + 1))$.

We also introduce some basic definitions and results of multivalued maps. See [29] for more details.

Let (X, d) be a metric space; $\mathcal{P}(X)$ denotes the family for all nonempty subsets of X. We use the following notations:

$$P_{cl}(X) = \{Y \in \mathcal{P}(X) : Y \text{ closed}\}, \qquad P_b(X) = \{Y \in \mathcal{P}(X) : Y \text{ bounded}\},$$

$$P_c(X) = \{Y \in \mathcal{P}(X) : Y \text{ convex}\}, \qquad P_{cp}(X) = \{Y \in \mathcal{P}(X) : Y \text{ compact}\}.$$

$$(2.12)$$

A multivalued map $F : X \to \mathcal{P}(X)$ is convex (closed) valued if F(x) is convex (closed) for all $x \in X$ and F is bounded on bounded sets if $F(B) = U_{x \in B}F(x)$ is bounded in X for all $B \in P_b(X)$, that is, $\sup_{x \in B} \{\sup\{|y| : y \in F(x)\}\} < \infty$. F is called upper semicontinuous (u.s.c. for short) on X if for each $x_0 \in X$ the set $F(x_0)$ is nonempty, closed subset of X, and for each open set \mathcal{U} of X containing $F(x_0)$, there exists an open neighborhood \mathcal{U} of x_0 such that $F(\mathcal{U}) \subset \mathcal{U}$. F is said to be completely continuous if F(B) is relatively compact for every $B \in P_b(X)$.

If the multivalued map *F* is completely continuous with nonempty compact valued, the *F* is u.s.c. if and only if *F* has closed graph, that is, $x_n \rightarrow x_*$, $y_n \rightarrow y_*$, $y_n \in F(x_n)$ imply $y_* \in F(x_*)$.

Definition 2.12 (see [30]). An upper semicontinuous map $G : X \to X$ is said to be condensing if for any bounded subset $V \subset X$ with $\alpha(V) \neq 0$, one has $\alpha(G(V)) < \alpha(V)$, where α denotes the Kuratowski measure of noncompactness.

We remark that a completely continuous multivalued map is the easiest example of a condensing map.

Theorem 2.13 (see [30]). Let *J* be a compact interval and *X* a Banach space. Let $F : J \times C(J, X) \rightarrow P_{b,cl,c}(X)$, $(t, u) \mapsto F(t, u)$ be measurable with respect to *t* for each $u \in X$, upper semicontinuous with respect to *u* for each $t \in J$. Moreover, for each fixed $u \in C(J, X)$ the set

$$N_{F,u} = \left\{ f \in L^1(J, X) : f(t) \in F(t, u) \text{ for a.e. } t \in J \right\}$$
(2.13)

is nonempty. Also let \mathcal{T} be a linear continuous mapping from $L^1(J,X)$ to C(J,X); then the operator

$$\mathcal{T} \circ N_F : \mathcal{C}(J, X) \longrightarrow \mathcal{P}_{b, cl, c}(\mathcal{C}(J, X)), \qquad u \longrightarrow (\mathcal{T} \circ N_F)(u) = \mathcal{T}(N_{F, u})$$
(2.14)

is a closed graph operator in $C(J, X) \times C(J, X)$.

Theorem 2.14 (Martelli, [31]). Let X be a Banach space and $\Phi : X \to P_{b,cl,c}(X)$ a condensing map. *If the set*

$$U = \{x \in X : \delta x \in \Phi x \text{ for some } \delta > 1\}$$
(2.15)

is bounded, then Φ has a fixed point.

3. Existence of Integral Solutions

In this section we will establish the existence results for problem (1.1). Let us consider the following problem:

$$D^{q}x(t) = Ax(t) + f(t, x(t)), \quad t \in (0, b],$$

$$x(0) = x_{0},$$

(3.1)

where $f : [0, \infty) \times X \to X$ is a given function and A is the same as that in problem (1.1).

Definition 3.1. One says that a continuous function $x : [0, b] \rightarrow X$ is an integral solution of problem (3.1) if

(i)
$$(1/\Gamma(q)) \int_0^t (t-s)^{q-1} x(s) ds \in D(A)$$
 for $t \in [0,b]$,
(ii) $x(t) = x_0 + (1/\Gamma(q)) A \int_0^t (t-s)^{q-1} x(s) ds + (1/\Gamma(q)) \int_0^t (t-s)^{q-1} f(s,x(s)) ds, t \in [0,b]$.

Lemma 3.2. If x is an integral solution of (1.1), then for all $t \in [0, b]$, $x(t) \in \overline{D(A)}$. In particular, $x(0) = x_0 \in \overline{D(A)}$.

Proof. By Remark 2.8 and $I_0^q x(t) \in D(A)$, for each $t \in (0, b]$, we get that $I_0^1 x(t) = I_0^{1-q} I_0^q x(t) \in D(A)$. From $I_0^1 x(t) = \int_0^t x(s) ds \in D(A)$ we have $(1/h) \int_t^{t+h} x(s) ds \in D(A)$ for $h > 0, t+h \in (0, b]$. Hence, we deduce that

$$x(t) = \lim_{h \to 0} \frac{1}{h} \int_{t}^{t+h} x(s) ds \in \overline{D(A)}.$$
(3.2)

The proof is completed.

Lemma 3.3 (see [32]). Let $\Psi_q(\theta) = (1/\pi) \sum_{n=1}^{\infty} (-1)^{n-1} \theta^{-qn-1} (\Gamma(nq+1)/n!) \sin(n\pi q), \theta \in \mathbf{R}^+$; then $\Psi_q(\theta)$ is a one-sided stable probability density function and its Laplace transform is given by

$$\int_0^\infty e^{-p\theta} \Psi_q(\theta) d\theta = e^{-p^q}, \quad q \in (0,1), \ p > 0.$$
(3.3)

Lemma 3.4. The integral solution in Definition 3.1 is given by

$$x(t) = \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta + \lim_{\lambda \to \infty} q \int_0^t \int_0^\infty \theta(t-s)^{q-1} h_q(\theta) S'\big((t-s)^q \theta\big) B_\lambda f(s, x(s)) d\theta ds,$$
(3.4)

where $h_q(\theta) = (1/q)\theta^{-1-(1/q)}\Psi_q(\theta^{-1/q})$ is the probability density function defined on \mathbb{R}^+ .

