# Research Article

# **Global Existence and Boundedness of Solutions to a Second-Order Nonlinear Differential System**

# Changjian Wu,<sup>1</sup> Shushuang Hao,<sup>2</sup> and Changwei Xu<sup>3</sup>

<sup>1</sup> Zhujiang College, South China Agricultural University, Guangdong, Conghua 510900, China

<sup>2</sup> Department of Information Engineering, Huanghe Science and Technology College, Henan, Zhengzhou 450063, China

<sup>3</sup> College of Science, Zhongyuan University of Technology, Henan, Zhengzhou 450006, China

Correspondence should be addressed to Shushuang Hao, hss9811@yahoo.com.cn

Received 25 March 2012; Accepted 2 August 2012

Academic Editor: Carla Roque

Copyright © 2012 Changjian Wu et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

We investigate the global existence and boundedness of solutions to a second-order nonlinear differential system.

# **1. Introduction**

In this paper, we study the nonlinear system

$$x' = \frac{1}{a(x)} [c(y) - b(x)],$$
  

$$y' = -a(x) [h(x) - e(t)],$$
(1.1)

where  $a : R \to (0, \infty)$ ,  $b, c, h : R \to R$ , and  $e : R \to R$  are continuous.

As a particular case of (1.1) we have well-known Lienard equation as follows:

$$x'' + f(x)x' + h(x) = e(t).$$
(1.2)

with a(x) = 1,  $b(x) = \int_0^x f(s)ds$ , c(x) = x,  $x \in R$  and the second-order nonlinear differential equation as follows:

$$x'' + (f(x) + g(x)x')x' + h(x) = e(t)$$
(1.3)

for  $a(x) = \exp(\int_0^x g(s)ds), b(x) = \int_0^x a(s)f(s)ds, c(x) = x, x \in R.$ 

System (1.1) can be regarded as a mathematical model for many phenomena in applied sciences (theory of feedback electronic circuits, motion of a mass-spring system). It has been investigated by several authors, compare [1–4] and the citations therein.

The purpose of this paper is to present new results on the global existence and boundedness of solutions for the system (1.1). The obtained results improve the recent results in [1, 5]. Our paper is divided into two section. In Section 2, we prove the global existence of solutions for (1.1). In Section 3, we get some new results on boundedness of solutions for the system (1.1).

# 2. Global Existence

In this section, we will present new results on the global existence of solutions to system (1.1) under general conditions on the nonlinearities.

Let us first define

$$C(y) = \int_0^y c(s)ds, \qquad H(x) = \int_0^x a^2(s)h(s)ds.$$
(2.1)

Then, we have the following.

Theorem 2.1. Assume that

(i) there exists some  $K \ge 0$ , such that

$$sgn(x)H(x) + K \ge 0, \quad x \in R,$$
  

$$sgn(y)C(y) + K \ge 0, \quad y \in R,$$
(2.2)

(ii) there exist some  $N \ge 0$  and Q > 0, such that

$$|H(x)| < Q, \quad |x| > N,$$
  
 $|C(y)| < Q, \quad |y| > N,$  (2.3)

- (iii)  $\lim_{|y|\to\infty} \operatorname{sgn}(y)C(y) = Q, \\ \lim_{|x|\to\infty} \left[1/(Q \operatorname{sgn}(x)H(x)) + \operatorname{sgn}(x)b(x)\right] = \infty,$
- (iv) there exist two positive functions  $\mu, \omega \in C([0, K + Q), (0, \infty))$  such that

$$a(x)|c(y)| \le \min\{\mu(\operatorname{sgn}(x)H(x) + K) + \omega(\operatorname{sgn}(x)H(x) + K), \\ \mu(\operatorname{sgn}(y)C(y) + K) + \omega(\operatorname{sgn}(y)C(y) + K)\}, \\ |x| > N, |y| > N,$$
(2.4)

(v) 
$$sgn(x)a(x)b(x)h(x) \ge -[\mu(sgn(x)H(x) + K) + \omega(sgn(x)H(x) + K)], |x| > N$$
 and  $|h(x)| \le M < \infty, x \in R$ .

