

*Research Article*

# Existence and Uniqueness of Homoclinic Solution for a Class of Nonlinear Second-Order Differential Equations

**Lijuan Chen and Shiping Lu**

*School of Mathematics and Statistics, Nanjing University of Information Science and Technology, Nanjing 210044, China*

Correspondence should be addressed to Lijuan Chen, [cljung@sohu.com](mailto:cljung@sohu.com)

Received 11 September 2012; Accepted 13 November 2012

Academic Editor: Julián López-Gómez

Copyright © 2012 L. Chen and S. Lu. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

The authors study the existence and uniqueness of a set with  $2kT$ -periodic solutions for a class of second-order differential equations by using Mawhin's continuation theorem and some analysis methods, and then a unique homoclinic orbit is obtained as a limit point of the above set of  $2kT$ -periodic solutions.

## 1. Introduction

In this paper, we study the existence and uniqueness of homoclinic solutions for the following nonlinear second-order differential equations:

$$u''(t) + g(u'(t)) + h(u(t)) = f(t), \quad (1.1)$$

where  $u(t) \in R$ ,  $g$ ,  $h$  and  $f$  are all in  $C(R, R)$ .

As usual we say that a nonzero solution  $u(t)$  of (1.1) is homoclinic (to 0) if  $u(t) \rightarrow 0$  and  $u'(t) \rightarrow 0$  as  $|t| \rightarrow +\infty$ .

Equation (1.1) is important in the applied sciences such as nonlinear vibration of masses, see [1–3] and the references therein. But most of the authors in those papers are interested in the study of problems of periodic solutions. Recently, the existence of homoclinic solutions for some second-order ordinary differential equation (system) has been extensively studied by using critical point theory, see [4–13] and the references therein. For example,

in [9], by using the Mountain Pass theorem, Lv et al. discussed the existence of homoclinic solutions for the following second-order Hamiltonian systems:

$$u''(t) - L(t)u(t) + \nabla w(t, u(t)) = 0, \quad (1.2)$$

and in [13], the authors by means of variational method studied the problem of homoclinic solutions for the forced pendulum equation without the first derivative term. But, as far as we know, there were few papers studying the existence of homoclinic solution for the equation such as (1.1). This is due to the fact that (1.1) contains the first derivative term  $g(u'(t))$ . This implies that the differential equation is not the Euler Lagrange equation associated with some functional  $I : W_{2kT}^{1,p} \rightarrow \mathbb{R}$ . So the method of critical point theory (or variational method) in [4–13] cannot be applied directly. Although paper [13] discussed the existence of homoclinic solutions for the following equation containing the first derivative term:

$$x''(t) + f(t)x'(t) + \beta(t)x(t) + g(t, x(t)) = 0, \quad (1.3)$$

the term containing the first derivative is only linear with respect to  $x'(t)$ .

In order to investigate the homoclinic solutions to (1.1), firstly, we study the existence of  $2kT$ -periodic solutions to the following equation for each  $k \in \mathbb{N}$ :

$$u''(t) + g(u'(t)) + h(u(t)) = f_k(t), \quad (1.4)$$

where  $f_k : \mathbb{R} \rightarrow \mathbb{R}$  is a  $2kT$ -periodic function such that

$$f_k(t) = \begin{cases} f(t), & t \in [-kT, kT - \varepsilon_0] \\ f(kT - \varepsilon_0) + \frac{f(-kT) - f(kT - \varepsilon_0)}{\varepsilon_0}(t - kT + \varepsilon_0), & t \in [kT - \varepsilon_0, kT], \end{cases} \quad (1.5)$$

$T > 0$  is a given constant, and  $\varepsilon_0 \in (0, T)$  is a constant independent of  $k$ . Then a homoclinic solution to (1.1) is obtained as a limit point of the set  $\{u_k(t)\}$ , where  $u_k(t)$  is an arbitrary  $2kT$ -periodic solution to (1.4) for each  $k \in \mathbb{N}$ .

The significance of present paper is that we not only investigate the existence of homoclinic solution to (1.1), but also study the uniqueness of the homoclinic solution and, the existence of  $2kT$ -periodic solutions to (1.4) is obtained by using Mawhin's continuation theorem [14], not by using the methods of critical point theory, which is quite different from the approaches of [4–13, 15]. Furthermore, the method to obtain the homoclinic solution to (1.1) is also different from the corresponding ones of [15].