Proof. From the definition, we have

$$x(t) = x_0 + \frac{1}{\Gamma(q)} A \int_0^t (t-s)^{q-1} x(s) ds + \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} f(s,x(s)) ds, \quad t \in [0,b].$$
(3.5)

Consider the Laplace transform

$$v(p) = \int_0^\infty e^{-pt} B_\lambda x(t) dt, \qquad w(p) = \int_0^\infty e^{-pt} B_\lambda f(t, x(t)) dt, \quad p > 0.$$
(3.6)

Note that for each t > 0, $B_{\lambda}x(t)$, $B_{\lambda}f(t, x(t)) \in D(A)$, then we have v(p), $w(p) \in \overline{D(A)}$. Applying (3.6) to (3.5) yields

$$v(p) = \frac{1}{p} B_{\lambda} x_{0} + \frac{1}{p^{q}} A v(p) + \frac{1}{p^{q}} w(p)$$

$$= p^{q-1} (p^{q} I - A)^{-1} B_{\lambda} x_{0} + (p^{q} I - A)^{-1} w(p)$$
(3.7)
$$= p^{q-1} \int_{0}^{\infty} e^{-p^{q} s} S'(s) B_{\lambda} x_{0} ds + \int_{0}^{\infty} e^{-p^{q} s} S'(s) w(p) ds,$$

where I is the identity operator defined on X.

From (3.3), we get

$$p^{q-1} \int_{0}^{\infty} e^{-p^{q}s} S'(s) B_{\lambda} x_{0} ds = \int_{0}^{\infty} p^{q-1} e^{-(pt)^{q}} S'(t^{q}) B_{\lambda} x_{0} qt^{q-1} dt$$

$$= \int_{0}^{\infty} -\frac{1}{p} \frac{d}{dt} \left(e^{-(pt)^{q}} \right) S'(t^{q}) B_{\lambda} x_{0} dt$$

$$= \int_{0}^{\infty} \left[\theta \Psi_{q}(\theta) e^{-pt\theta} S'(t^{q}) B_{\lambda} x_{0} \right] d\theta dt \qquad (3.8)$$

$$= \int_{0}^{\infty} \left[\Psi_{q}(\theta) e^{-ps} S'\left(\left(\frac{s}{\theta}\right)^{q}\right) B_{\lambda} x_{0} \right] d\theta ds$$

$$= \int_{0}^{\infty} e^{-pt} \left[\int_{0}^{\infty} \Psi_{q}(\theta) S'\left(\left(\frac{t}{\theta}\right)^{q}\right) B_{\lambda} x_{0} d\theta \right] dt,$$

$$\int_{0}^{\infty} e^{-p^{q}s} S'(s) w(p) ds = \iint_{0}^{\infty} e^{-pt} S'(s) B_{\lambda} f(t, x(t)) dt ds$$

$$= \iint_{0}^{\infty} q S^{q-1} e^{-(ps)^{q}} e^{-pt} S'(s^{q}) B_{\lambda} f(t, x(t)) dt ds$$

$$= \iint_{0}^{\infty} \int_{0}^{\infty} q \Psi_{q}(\theta) e^{-ps\theta} e^{-pt} S'(s^{q}) B_{\lambda} f(t, x(t)) d\theta dt ds$$

$$= \iint_{0}^{\infty} \int_{0}^{\infty} q \Psi_{q}(\theta) e^{-p(s+t)} \frac{s^{q-1}}{\theta^{q}} S'\left(\left(\frac{s}{\theta}\right)^{q}\right) B_{\lambda} f(t, x(t)) d\theta dt ds$$

$$= \int_{0}^{\infty} e^{-ps} q \int_{0}^{s} \int_{0}^{\infty} \Psi_{q}(\theta) \frac{(s-t)^{q-1}}{\theta^{q}} S'\left(\frac{(s-t)^{q}}{\theta^{q}}\right) B_{\lambda} f(t, x(t)) d\theta dt ds$$

$$= \int_{0}^{\infty} e^{-pt} q \int_{0}^{t} \int_{0}^{\infty} \Psi_{q}(\theta) \frac{(t-s)^{q-1}}{\theta^{q}} S'\left(\frac{(t-s)^{q}}{\theta^{q}}\right) B_{\lambda} f(s, x(s)) d\theta ds dt.$$
(3.9)

According to (3.7), (3.8), and (3.9), we have

$$\begin{aligned} \upsilon(p) &= \int_0^\infty e^{-pt} \left[\int_0^\infty \Psi_q(\theta) S'\left(\left(\frac{t}{\theta}\right)^q\right) B_\lambda x_0 d\theta \right] dt \\ &+ \int_0^\infty e^{-pt} q \int_0^t \int_0^\infty \Psi_q(\theta) \frac{(t-s)^{q-1}}{\theta^q} S'\left(\frac{(t-s)^q}{\theta^q}\right) B_\lambda f(s,x(s)) d\theta ds \, dt. \end{aligned}$$
(3.10)

Inverting the last Laplace transform, we obtain

$$\begin{split} B_{\lambda}x(t) &= \int_{0}^{\infty} \Psi_{q}(\theta) S'\left(\left(\frac{t}{\theta}\right)^{q}\right) B_{\lambda}x_{0}d\theta \\ &+ q \int_{0}^{t} \int_{0}^{\infty} \Psi_{q}(\theta) \frac{(t-s)^{q-1}}{\theta^{q}} S'\left(\frac{(t-s)^{q}}{\theta^{q}}\right) B_{\lambda}f(s,x(s))d\theta ds \\ &= \int_{0}^{\infty} h_{q}(\theta) S'(t^{q}\theta) B_{\lambda}x_{0}d\theta \\ &+ q \int_{0}^{t} \int_{0}^{\infty} \theta(t-s)^{q-1}h_{q}(\theta) S'((t-s)^{q}\theta) B_{\lambda}f(s,x(s))d\theta ds. \end{split}$$
(3.11)

In view of $\lim_{\lambda \to \infty} B_{\lambda} x = x$ for $x \in \overline{D(A)}$ and Lemma 3.2, we have

$$x(t) = \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta + \lim_{\lambda \to \infty} q \int_0^t \int_0^\infty \theta(t-s)^{q-1} h_q(\theta) S'((t-s)^q \theta) B_\lambda f(s, x(s)) d\theta ds.$$
(3.12)

The proof is completed.