If

$$\int_{0}^{K+Q} \frac{ds}{\mu(s) + \omega(s)} = \infty, \qquad (2.5)$$

then every solution of (1.1) exists globally.

*Proof.* Due that  $a : R \to (0, \infty)$ ,  $b, c, h : R \to R$  and  $e : R \to R$  are continuous, by Peano's Existence Theorem [6], we have that the system (1.1) with any initial data  $(x_0, y_0)$  possesses a solution (x(t), y(t)) on [0, T) for some maximal T > 0. If  $T < \infty$ , one has

$$\lim_{t \to T} (|x(t)| + |y(t)|) = \infty.$$
(2.6)

First, assume that  $\lim_{t\to T} |y(t)| = \infty$ .

Since y(t) is continuous, there exists  $0 \le T_0 < T$  such that

$$|y(t)| > N, \quad t \in [T_0, T).$$
 (2.7)

Take  $V_1(t, x, y) = \text{sgn}(y)C(y) + K$ ,  $t \in R_+$ ,  $x, y \in R$ . Differentiating  $V_1(t, x, y)$  with respect to t along solution (x(t), y(t)) of (1.1), we have

$$\frac{dV_1}{dt} = \operatorname{sgn}(y) \left[ -a(x)c(y)h(x) + a(x)c(y)e(t) \right] 
\leq (|h(x)| + |e(t)|)a(x)|c(y)| 
\leq (M + |e(t)|) \left[ \mu(\operatorname{sgn}(y)C(y) + K) + \omega(\operatorname{sgn}(y)C(y) + K) \right], 
t \in [T_0, T).$$
(2.8)

Since  $0 \le \operatorname{sgn}(y(t))C(y(t)) + K < Q + K, t \in [T_0, T)$ , we obtain

$$\frac{dV_1(t)}{\mu(V_1(t)) + \omega(V_1(t))} \le (M + |e(t)|)dt, \quad t \in [T_0, T).$$
(2.9)

We denote that  $V_1(t) = V_1(t, x(t), y(t))$ .

Since  $\lim_{|y|\to\infty} \operatorname{sgn}(y)C(y) = Q$ ,  $\int_0^{K+Q} (ds/(\mu(s) + \omega(s))) = \infty$ , y(t), C(y) are continuous, there exists  $T_0 \le t_1 < t_2 < T$  such that

$$\int_{V_1(t_1)}^{V_1(t_2)} \frac{ds}{\mu(s) + \omega(s)} > M \int_0^T dt + \int_0^T |e(t)| dt.$$
(2.10)

Integrating (2.9) on  $[t_1, t_2]$  with respect to t and using the above relation, we obtain the following contradiction:

$$M\int_{0}^{T} dt + \int_{0}^{T} |e(t)| dt < \int_{V_{1}(t_{1})}^{V_{1}(t_{2})} \frac{ds}{\mu(s) + \omega(s)} = \int_{t_{1}}^{t_{2}} \frac{dV_{1}(t)}{\mu(V_{1}(t)) + \omega(V_{1}(t))}$$

$$\leq \int_{t_{1}}^{t_{2}} (M + |e(t)|) dt \leq M \int_{0}^{T} dt + \int_{0}^{T} |e(t)| dt.$$
(2.11)

Thus, there exists an M > 0 such that

$$|y(t)| \le M, \quad t \in [0,T).$$
 (2.12)

Second, by the result above, we have  $\lim_{t\to T} |x(t)| = \infty$ .

If  $\lim_{|x|\to\infty} (1/(Q - \operatorname{sgn}(x)H(x))) = \infty$ , that is,  $\lim_{|x|\to\infty} \operatorname{sgn}(x)H(x) = Q$ , we set

$$V_2(t, x, y) = \operatorname{sgn}(x)H(x) + K, \quad t \in R_+, \ x, y \in R.$$
(2.13)

Since x(t) is continuous, there exists  $0 \le T_1 < T$  such that

$$|x(t)| > N, \quad t \in [T_1, T).$$
 (2.14)