## 2. Main Lemmas

For each  $k \in \mathbb{N}$ , let  $C_{2kT} = \{x \mid x \in C(\mathbb{R}, \mathbb{R}), x(t + 2kT) \equiv x(t)\}$ ,  $C_{2kT}^1 = \{x \mid x \in C^1(\mathbb{R}, \mathbb{R}), x(t + 2kT) \equiv x(t)\}$ , the norms of  $C_{2kT}$  and  $C_{2kT}^1$  are defined by  $\|\cdot\|_\infty = \max_{t \in [-kT, kT]} |x(t)|$  and  $\|x\|_{C_{2kT}^1} = \max\{\|x\|_\infty, \|x'\|_\infty\}$ , respectively, then  $C_{2kT}$  and  $C_{2kT}^1$  are all Banach spaces.

Furthermore for  $x \in C_{2kT}$ ,  $\|x\|_r = \left(\int_{-kT}^{kT} |x(t)|^r dt\right)^{1/r}$ , where  $r \in (1, +\infty)$ .

**Lemma 2.1** (see [12]). Let  $a > 0$  and  $q \in W^{1,p}(R, R)$ , then for every  $t \in R$ , the following inequality holds:

$$|q(t)| \leq (2a)^{-1/\mu} \left( \int_{t-a}^{t+a} |q(s)|^\mu ds \right)^{1/\mu} + a(2a)^{-1/p} \left( \int_{t-a}^{t+a} |q'(s)|^p ds \right)^{1/p}, \quad (2.1)$$

where  $\mu, p \in (1, +\infty)$  are constants.

**Lemma 2.2** (see [12]). Let  $q \in W_{2kT}^{1,p}(R, R^n)$ , then the following inequality holds:

$$\|q\|_\infty \leq T^{-1/\nu} \left( \int_{-kT}^{kT} |q(s)|^\nu ds \right)^{1/\nu} + T^{(p-1)/p} \left( \int_{-kT}^{kT} |q'(s)|^p ds \right)^{1/p}, \quad (2.2)$$

where  $\nu$  and  $p$  are constants with  $\nu > 1$  and  $p > 1$ .

In order to use Mawhin's continuation theorem for investigating the existence of  $2kT$ -periodic solutions to (1.4), we give some definitions associated with Mawhin's continuation theorem.

*Definition 2.3* (see [14]). Let  $X$  and  $Y$  be two Banach spaces with norms  $\|x\|_X$  and  $\|x\|_Y$ , respectively. A linear operator

$$L : D(L) \subset X \longrightarrow Y \quad (2.3)$$

is said to be a Fredholm operator with index zero provided that

- (1)  $\text{Im } L$  is a closed subset of  $Y$ ;
- (2)  $\dim \text{Ker } L = \text{codim Im } L < \infty$ .

If  $L : D(L) \subset X \rightarrow Y$  is a Fredholm operator with index zero, then  $X = \text{ker } L \oplus X_1$  and  $Y = \text{Im } L \oplus Y_1$ . Let  $P : X \rightarrow \text{ker } L$  and  $Q : Y \rightarrow Y_1$  be the continuous projectors. Clearly,  $\text{ker } L \cap (D(L) \cap X_1) = \{0\}$ , thus the restriction  $L_P := L|_{D(L) \cap X_1}$  is invertible. Denote by  $K_P$  the inverse of  $L_P$ .

*Definition 2.4* (see [14]). Let  $X$  and  $Y$  be two Banach spaces with norms  $\|x\|_X$  and  $\|x\|_Y$ , respectively, and the operator

$$L : D(L) \subset X \longrightarrow Y \quad (2.4)$$

is a Fredholm operator with index zero,  $\Omega \subset X$  is an open bounded set with  $D(L) \cap \Omega \neq \emptyset$ . A continuous operator  $N : \overline{\Omega} \subset X \rightarrow Y$  is said to be  $L$ -compact in  $\overline{\Omega}$ , provided that

- (1)  $K_P(I - Q)N(\overline{\Omega})$  is a relative compact set of  $X$ ;
- (2)  $QN(\overline{\Omega})$  is a bounded set of  $Y$ .