Remark 3.5. According to [32], one can easily check that

$$\int_{0}^{\infty} \theta h_{q}(\theta) d\theta = \int_{0}^{\infty} \frac{1}{\theta^{q}} \Psi_{q}(\theta) d\theta = \frac{1}{\Gamma(1+q)}.$$
(3.13)

Based on the Lemma 3.4, we will define the concept of integral solution of (1.1) as follows.

Definition 3.6. One says that a continuous function $x : [0,b] \rightarrow X$ is an integral solution of problem (1.1) if

(i) $(1/\Gamma(q)) \int_0^t (t-s)^{q-1} x(s) ds \in D(A)$ for $t \in [0, b]$, (ii) $x(0) = x_0$ and there exists $f \in L^1([0, b], X)$ such that $f(t) \in F(t, x(t))$ for a.e. $t \in [0, b]$ and

$$x(t) = \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta + \lim_{\lambda \to \infty} q \int_0^t \int_0^\infty \theta(t-s)^{q-1} h_q(\theta) S'\big((t-s)^q \theta\big) B_\lambda f(s) d\theta ds, \ t \in [0,b].$$
(3.14)

We are now in a position to state and prove our main results of the existence of solutions for problem (1.1).

Let us list the following hypotheses:

- (H1) A satisfies the Hille-Yosida condition;
- (H2) the operator S'(t) is compact in $\overline{D(A)}$ whenever t > 0 and satisfies $\sup_{t \in [0,\infty]} ||S'(t)|| = M_0 < \infty$, where M_0 is a constant;
- (H3) $F : [0,b] \times X \rightarrow P_{b,cl,c}(X)$, for each $x \in X$, $F(\cdot, x)$ is measurable and for each $t \in [0,b]$, $F(t, \cdot)$ is upper semicontinuous; for each fixed $x \in X$, the set $N_{F,x} = \{f \in L^1([0,b],X) : f(t) \in F(t,x), \text{ for a.e. } t \in [0,b]\}$ is not empty;
- (H4) for each $x \in X$, there exist $m \in L^{1/q_1}([0, b], \mathbb{R}^+)$ and $n \in C([0, b], \mathbb{R}^+)$ such that

$$\sup\{|f(t)|: f(t) \in F(t,x)\} \le m(t) + n(t)|x| \quad \text{for a.e. } t \in [0,b],$$
(3.15)

where $q_1 \in [0, q)$.

Theorem 3.7. Assume that hypotheses (H1)–(H4) hold; then problem (1.1) has an integral solution $x \in C([0,b], \overline{D(A)})$.

Proof. Denote $C_0 = C([0,b], \overline{D(A)})$, which is a closed subset of C([0,b], X). Obviously, C_0 with the same norm in C([0,b], X) is also a Banach space. Transform the problem (1.1) into a fixed point problem. Consider the multivalued operator $\Phi : C_0 \to \mathcal{P}(C_0)$ defined by

$$\Phi x = \left\{ h \in C_0 : h(t) = \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta + \lim_{\lambda \to \infty} q \int_0^t \int_0^\infty \theta(t-s)^{q-1} h_q(\theta) S'((t-s)^q \theta) B_\lambda f(s) d\theta ds \right\},$$
(3.16)

where $f \in N_{F,x} = \{f \in L^1([0,b],X) : f(t) \in F(t,x(t)), \text{ for a.e. } t \in [0,b]\}$. Obviously, the fixed points of the operator Φ are integral solutions of problem (1.1). Now we will show that Φ satisfies all conditions of Theorem 2.14. The proof would be divided into the following steps.

Step 1 ($\Phi(x)$ is convex for each $x \in C_0$). Indeed, if h_1 and h_2 belong to Φx , then there exist f_1 , $f_2 \in N_{F,x}$ such that for each $t \in [0, b]$, we have

$$h_{i}(t) = \int_{0}^{\infty} h_{q}(\theta) S'(t^{q}\theta) x_{0} d\theta + \lim_{\lambda \to \infty} q \int_{0}^{t} \int_{0}^{\infty} \theta(t-s)^{q-1} h_{q}(\theta) S'((t-s)^{q}\theta) B_{\lambda} f_{i}(s) d\theta ds, \quad i = 1, 2.$$

$$(3.17)$$

Let $0 \le k \le 1$; then for each $t \in [0, b]$, we have

$$(kh_{1} + (1-k)h_{2})(t) = \int_{0}^{\infty} h_{q}(\theta)S'(t^{q}\theta)x_{0}d\theta$$

+
$$\lim_{\lambda \to \infty} q \int_{0}^{t} \int_{0}^{\infty} \theta(t-s)^{q-1}h_{q}(\theta)S'((t-s)^{q}\theta)B_{\lambda}$$

×
$$(kf_{1}(s) + (1-k)f_{2}(s))d\theta ds.$$
(3.18)

Since $N_{F,x}$ is convex, we have $kh_1 + (1 - k)h_2 \in \Phi x$.

Step 2 (Φ maps bounded sets into bounded sets in C_0). Indeed, it is enough to show that there exists a positive constant *l* such that for each $h \in \Phi x$, $x \in B_r = \{x \in C_0, ||x|| \le r\}$ one has $||h|| \le l$.