Differentiating  $V_2(t, x, y)$  with respect to *t* along solution (x(t), y(t)) of (1.1), we have

$$\frac{dV_2}{dt} = \operatorname{sgn}(x) \left[ a(x)c(y)h(x) - a(x)b(x)h(x) \right]$$
  

$$\leq (M+1) \left[ \mu(\operatorname{sgn}(x)H(x) + K) + \omega(\operatorname{sgn}(x)H(x) + K) \right], \qquad (2.15)$$
  

$$t \in [T_1, T).$$

Since  $0 \leq \text{sgn}(x(t))H(x(t)) + K < Q + K$ ,  $t \in [T_1, T)$ , we obtain

$$\frac{dV_2(t)}{\mu(V_2(t)) + \omega(V_2(t))} \le (M+1)dt, \quad t \in [T_1, T).$$
(2.16)

We denote  $V_2(t) = V_2(t, x(t), y(t))$ .

Since  $\lim_{|x|\to\infty} \operatorname{sgn}(x)H(x) = Q$ ,  $\int_0^{K+Q} (ds/(\mu(s) + \omega(s))) = \infty$ , x(t), H(x) are continuous, there exists  $T_1 \le t_3 < t_4 < T$  such that

$$\int_{V_2(t_3)}^{V_2(t_4)} \frac{ds}{\mu(s) + \omega(s)} > (M+1) \int_0^T dt.$$
(2.17)

Integrating (2.16) on  $[t_3, t_4]$  with respect to *t* and using the above relation, we obtain the contradiction as follows:

$$(M+1)\int_{0}^{T} dt < \int_{V_{2}(t_{3})}^{V_{2}(t_{4})} \frac{ds}{\mu(s) + \omega(s)} = \int_{t_{3}}^{t_{4}} \frac{dV_{2}(t)}{\mu(V_{2}(t)) + \omega(V_{2}(t))}$$

$$\leq \int_{t_{3}}^{t_{4}} (M+1)dt \leq (M+1)\int_{0}^{T} dt.$$
(2.18)

So consider  $\lim_{|x|\to\infty} (1/(Q - \operatorname{sgn}(x)H(x))) < \infty$ . By (iii), we have  $\lim_{|x|\to\infty} \operatorname{sgn}(x)b(x) = \infty$ . Set

$$W(t, x, y) = x, \quad t \in R_+, \ x, y \in R.$$
 (2.19)

Then, along solutions to (1.1) we have

$$\frac{dW}{dt} = \frac{1}{a(x)} [c(y) - b(x)].$$
(2.20)

If  $\lim_{t\to T} x(t) = \infty$ , we deduce that there exist  $x_1$  and  $x_2$  such that  $x_0 < x_1 < x_2$  and

$$\frac{dW}{dt} < 0, \qquad x_1 \le x \le x_2, \qquad |y| \le M.$$
(2.21)

Then, by the continuity of the solution, there exist  $0 < t_1 < t_2 < T$  such that  $x(t_1) = x_1$ ,  $x(t_2) = x_2$ . Integrating (2.21) on  $[t_1, t_2]$ , we have

$$W(t_1, x(t_1), y(t_1)) = x_1 > x_2 = W(t_2, x(t_2), y(t_2)).$$
(2.22)

This contradicts  $x_1 < x_2$ . Hence x(t) is bounded from above.

Similarly, if  $\lim_{t\to T} x(t) = -\infty$ , we can obtain a contradiction by setting W(t, x, y) = -x. Thus, it follows that x(t) is also bounded from above. This forces  $T = \infty$  and completes the proof of Theorem 2.1.

*Example 2.2.* Consider the following nonlinear system:

$$x' = \frac{\sqrt{1+x^2}}{1+y^2},$$

$$y' = -\frac{1}{\sqrt{1+x^2}} + \frac{t^2}{\sqrt{1+x^2}}.$$
(2.23)

Set  $a(x) = 1/\sqrt{1+x^2}$ , b(x) = 0,  $c(y) = 1/(1+y^2)$ , h(x) = 1,  $e(t) = t^2$ . Then we have

$$C(y) = \arctan y, \qquad H(x) = \arctan x.$$
 (2.24)

Take K = N = 0,  $Q = \pi/2$ , and  $\mu(\theta) = \omega(\theta) = \cos \theta/2$ ,  $\theta \in [0, \pi/2)$ . Note that

$$a(x)|c(y)| = \frac{1}{\sqrt{1+x^2}} \cdot \frac{1}{1+y^2} \le \min\left\{\frac{1}{\sqrt{1+x^2}}, \frac{1}{\sqrt{1+y^2}}\right\}$$
  
= min{ $\mu(\operatorname{sgn}(x) \arctan x + K) + \omega(\operatorname{sgn}(x) \arctan x + K),$   
 $\mu(\operatorname{sgn}(y) \arctan y + K) + \omega(\operatorname{sgn}(y) \arctan y + K)$ }  
(2.25)

sgn(x)a(x)b(x)h(x) = 0, |h(x)| = 1 and

$$\int_{0}^{\pi/2} \frac{d\theta}{\mu(\theta) + \omega(\theta)} = \int_{0}^{\pi/2} \frac{d\theta}{\cos \theta} \ge \frac{1}{2} \int_{0}^{1} \frac{dx}{1 - x} = \infty.$$
(2.26)

Applying Theorem 2.1, we know that every solution of (2.23) exists globally. Observe that the theorem and corollary in [5] cannot be used in the present case.

**Theorem 2.3.** *Assume that* 

(i) there exists some  $K \ge 0$ , such that

$$H(x) + K \ge 0, \quad x \in R,$$
  

$$C(y) + K \ge 0, \quad y \in R,$$
(2.27)

(ii) there exist some  $N \ge 0$  and Q > 0, such that

$$|H(x)| < Q, |x| > N,$$
  
 $|C(y)| < Q, |y| > N,$  (2.28)

(iii)  $\lim_{|y|\to\infty} C(y) = Q$ ,  $\lim_{|x|\to\infty} [1/(Q - H(x)) + \operatorname{sgn}(x)b(x)] = \infty$ , (iv) there exist two positive functions  $\mu, \omega \in C([0, K + Q), (0, \infty))$  such that

$$a(x)|c(y)| \le \min\{\mu(H(x) + K) + \omega(H(x) + K), \\ \mu(C(y) + K) + \omega(C(y) + K)\}, \\ |x| > N, |y| > N,$$
(2.29)

(v) 
$$a(x)b(x)h(x) \ge -[\mu(H(x)+K)+\omega(H(x)+K)], |x| > N \text{ and } |h(x)| \le M < \infty, x \in R.$$
  
If

$$\int_{0}^{K+Q} \frac{ds}{\mu(s) + \omega(s)} = \infty, \qquad (2.30)$$

then every solution of (1.1) exists globally.

*Proof.* The proof of Theorem 2.3 is similar to that of Theorem 2.1, so we omit it.

*Example 2.4.* Consider the following nonlinear system:

$$x' = \frac{2y}{(1+y^2)^2} + \frac{2y \ln(1+x^2)}{(1+y^2)^2},$$
  

$$y' = -\frac{2x}{(1+x^2)[1+\ln(1+x^2)]} + \frac{t^3}{1+\ln(1+x^2)}.$$
(2.31)

Set  $a(x) = 1/(1 + \ln(1 + x^2))$ , b(x) = 0,  $c(y) = 2y/(1 + y^2)^2$ ,  $h(x) = 2x/(1 + x^2)$ ,  $e(t) = t^3$ . Then we have  $C(y) = 1 - (1/(1 + y^2))$ ,  $H(x) = 1 - (1/(1 + \ln(1 + x^2)))$ . Take K = N = 0, Q = 1 and  $\mu(t) = \omega(t) = (1 - t)/2$ ,  $t \in [0, 1)$ . Note that

$$a(x)|c(y)| = \frac{1}{1+\ln(1+x^2)} \cdot \frac{2|y|}{(1+y^2)^2} \le \min\left\{\frac{1}{1+\ln(1+x^2)}, \frac{1}{1+y^2}\right\}$$
  
=  $\min\{\mu(H(x)+K) + \omega(H(x)+K), \mu(C(y)+K) + \omega(C(y)+K)\}.$  (2.32)

 $a(x)b(x)h(x) = 0, |h(x)| = 2|x|/(1+x^2) \le 1$  and

$$\int_{0}^{1} \frac{ds}{\mu(s) + \omega(s)} = \int_{0}^{1} \frac{ds}{1 - s} = \infty.$$
(2.33)

Applying Theorem 2.3, we know that every solution of (2.31) exists globally. Observe that the theorem and corollary in [5] cannot be uses in the present case.