Let $h \in \Phi x$; then there exists $f \in N_{F,x}$ such that for $t \in [0, b]$, we have

$$h(t) = \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta + \lim_{\lambda \to \infty} q \int_0^t \int_0^\infty \theta(t-s)^{q-1} h_q(\theta) S'((t-s)^q \theta) B_\lambda f(s) d\theta ds.$$
(3.19)

From (H2) and the fact that $||B_{\lambda}|| \le M$, for $t \in [0, b]$ we have

$$\begin{aligned} |h(t)| &\leq \left| \int_{0}^{\infty} h_{q}(\theta) S'(t^{q}\theta) x_{0} d\theta \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{t} \int_{0}^{\infty} \theta(t-s)^{q-1} h_{q}(\theta) S'((t-s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &\leq M_{0}|x_{0}| + M M_{0} \int_{0}^{t} \int_{0}^{\infty} \theta h_{q}(\theta) \left| (t-s)^{q-1}f(s) \right| d\theta ds \\ &\leq M_{0}|x_{0}| + \frac{q M M_{0}}{\Gamma(1+q)} \int_{0}^{t} \left| (t-s)^{q-1}f(s) \right| ds. \end{aligned}$$

$$(3.20)$$

From Lemma 2.1 and (H4), for $t \in [0, b]$ we have

$$\int_{0}^{t} \left| (t-s)^{q-1} f(s) \right| ds \leq \left(\int_{0}^{t} (t-s)^{(q-1)/(1-q_{1})} ds \right)^{1-q_{1}} \|m\|_{L^{1/q_{1}}[0,t]} + \overline{n}r \int_{0}^{t} (t-s)^{q-1} ds$$

$$\leq \frac{M_{1}}{(1+a)^{1-q_{1}}} b^{(1+a)(1-q_{1})} + \frac{\overline{n}rb^{q}}{q},$$
(3.21)

where $a = (q-1)/(1-q_1) \in (-1,0), M_1 = ||m||_{L^{1/q_1}[0,b]}, \overline{n} = \sup\{n(t), t \in [0,b]\}.$ Then from (3.20) and (3.21), we get that

$$\|h\| \le M_0 |x_0| + \frac{MM_0}{\Gamma(1+q)} \left(\frac{qM_1}{(1+a)^{1-q_1}} b^{(1+a)(1-q_1)} + \overline{n}r b^q \right) := l.$$
(3.22)

Step 3 (Φ maps bounded sets into equicontinuous sets of C_0). Let $t_1, t_2 \in [0, b]$, $t_1 < t_2$, and $\mathcal{B}_r = \{x \in C_0, \|x\| \le r\}$ be a bounded set of C_0 . For each $x \in \mathcal{B}_r$ and $h \in \Phi x$, there exists $f \in N_{F,x}$ such that

$$h(t) = \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta + \lim_{\lambda \to \infty} q \int_0^t \int_0^\infty \theta(t-s)^{q-1} h_q(\theta) S'\big((t-s)^q \theta\big) B_\lambda f(s) d\theta ds.$$
(3.23)

Then,

$$\begin{split} |h(l_{2}) - h(l_{1})| &= \left| \int_{0}^{\infty} h_{q}(\theta) S'(t_{2}^{q}\theta) x_{0} d\theta - \int_{0}^{\infty} h_{q}(\theta) S'(t_{1}^{q}\theta) x_{0} d\theta \right. \\ &+ \lim_{\lambda \to \infty} q \int_{0}^{l_{2}} \int_{0}^{\infty} \theta(t_{2} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \\ &- \lim_{\lambda \to \infty} q \int_{0}^{l_{2}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) S'((t_{1} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &\leq \int_{0}^{\infty} h_{q}(\theta) \left\| S'(t_{2}^{q}\theta) - S'(t_{1}^{q}\theta) \right\| |x_{0}| d\theta \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{2}} \int_{0}^{\infty} \theta(t_{2} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{1}} \int_{0}^{\infty} \theta(t_{2} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{1}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{1}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{1}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{1}} \int_{0}^{\infty} \theta(t_{2} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{2}} \int_{0}^{\infty} \theta(t_{2} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{2}} \int_{0}^{\infty} \theta(t_{2} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{2}} \int_{0}^{\infty} \theta(t_{2} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{2}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{2}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) [(S'(t_{2} - s)^{q}\theta) - S'((t_{1} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{1}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) [(S'(t_{2} - s)^{q}\theta) - S'((t_{1} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{1}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) [(S'(t_{2} - s)^{q}\theta) - S'((t_{1} - s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{l_{1}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) [(S'(t_{2} - s)^{q}\theta) - S'((t_{1} -$$

where

$$\begin{split} I_{1} &= \int_{0}^{\infty} h_{q}(\theta) \left\| S'\left(t_{2}^{q}\theta\right) - S'\left(t_{1}^{q}\theta\right) \right\| |x_{0}| d\theta, \\ I_{2} &= \left| \lim_{\lambda \to \infty} \int_{t_{1}}^{t_{2}} \int_{0}^{\infty} \theta(t_{2} - s)^{q-1} h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda} f(s) d\theta ds \right|, \\ I_{3} &= \left| \lim_{\lambda \to \infty} \int_{0}^{t_{1}} \int_{0}^{\infty} \theta \Big[(t_{2} - s)^{q-1} - (t_{1} - s)^{q-1} \Big] h_{q}(\theta) S'((t_{2} - s)^{q}\theta) B_{\lambda} f(s) d\theta ds \right|, \\ I_{4} &= \left| \lim_{\lambda \to \infty} \int_{0}^{t_{1}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) \left[S'((t_{2} - s)^{q}\theta) - S'((t_{1} - s)^{q}\theta) \right] B_{\lambda} f(s) d\theta ds \right|. \end{split}$$
(3.25)

By using analogous argument performed in (3.20) and (3.21), we can conclude that

$$\begin{split} I_{2} &\leq \frac{MM_{0}}{\Gamma(1+q)} \left(\frac{M_{1}}{(1+a)^{1-q_{1}}} (t_{2}-t_{1})^{(1+a)(1-q_{1})} + \frac{\overline{n}r(t_{2}-t_{1})^{q}}{q} \right), \\ I_{3} &\leq \frac{MM_{0}}{\Gamma(1+q)} \left[\left(\int_{0}^{t_{1}} \left((t_{1}-s)^{q-1} - (t_{2}-s)^{q-1} \right)^{1/(1-q_{1})} ds \right)^{1-q_{1}} \|m\|_{L^{1/q_{1}}[0,t_{1}]} \right. \\ &\quad \left. + \overline{n}r \int_{0}^{t_{1}} \left((t_{1}-s)^{q-1} - (t_{2}-s)^{q-1} \right) ds \right] \\ &\leq \frac{MM_{0}}{\Gamma(1+q)} \left[M_{1} \left(\int_{0}^{t_{1}} \left((t_{1}-s)^{a} - (t_{2}-s)^{a} \right) ds \right)^{1-q_{1}} \right. \\ &\quad \left. + \overline{n}r \left(\frac{(t_{2}-t_{1})^{q}}{q} - \frac{t_{2}^{q}}{q} + \frac{t_{1}^{q}}{q} \right) \right] \\ &= \frac{MM_{0}}{\Gamma(1+q)} \left(\frac{M_{1}}{(1+a)^{1-q_{1}}} \left(t_{1}^{1+a} - t_{2}^{1+a} + (t_{2}-t_{1})^{1+a} \right)^{1-q_{1}} \\ &\quad \left. + \frac{\overline{n}r}{q} \left[(t_{2}-t_{1})^{q} - t_{2}^{q} + t_{1}^{q} \right] \right) \\ &\leq \frac{MM_{0}}{\Gamma(1+q)} \left(\frac{M_{1}}{(1+a)^{1-q_{1}}} (t_{2}-t_{1})^{(1+a)(1-q_{1})} + \frac{\overline{n}r}{q} (t_{2}-t_{1})^{q} \right). \end{split}$$

Hence $\lim_{t_2 \to t_1} I_2 = 0$ and $\lim_{t_2 \to t_1} I_3 = 0$.

On the other hand, (H2) implies that S'(t) for t > 0 is continuous in the uniform operator topology; then from the Lebesgue dominated convergence theorem, we get $\lim_{t_2 \to t_1} I_1 = 0$ and

$$\begin{split} \lim_{t_{2} \to t_{1}} I_{4} &\leq \lim_{t_{2} \to t_{1}} M \int_{0}^{t_{1}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) \left\| S'((t_{2} - s)^{q} \theta) - S'((t_{1} - s)^{q} \theta) \right\| \left\| f(s) \right\| d\theta ds \\ &\leq M \int_{0}^{t_{1}} \int_{0}^{\infty} \theta(t_{1} - s)^{q-1} h_{q}(\theta) \lim_{t_{2} \to t_{1}} \left\| S'((t_{2} - s)^{q} \theta) - S'((t_{1} - s)^{q} \theta) \right\| \left\| f(s) \right\| d\theta ds \\ &= 0. \end{split}$$

$$(3.27)$$

Consequently, $|h(t_2)-h(t_1)| \to 0$ independently of $x \in \mathcal{B}_r$ as $t_2 \to t_1$, which means that $\Phi(\mathcal{B}_r)$ is equicontinuous.

Step 4 (For each $t \in [0, b]$, $V(t) = \{(\Phi x)(t), x \in B_r\}$ is relatively compact in X). Obviously, $V(0) = \{x_0\}$ is relatively compact in X. Let 0 < t < b be fixed. For $x \in B_r$ and $h \in \Phi x$, there exists $f \in N_{F,x}$ such that

$$h(t) = \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta + \lim_{\lambda \to \infty} q \int_0^t \int_0^\infty \theta(t-s)^{q-1} h_q(\theta) S'((t-s)^q \theta) B_\lambda f(s) d\theta ds.$$
(3.28)

For arbitrary $\epsilon \in (0, t)$ and $\delta > 0$, define an operator $F_{\epsilon, \delta}$ on \mathcal{B}_r by

$$(F_{\epsilon,\delta}x)(t) = \int_{\delta}^{\infty} h_{q}(\theta)S'(t^{q}\theta)x_{0}d\theta$$

$$+ \lim_{\lambda \to \infty} q \int_{0}^{t-\epsilon} \int_{\delta}^{\infty} \theta(t-s)^{q-1}h_{q}(\theta)S'((t-s)^{q}\theta)B_{\lambda}f(s)d\theta ds$$

$$= \int_{\delta}^{\infty} h_{q}(\theta)S'(t^{q}\delta)S'((t^{q}\theta) - t^{q}\delta)x_{0}d\theta$$

$$+ \lim_{\lambda \to \infty} q \int_{0}^{t-\epsilon} \int_{\delta}^{\infty} \theta(t-s)^{q-1}h_{q}(\theta)S'(\epsilon^{q}\delta)S'((t-s)^{q}\theta - \epsilon^{q}\delta)B_{\lambda}f(s)d\theta ds$$

$$= S'(t^{q}\delta) \int_{\delta}^{\infty} h_{q}(\theta)S'((t^{q}\theta) - t^{q}\delta)x_{0}d\theta$$

$$+ S'(\epsilon^{q}\delta) \lim_{\lambda \to \infty} q \int_{0}^{t-\epsilon} \int_{\delta}^{\infty} \theta(t-s)^{q-1}h_{q}(\theta)S'((t-s)^{q}\theta - \epsilon^{q}\delta)B_{\lambda}f(s)d\theta ds.$$
(3.29)

Then from the compactness of S'(t), t > 0, we get that the set $V_{\epsilon,\delta}(t) = \{(F_{\epsilon,\delta}x)(t), x \in \mathcal{B}_r\}$ is relatively compact in X for each $\epsilon \in (0, t)$ and $\delta > 0$. Moreover, for every $x \in \mathcal{B}_r$, we have