## 3. Boundedness

In this section, we will present some results on the boundedness of solutions to (1.1) under general conditions on the nonlinearities.

#### **Theorem 3.1.** Assume that

(i) there exist functions  $f_1, f_2 \in C(R_+, R)$  such that

$$f_1(t) \le y'(t) = -a(x)[h(x) - e(t)] \le f_2(t), \quad x \in \mathbb{R}, \ t \in \mathbb{R}_+,$$
(3.1)

 $\begin{array}{l} and \mid \int_0^\infty f_1(t)dt \mid < \infty, \mid \int_0^\infty f_2(t)dt \mid < \infty, \\ (\text{ii}) \ \lim_{|x| \to \infty} \operatorname{sgn}(x)b(x) = \infty. \\ \text{If the solution } (x(t), y(t)) \ of \ (1.1) \ exists \ globally, \ then \ (x(t), y(t)) \ is \ bounded. \end{array}$ 

Proof. By (i), we have

$$f_1(t) \le y'(t) \le f_2(t), \quad x \in R, \ t \in R_+.$$
 (3.2)

Integrating (3.2) on [0, t] with respect to t, we have

$$\int_{0}^{t} f_{1}(s)ds \le y(t) - y_{0} \le \int_{0}^{t} f_{2}(s)ds.$$
(3.3)

Since  $|\int_0^\infty f_1(t)dt| < \infty$ ,  $|\int_0^\infty f_2(t)dt| < \infty$ . Thus, there exists a  $\Upsilon > 0$  such that

$$|y(t)| \le \Upsilon, \quad t \ge 0. \tag{3.4}$$

Set

$$W(t, x, y) = -x, \quad t \in R_+, \ x, y \in R.$$
 (3.5)

Then, along solutions to (1.1), we have

$$\frac{dW}{dt} = -\frac{1}{a(x)} [c(y) - b(x)].$$
(3.6)

If  $\lim_{t\to\infty} x(t) = -\infty$ , we deduce that there exist  $x_1$  and  $x_2$  such that  $x(0) > x_1 > x_2$  and

$$\frac{dW}{dt} < 0, \qquad x_2 \le x \le x_1, \qquad |y| \le Y.$$
(3.7)

Then, by the continuity of the solution, we have that there exist  $0 < t_1 < t_2 < \infty$  such that  $x(t_1) = x_1$  and  $x(t_2) = x_2$ . Integrating (3.7) on  $[t_1, t_2]$ , we get

$$W(t_1, x(t_1), y(t_1)) = -x_1 > -x_2 = W(t_2, x(t_2), y(t_2)).$$
(3.8)

This contradicts  $x_1 > x_2$ . Hence x(t) is bounded from below.

Similarly, if  $\lim_{t\to T} x(t) = \infty$ , we can obtain a contradiction by setting W(t, x, y) = x. Thus, it follows that x(t) is also bounded from above. This completes the proof of Theorem 3.1.

*Example 3.2.* Consider the following nonlinear system:

$$\begin{aligned} x' &= \frac{\sqrt{1+x^2}}{1+y^2} - x\sqrt{1+x^2}, \\ y' &= \frac{1}{\sqrt{1+x^2}} \cdot \frac{1}{1+t^2}. \end{aligned} \tag{3.9}$$

Set  $a(x) = 1/\sqrt{1+x^2}$ , b(x) = x,  $c(y) = 1/(1+y^2)$ , h(x) = 1,  $e(t) = 1 + (1/(1+t^2))$ . Then we have  $C(y) = \arctan y$  and  $H(x) = \arctan x$ . Take K = N = 0,  $Q = \pi/2$  and  $\mu(\theta) = \omega(\theta) = \cos \theta/2$ ,  $\theta \in [0, \pi/2)$ . Applying Theorem 2.1, we know that every solution of (3.9) exists globally.