$$\begin{split} |(\Phi x)(t) - (F_{\epsilon,\delta}x)(t)| &= \left| \int_{0}^{\delta} h_{q}(\theta) S'(t^{q}\theta) x_{0} d\theta \right| \\ &+ \left| \lim_{\lambda \to \infty} q \int_{0}^{t} \int_{0}^{\delta} \theta(t-s)^{q-1} h_{q}(\theta) S'((t-s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ \lim_{\lambda \to \infty} q \int_{0}^{t-\epsilon} \int_{\delta}^{\infty} \theta(t-s)^{q-1} h_{q}(\theta) S'((t-s)^{q}\theta) B_{\lambda}f(s) d\theta ds \\ &- \lim_{\lambda \to \infty} q \int_{0}^{t-\epsilon} \int_{\delta}^{\infty} \theta(t-s)^{q-1} h_{q}(\theta) S'((t-s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &\leq M_{0} |x_{0}| \int_{0}^{\delta} h_{q}(\theta) d\theta \\ &+ q \left| \lim_{\lambda \to \infty} \int_{0}^{t} \int_{0}^{\delta} \theta(t-s)^{q-1} h_{q}(\theta) S'((t-s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &+ q \left| \lim_{\lambda \to \infty} \int_{t-\epsilon}^{t} \int_{\delta}^{\infty} \theta(t-s)^{q-1} h_{q}(\theta) S'((t-s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &\leq M_{0} |x_{0}| \int_{0}^{\delta} h_{q}(\theta) d\theta + q M M_{0} \int_{0}^{t} (t-s)^{q-1} |f(s)| ds \int_{0}^{\delta} \theta h_{q}(\theta) d\theta \\ &+ q M M_{0} \int_{t-\epsilon}^{t} (t-s)^{q-1} |f(s)| ds \int_{0}^{\infty} \theta h_{q}(\theta) d\theta. \end{split}$$

$$(3.30)$$

In view of (3.21), we have

$$\begin{split} |(\Phi x)(t) - (F_{e,\delta}x)(t)| \\ &\leq M_0 |x_0| \int_0^{\delta} h_q(\theta) d\theta + q M M_0 \int_0^{\delta} \theta h_q(\theta) d\theta \left(\frac{M_1}{(1+a)^{1-q_1}} b^{(1+a)(1-q_1)} + \frac{\overline{n}r b^q}{q} \right) \\ &+ \frac{q M M_0}{\Gamma(1+q)} \left[\left(\int_{t-e}^t (t-s)^{(q-1)/(1-q_1)} ds \right)^{1-q_1} \|m\|_{L^{1/q_1}[t-e,t]} + \overline{n}r \int_{t-e}^t (t-s)^{q-1} ds \right] \\ &\leq M_0 |x_0| \int_0^{\delta} h_q(\theta) d\theta + q M M_0 \int_0^{\delta} \theta h_q(\theta) d\theta \left(\frac{M_1}{(1+a)^{1-q_1}} b^{(1+a)(1-q_1)} + \frac{\overline{n}r b^q}{q} \right) \\ &+ \frac{q M M_0}{\Gamma(1+q)} \left(\frac{M_1}{(1+a)^{1-q_1}} e^{(1+a)(1-q_1)} + \frac{\overline{n}r e^q}{q} \right). \end{split}$$
(3.31)

From $\lim_{\delta \to 0} \int_0^{\delta} h_q(\theta) d\theta = 0$ and $\lim_{\delta \to 0} \int_0^{\delta} \theta h_q(\theta) d\theta = 0$, we get that there are relatively compact sets arbitrarily close to the set V(t), t > 0. Hence the set V(t), t > 0, is also relatively compact in *X*.

Step 5 (Φ has a closed graph). Let $x_n \to x_*$, $h_n \in \Phi x_n$, and $h_n \to h_*$ as $n \to \infty$; we will prove that $h_* \in \Phi x_*$. $h_n \in \Phi x_n$ means that there exists $f_n \in N_{F,x_n}$ such that

$$h_n(t) = \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta + \lim_{\lambda \to \infty} q \int_0^t \int_0^\infty \theta(t-s)^{q-1} h_q(\theta) S'\big((t-s)^q \theta\big) B_\lambda f_n(s) d\theta ds.$$
(3.32)

We must prove that there exists $f_* \in N_{F,x_*}$ such that

$$h_*(t) = \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta + \lim_{\lambda \to \infty} q \int_0^t \int_0^\infty \theta(t-s)^{q-1} h_q(\theta) S'((t-s)^q \theta) B_\lambda f_*(s) d\theta ds.$$
(3.33)

Consider the linear continuous operator \mathcal{T} : $L^1([0,b],X) \rightarrow C([0,b],X)$ defined by

$$(\mathcal{T}f)(t) = \lim_{\lambda \to \infty} q \int_0^t \int_0^\infty \theta(t-s)^{q-1} h_q(\theta) S'((t-s)^q \theta) B_\lambda f(s) d\theta ds.$$
(3.34)

We can easily see that τ is continuous. On the other hand,

$$\left| \left(h_n(t) - \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta \right) - \left(h_*(t) - \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta \right) \right|$$

$$\leq \|h_n - h_*\| \longrightarrow 0, \quad \text{as } n \longrightarrow 0.$$
(3.35)

From Theorem 2.13, it follows that $\mathcal{T} \circ N_F$ is a closed graph operator. Moreover, we have that

$$h_n - \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta \in \mathcal{T}(N_{F,x_n}).$$
(3.36)

Since $x_n \to x_*$, it follows from Theorem 2.13 that there exists $f_* \in N_{F,x_*}$ such that

$$h_{*}(t) - \int_{0}^{\infty} h_{q}(\theta) S'(t^{q}\theta) x_{0} d\theta = \lim_{\lambda \to \infty} q \int_{0}^{t} \int_{0}^{\infty} \theta(t-s)^{q-1} h_{q}(\theta) S'\big((t-s)^{q}\theta\big) B_{\lambda}f_{*}(s) d\theta ds.$$
(3.37)

Thus,

$$h_{*}(t) = \int_{0}^{\infty} h_{q}(\theta) S'(t^{q}\theta) x_{0} d\theta + \lim_{\lambda \to \infty} q \int_{0}^{t} \int_{0}^{\infty} \theta(t-s)^{q-1} h_{q}(\theta) S'((t-s)^{q}\theta) B_{\lambda} f_{*}(s) d\theta ds.$$

$$(3.38)$$

This implies that $h_* \in \Phi x_*$.

Therefore Φ is a completely continuous multivalued map, u.s.c. with convex closed values. In order to prove that Φ has a fixed point, we need one more step.