Take  $f_1(t) = 0$ ,  $f_2(t) = 1/(1 + t^2)$ , we have

$$f_1(t) = 0 \le y'(t) \le f_2(t) = \frac{1}{1+t^2}, \quad x \in R, \ t \in R_+$$
 (3.10)

and  $\left|\int_{0}^{\infty} f_{2}(t)dt\right| = \pi/2 < \infty$ ,  $\lim_{|x|\to\infty} \operatorname{sgn}(x)b(x) = \lim_{|x|\to\infty} x \operatorname{sgn}(x) = \infty$ . Applying Theorem 3.1, we know that every solution of (3.9) is bounded.

#### Theorem 3.3. Assume that

(i) there exists some  $K \ge 0$ , such that

$$sgn(x)H(x) + K \ge 0, \quad x \in R,$$
  

$$sgn(y)C(y) + K \ge 0, \quad y \in R,$$
(3.11)

(ii) there exist some  $N \ge 0$  and Q > 0, such that

$$|H(x)| < Q, |x| > N,$$
  
 $|C(y)| < Q, |y| > N,$  (3.12)

(iii)  $\lim_{|y|\to\infty} \operatorname{sgn}(y)C(y) = Q$ ,  $\lim_{|x|\to\infty} [1/(Q - \operatorname{sgn}(x)H(x)) + \operatorname{sgn}(x)b(x)] = \infty$ , (iv) there exist two positive functions  $\mu, \omega \in C([0, K + Q), (0, \infty))$  such that

$$a(x)|c(y)| \le \min\{\mu(\operatorname{sgn}(x)H(x) + K) + \omega(\operatorname{sgn}(x)H(x) + K), \\ \mu(\operatorname{sgn}(y)C(y) + K) + \omega(\operatorname{sgn}(y)C(y) + K)\},$$
(3.13)  
$$|x| > N, \ |y| > N,$$

(v)  $\operatorname{sgn}(x)a(x)b(x)h(x) \ge 0$ , |x| > N and  $|h(x)| \le M < \infty$ ,  $x \in R$ , (vi)  $E = \int_0^\infty |e(t)|dt < \infty$ , and  $\int_0^{K+Q} (ds/(\mu(s) + \omega(s))) = \infty$ . If there exists g(x) such that

$$0 < \frac{a(x)}{|c(y) - b(x)|} \le g(x), \quad x, y \in R$$
(3.14)

and  $G = \int_{-\infty}^{\infty} g(x) |h(x)| dx < \infty$ , then every solution of (1.1) is bounded.

*Proof.* Let (x(t), y(t)) be a solution to (1.1) with initial data  $(x_0, y_0)$ . By Theorem 2.1, we have that (x(t), y(t)) exists globally. If (x(t), y(t)) is unbounded, we have

$$\lim_{t \to \infty} |x(t)| = \infty \quad \text{or} \quad \lim_{t \to \infty} |y(t)| = \infty.$$
(3.15)

First, assume that  $\lim_{t\to T} |y(t)| = \infty$ .

Since y(t) is continuous, there exists  $T_1 \ge 0$  such that

$$|y(t)| > N, \quad t \in [T_1, \infty).$$
 (3.16)

Take  $V_1(t, x, y) = \text{sgn}(y)C(y) + K$ ,  $t \in R_+$ ,  $x, y \in R$ . Differentiating  $V_1(t, x, y)$  with respect to t along solution (x(t), y(t)) of (1.1), we have

$$\frac{dV_{1}}{dt} = \operatorname{sgn}(y) \left[ -a(x)c(y)h(x) + a(x)c(y)e(t) \right] 
\leq (|h(x)| + |e(t)|)a(x)|c(y)| 
\leq (|h(x)| + |e(t)|) \left[ \mu(\operatorname{sgn}(y)C(y) + K) + \omega(\operatorname{sgn}(y)C(y) + K) \right], 
t \in [T_{1}, \infty).$$
(3.17)

Since  $0 \le \operatorname{sgn}(y(t))C(y(t)) + K < Q + K, t \in [T_1, \infty)$ , we obtain

$$\frac{dV_1(t)}{\mu(V_1(t)) + \omega(V_1(t))} \le (|h[x(t)]| + |e(t)|)dt, \quad t \in [T_1, \infty).$$
(3.18)

We denote  $V_1(t) = V_1(t, x(t), y(t))$ .

By (vi), there exists  $T_1 \le t_1 < t_2 < \infty$  such that

$$\int_{V_1(t_1)}^{V_1(t_2)} \frac{ds}{\mu(s) + \omega(s)} > G + E.$$
(3.19)

Integrating (3.18) on  $[t_1, t_2]$  with respect to *t* and using the above relation, we obtain the contradiction as follows:

$$G + E < \int_{V_{1}(t_{2})}^{V_{1}(t_{2})} \frac{ds}{\mu(s) + \omega(s)} = \int_{V_{1}(t_{2})}^{V_{1}(t_{2})} \frac{dV_{1}(t)}{\mu(V_{1}(t)) + \omega(V_{1}(t))}$$
  
$$\leq \int_{t_{1}}^{t_{2}} |h(x(t))| dt + \int_{t_{1}}^{t_{2}} |e(t)| dt \leq \int_{x(t_{1})}^{x(t_{2})} |h(x)| \frac{dx}{x'(t)} + E \qquad (3.20)$$
  
$$\leq \int_{-\infty}^{\infty} g(x) |h(x)| dx + E = G + E.$$

Thus, there exists a Y > 0 such that

$$|y(t)| \le Y, \quad t \in [0,\infty). \tag{3.21}$$

Second assume that  $\lim_{t\to T} |x(t)| = \infty$ . If  $\lim_{|x|\to\infty} (1/(Q - \operatorname{sgn}(x)H(x))) = \infty$ , that is,  $\lim_{|x|\to\infty} \operatorname{sgn}(x)H(x) = Q$ , we set

$$V_2(t, x, y) = \operatorname{sgn}(x)H(x) + K, \quad t \in R_+, \ x, y \in R.$$
(3.22)

Since x(t) is continuous, there exists  $0 \le T_2 < \infty$  such that

$$|x(t)| > N, \quad t \in [T_2, \infty).$$
 (3.23)

Differentiating  $V_2(t, x, y)$  with respect to *t* along solution (x(t), y(t)) of (1.1), we have

$$\frac{dV_2}{dt} = \operatorname{sgn}(x) \left[ a(x)c(y)h(x) - a(x)b(x)h(x) \right] 
\leq |h(x)| \left[ \mu(\operatorname{sgn}(x)H(x) + K) + \omega(\operatorname{sgn}(x)H(x) + K) \right], \qquad (3.24) 
t \in [T_2, \infty).$$

Since  $0 \le \operatorname{sgn}(x(t))H(x(t)) + K < Q + K, t \in [T_2, \infty)$ , we obtain

$$\frac{dV_2(t)}{\mu(V_2(t)) + \omega(V_2(t))} \le |h[x(t)]| dt, \quad t \in [T_2, \infty).$$
(3.25)

We denote that  $V_2(t) = V_2(t, x(t), y(t))$ .

By (vi), there exists  $T_2 \le t_3 < t_4 < T$  such that

$$\int_{V_2(t_3)}^{V_2(t_4)} \frac{ds}{\mu(s) + \omega(s)} > G.$$
(3.26)

Integrating (3.25) on  $[t_3, t_4]$  with respect to *t* and using the above relation, we obtain the contradiction as follows:

$$G < \int_{V_{2}(t_{3})}^{V_{2}(t_{4})} \frac{ds}{\mu(s) + \omega(s)} = \int_{t_{3}}^{t_{4}} \frac{dV_{2}(t)}{\mu(V_{2}(t)) + \omega(V_{2}(t))} \le \int_{t_{3}}^{t_{4}} |h(x(t))| dt$$

$$= \int_{x(t_{3})}^{x(t_{4})} |h(x)| \frac{dx}{x'(t)} \le \int_{-\infty}^{\infty} g(x) |h(x)| dx = G.$$
(3.27)

So consider  $\lim_{|x|\to\infty} (1/((Q - \operatorname{sgn}(x)H(x)))) < \infty$ .