Step 6 (The set $U = \{x \in C_0 : \delta x \in \Phi x, \text{ for some } \delta > 1\}$ is bounded). Let $x \in U$; then $\delta x \in \Phi x$ for some $\delta > 1$. Thus there exists $f \in N_{F,x}$ such that for $t \in [0, b]$,

$$x(t) = \frac{1}{\delta} \int_0^\infty h_q(\theta) S'(t^q \theta) x_0 d\theta + \lim_{\lambda \to \infty} \frac{q}{\delta} \int_0^t \int_0^\infty \theta(t-s)^{q-1} h_q(\theta) S'\big((t-s)^q \theta\big) B_\lambda f(s) d\theta ds.$$
(3.39)

From (H4), for each $t \in [0, b]$ we have

$$\begin{aligned} |x(t)| &= \left| \frac{1}{\delta} \int_{0}^{\infty} h_{q}(\theta) S'(t^{q}\theta) x_{0} d\theta + \lim_{\lambda \to \infty} \frac{q}{\delta} \int_{0}^{t} \int_{0}^{\infty} \theta(t-s)^{q-1} h_{q}(\theta) S'((t-s)^{q}\theta) B_{\lambda}f(s) d\theta ds \right| \\ &\leq M_{0} |x_{0}| + \frac{q M M_{0}}{\Gamma(1+q)} \int_{0}^{t} (t-s)^{q-1} |f(s)| ds \\ &\leq M_{0} |x_{0}| + \frac{q M M_{0}}{\Gamma(1+q)} \int_{0}^{t} (t-s)^{q-1} m(s) ds + \frac{q \overline{n} M M_{0}}{\Gamma(1+q)} \int_{0}^{t} (t-s)^{q-1} |x(s)| ds \\ &\leq M_{0} |x_{0}| + \frac{q M M_{0} M_{1}}{\Gamma(1+q)(1+a)^{1-q_{1}}} b^{(1+a)(1-q_{1})} + \frac{q \overline{n} M M_{0}}{\Gamma(1+q)} \int_{0}^{t} (t-s)^{q-1} |x(s)| ds \\ &\leq \overline{a} + \overline{b} \int_{0}^{t} (t-s)^{q-1} |x(s)| ds, \end{aligned}$$

$$(3.40)$$

where $\overline{a} = M_0 |x_0| + (qMM_0M_1/\Gamma(1+q)(1+a)^{(1-q_1)})b^{(1+a)(1-q_1)}, \overline{b} = q\overline{n}MM_0/\Gamma(1+q).$ Then from Corollary 2.11, we have

$$|x(t)| \le \overline{a} E_q \Big(\overline{b} \Gamma(q) t^q \Big). \tag{3.41}$$

Therefore, we obtain that

$$\|x\| \le \overline{a} E_q \Big(\overline{b} \Gamma(q) b^q \Big). \tag{3.42}$$

This shows that *U* is bounded.

As a consequence of Theorem 2.14, we conclude that Φ has a fixed point which is the integral solution of problem (1.1). This completes the proof.

4. An Example

As an application of our results we consider the following fractional differential inclusions of the form

$$D^{q}u(t,z) \in \frac{\partial^{2}}{\partial z^{2}}u(t,z) + G(t,u(t,z)), \quad z \in [0,\pi], \quad t \in (0,b],$$

$$u(t,0) = u(t,\pi) = 0, \quad t \in [0,b],$$

$$u(0,z) = u_{0}, \quad z \in [0,\pi],$$
(4.1)

where b > 0, $G : [0, b] \times X \rightarrow \mathcal{P}(X)$ satisfies semi-continuous assumptions (H3) and (H4).

Consider $X = C([0, \pi]; \mathbf{R})$ endowed with the supnorm and the operator $A : D(A) \subset X \to X$ defined by

$$D(A) = \left\{ u \in C^2([0,\pi]; \mathbf{R}) : u(t,0) = u(t,\pi) = 0 \right\}, \quad Au = \frac{\partial^2}{\partial z^2} u(t,z).$$
(4.2)

Now, we have $\overline{D(A)} = \{u \in X : u(t, 0) = u(t, \pi) = 0\} \neq X$. As we know from [17] that *A* satisfies the Hille-Yosida condition with $(0, +\infty) \subseteq \rho(A)$ and $\lambda > 0$, $||R(\lambda, A)|| \leq 1/\lambda$. Hence, operator *A* satisfies (H1), (H2), and $M = M_0 = 1$.

Then the system (4.1) can be reformulated as

$$D^{q}x(t) \in Ax(t) + F(t, x(t)), \quad t \in [0, b],$$

$$x(0) = u_{0},$$

(4.3)

where x(t)(z) = u(t, z), F(t, x(t))(z) = G(t, u(t, z)).

If we assume that F satisfies (H3) and (H4), then all conditions of Theorem 3.7 are satisfied and we deduce (4.1) has at least one integral solution.

Acknowledgments

This work was partially supported by National Natural Science Foundation of China (11171122) and Anhui Province College Natural Science Foundation (KJ2012A265, KJ2012B187, KJ2011B176).

References

 K. B. Oldham and J. Spanier, *The Fractional Calculus*, vol. 111, Academic Press, New York, NY, USA, 1974, Theory and applications of differentiation and integration to arbitrary order, With an annotated chronological bibliography by Bertram Ross, Mathematics in Science and Engineering.

- [2] K. S. Miller and B. Ross, An Introduction to the Fractional Calculus and Fractional Differential Equations, A Wiley-Interscience Publication, John Wiley & Sons, New York, NY, USA, 1993.
- [3] I. Podlubny, *Fractional Differential Equations*, vol. 198 of *Mathematics in Science and Engineering*, Academic Press, San Diego, Calif, USA, 1999, An introduction to fractional derivatives, fractional differential equations, to methods of their solution and some of their applications.
- [4] D. Delbosco and L. Rodino, "Existence and uniqueness for a nonlinear fractional differential equation," *Journal of Mathematical Analysis and Applications*, vol. 204, no. 2, pp. 609–625, 1996.
- [5] S. Aizicovici and M. McKibben, "Existence results for a class of abstract nonlocal Cauchy problems," Nonlinear Analysis: Theory, Methods & Applications, vol. 39, no. 5, pp. 649–668, 2000.
- [6] K. Diethelm and N. J. Ford, "Analysis of fractional differential equations," Journal of Mathematical Analysis and Applications, vol. 265, no. 2, pp. 229–248, 2002.
- [7] S. D. Eidelman and A. N. Kochubei, "Cauchy problem for fractional diffusion equations," *Journal of Differential Equations*, vol. 199, no. 2, pp. 211–255, 2004.
- [8] V. Daftardar-Gejji and H. Jafari, "Analysis of a system of nonautonomous fractional differential equations involving Caputo derivatives," *Journal of Mathematical Analysis and Applications*, vol. 328, no. 2, pp. 1026–1033, 2007.
- [9] Y.-K. Chang and J. J. Nieto, "Some new existence results for fractional differential inclusions with boundary conditions," *Mathematical and Computer Modelling*, vol. 49, no. 3-4, pp. 605–609, 2009.
- [10] R. P. Agarwal, M. Benchohra, and S. Hamani, "A survey on existence results for boundary value problems of nonlinear fractional differential equations and inclusions," *Acta Applicandae Mathematicae*, vol. 109, no. 3, pp. 973–1033, 2010.
- [11] M. M. El-Borai, "Some probability densities and fundamental solutions of fractional evolution equations," Chaos, Solitons and Fractals, vol. 14, no. 3, pp. 433–440, 2002.
- [12] Y. Zhou and F. Jiao, "Existence of mild solutions for fractional neutral evolution equations," Computers & Mathematics with Applications, vol. 59, no. 3, pp. 1063–1077, 2010.
- [13] Y. Zhou and F. Jiao, "Nonlocal Cauchy problem for fractional evolution equations," *Nonlinear Analysis: Real World Applications*, vol. 11, no. 5, pp. 4465–4475, 2010.
- [14] J. Wang and Y. Zhou, "A class of fractional evolution equations and optimal controls," Nonlinear Analysis: Real World Applications, vol. 12, no. 1, pp. 262–272, 2011.
- [15] J. Cao, Q. Yang, and Z. Huang, "Optimal mild solutions and weighted pseudo-almost periodic classical solutions of fractional integro-differential equations," *Nonlinear Analysis: Theory, Methods & Applications*, vol. 74, no. 1, pp. 224–234, 2011.
- [16] Z. Yan, "Controllability of fractional-order partial neutral functional integrodifferential inclusions with infinite delay," *Journal of the Franklin Institute*, vol. 348, no. 8, pp. 2156–2173, 2011.
- [17] G. Da Prato and E. Sinestrari, "Differential operators with nondense domain," Annali della Scuola Normale Superiore di Pisa. Classe di Scienze, vol. 14, no. 2, pp. 285–344, 1987.
- [18] H. R. Thieme, ""Integrated semigroups" and integrated solutions to abstract Cauchy problems," Journal of Mathematical Analysis and Applications, vol. 152, no. 2, pp. 416–447, 1990.
- [19] H. R. Thieme, "Semiflows generated by Lipschitz perturbations of non-densely defined operators," Differential and Integral Equations, vol. 3, no. 6, pp. 1035–1066, 1990.
- [20] M. Adimy, H. Bouzahir, and K. Ezzinbi, "Existence for a class of partial functional differential equations with infinite delay," *Nonlinear Analysis: Theory, Methods & Applications*, vol. 46, no. 1, pp. 91–112, 2001.
- [21] K. Ezzinbi and J. H. Liu, "Nondensely defined evolution equations with nonlocal conditions," Mathematical and Computer Modelling, vol. 36, no. 9-10, pp. 1027–1038, 2002.
- [22] M. Benchohra, E. P. Gatsori, J. Henderson, and S. K. Ntouyas, "Nondensely defined evolution impulsive differential inclusions with nonlocal conditions," *Journal of Mathematical Analysis and Applications*, vol. 286, no. 1, pp. 307–325, 2003.
- [23] N. Abada, M. Benchohra, and H. Hammouche, "Existence and controllability results for nondensely defined impulsive semilinear functional differential inclusions," *Journal of Differential Equations*, vol. 246, no. 10, pp. 3834–3863, 2009.
- [24] J. Wang and Y. Zhou, "Existence and controllability results for fractional semilinear differential inclusions," Nonlinear Analysis: Real World Applications, vol. 12, no. 6, pp. 3642–3653, 2011.
- [25] W. Arendt, "Vector-valued Laplace transforms and Cauchy problems," Israel Journal of Mathematics, vol. 59, no. 3, pp. 327–352, 1987.
- [26] H. Kellerman and M. Hieber, "Integrated semigroups," Journal of Functional Analysis, vol. 84, no. 1, pp. 160–180, 1989.

- [27] W. Arendt, "Resolvent positive operators," *Proceedings of the London Mathematical Society*, vol. 54, no. 2, pp. 321–349, 1987.
- [28] H. Ye, J. Gao, and Y. Ding, "A generalized Gronwall inequality and its application to a fractional differential equation," *Journal of Mathematical Analysis and Applications*, vol. 328, no. 2, pp. 1075–1081, 2007.
- [29] K. Deimling, Multivalued Differential Equations, vol. 1 of de Gruyter Series in Nonlinear Analysis and Applications, Walter de Gruyter &, Berlin, Germany, 1992.
- [30] A. Lasota and Z. Opial, "An application of the Kakutani-Ky-Fan theorem in the theory of ordinary differential equations," Bulletin de l'Académie Polonaise des Sciences, Série des Sciences Mathématiques, Astronomiques et Physiques, vol. 13, pp. 781–786, 1965.
- [31] M. Martelli, "A Rothe's type theorem for non-compact acyclic-valued maps," Bollettino della Unione Matematica Italiana, vol. 11, no. 4, pp. 70–76, 1975.
- [32] F. Mainardi, P. Paradisi, and R. Gorenflo, "Probability distributions generated by fractional diffusion equations," in *Econophysics: An Emerging Science*, J. Kertesz and I. Kondor, Eds., Kluwer, Dordrecht, The Netherlands, 2000.



Advances in **Operations Research**

The Scientific

World Journal





Mathematical Problems in Engineering

Hindawi

Submit your manuscripts at http://www.hindawi.com



Algebra



Journal of Probability and Statistics



International Journal of Differential Equations





International Journal of Combinatorics

Complex Analysis











Journal of Function Spaces



Abstract and Applied Analysis





Discrete Dynamics in Nature and Society