By (iii), we have  $\lim_{|x|\to\infty} \operatorname{sgn}(x)b(x) = \infty$ . The proof of this condition is similar to that of Theorem 3.1, so we omit it. Thus, it follows that x(t) is also bounded from above. Then every solution of (1.1) is bounded. This completes the proof of Theorem 3.3.

#### **Theorem 3.4.** Assume that

(i) there exists some  $K \ge 0$ , such that

$$H(x) + K \ge 0, \quad x \in R,$$
  

$$C(y) + K \ge 0, \quad y \in R,$$
(3.28)

(ii) there exist some  $N \ge 0$  and Q > 0, such that

$$|H(x)| < Q, |x| > N,$$
  
 $|C(y)| < Q, |y| > N,$  (3.29)

(iii)  $\lim_{|y|\to\infty} C(y) = Q$ ,  $\lim_{|x|\to\infty} [1/(Q - H(x)) + \operatorname{sgn}(x)b(x)] = \infty$ , (iv) there exist two positive functions  $\mu, \omega \in C([0, K + Q), (0, \infty))$  such that

$$a(x)|c(y)| \le \min\{\mu(H(x) + K) + \omega(H(x) + K), \\ \mu(C(y) + K) + \omega(C(y) + K)\},$$
(3.30)  
$$|x| > N, |y| > N,$$

(v)  $\operatorname{sgn}(x)a(x)b(x)h(x) \ge 0$ , |x| > N and  $|h(x)| \le M < \infty$ ,  $x \in R$ , (vi)  $E = \int_0^\infty |e(t)|dt < \infty$ , and  $\int_0^{K+Q} (ds/(\mu(s) + \omega(s))) = \infty$ . If there exists g(x) such that

$$0 < \frac{a(x)}{|c(y) - b(x)|} \le g(x), \quad x, y \in R$$
(3.31)

and  $G = \int_{-\infty}^{\infty} g(x) |h(x)| dx < \infty$ , then every solution of (1.1) is bounded.

*Proof.* The proof of Theorem 3.4 is similar to that of Theorem 3.3, so we omit it.  $\Box$ 

## Acknowledgments

The authors thank the helpful suggestions by Professor Zhaoyang YIN and the referees for careful reading. This work is supported by Natural Science Foundation of the Education Department of Henan Province, China (no. 2011C110005).

## References

- A. Constantin, "A note on a second-order nonlinear differential system," *Glasgow Mathematical Journal*, vol. 42, no. 2, pp. 195–199, 2000.
- [2] T. A. Burton, "On the equation x'' + f(x)h(x')x' + g(x) = e(t)," Annali di Matematica Pura ed Applicata, vol. 85, pp. 277–285, 1970.
- [3] A. Constantin, "Global existence of solutions for perturbed differential equations," Annali di Matematica Pura ed Applicata, vol. 168, pp. 237–299, 1995.
- [4] J. Kato, "On a boundedness condition for solutions of a generalized Liénard equation," Journal of Differential Equations, vol. 65, no. 2, pp. 269–286, 1986.
- [5] Z. Yin, "Global existence and boundedness of solutions to a second order nonlinear differential system," *Studia Scientiarum Mathematicarum Hungarica*, vol. 41, no. 4, pp. 365–378, 2004.
- [6] V. Lakshmikantham and S. Leela, *Differential and Integral Inequalities—Volume I: Ordinary Differential Equation*, Academic Press, London, UK, 1969.



Advances in **Operations Research** 

**The Scientific** 

World Journal





Mathematical Problems in Engineering

Hindawi

Submit your manuscripts at http://www.hindawi.com



Algebra



Journal of Probability and Statistics



International Journal of Differential Equations





International Journal of Combinatorics

Complex Analysis









International Journal of Stochastic Analysis

Journal of Function Spaces



Abstract and Applied Analysis





Discrete Dynamics in Nature and Society