**Lemma 2.5** (see [14]). *Suppose that  $X$  and  $Y$  are two Banach spaces, and  $L : D(L) \subset X \rightarrow Y$  is a Fredholm operator with index zero. Furthermore,  $\Omega \subset X$  is an open bounded subset and  $N : \overline{\Omega} \rightarrow Y$  is  $L$ -compact on  $\overline{\Omega}$ . If all the following conditions hold:*

- (1)  $Lx \neq \lambda Nx$ , for all  $x \in \partial\Omega \cap D(L)$ ,  $\lambda \in (0, 1)$ ;
- (2)  $Nx \notin \text{Im } L$ , for all  $x \in \partial\Omega \cap \text{Ker } L$ ;
- (3)  $\text{deg}\{JQN, \Omega \cap \text{Ker } L, 0\} \neq 0$ ,

where  $J : \text{Im } Q \rightarrow \text{Ker } L$  is an isomorphism. Then equation  $Lx = Nx$  has a solution on  $\overline{\Omega} \cap D(L)$ .

**Lemma 2.6.** *Assume that there are positive constants  $m$ ,  $m_1$ ,  $n$ ,  $l_0$ , and  $l_1$  with  $l_0 \geq l_1$ , such that the following conditions hold.*

$$(A1) \sup_{t \in \mathbb{R}} |f(t)| < +\infty, \int_{\mathbb{R}} |f(t)|^{(l_0+1)/l_0} dt < +\infty, \int_{\mathbb{R}} |f(t)|^{(l_1+1)/l_1} dt < +\infty \text{ and } \int_{\mathbb{R}} |f(t)|^2 dt < +\infty.$$

$$(A2)$$

$$\begin{aligned} -m_1|x|^{l_0+1} \leq xg(x) \leq -m|x|^{l_0+1}, \quad \forall x \in \mathbb{R}, \\ xh(x) \leq -n|x|^{l_1+1}, \quad \forall x \in \mathbb{R}. \end{aligned} \tag{2.5}$$

$$(A3) h \in C^1(\mathbb{R}, \mathbb{R}) \text{ with } h'(x) \leq 0 \text{ for all } x \in \mathbb{R}.$$

Then for every  $k \in \mathbb{N}$ , (1.4) possesses a  $2kT$ -periodic solution.

*Remark 2.7.* From (1.5), we see

$$\begin{aligned} \|f_k\|_{\infty} &\leq \sup_{t \in \mathbb{R}} |f(t)| < +\infty, \quad \forall k \in \mathbb{N}, \\ \|f_k\|_{(l_0+1)/l_0} &= \left( \int_{-kT}^{kT} |f_k(s)|^{(l_0+1)/l_0} ds \right)^{l_0/(l_0+1)} \\ &\leq \left( \int_{-kT}^{kT-\varepsilon_0} |f_k(s)|^{(l_0+1)/l_0} ds \right)^{l_0/(l_0+1)} + \left( \int_{kT-\varepsilon_0}^{kT} |f_k(s)|^{(l_0+1)/l_0} ds \right)^{l_0/(l_0+1)} \tag{2.6} \\ &\leq \left( \int_{\mathbb{R}} |f(s)|^{(l_0+1)/l_0} ds \right)^{l_0/(l_0+1)} + \varepsilon_0^{l_0/(l_0+1)} \sup_{t \in \mathbb{R}} |f(t)|, \quad \forall k \in \mathbb{N}, \end{aligned}$$

which together with assumption (A1) yields that  $\|f_k\|_{\infty}$  and  $\|f_k\|_{(l_0+1)/l_0}$  are two constants independent of  $k \in \mathbb{N}$ .

Similarly, we have that  $\|f_k\|_{(l_1+1)/l_1} < +\infty$  and  $\|f_k\|_2 < +\infty$  are two constants independent of  $k \in \mathbb{N}$ .

*Proof.* Set  $X = C_{2kT}^1$ ,  $Y = C_{2kT}$ ,  $L : D(L) \subset X \rightarrow Y$ ,  $Lu = u''$ , where  $D(L) = \{u \mid u \in C_{2kT}^2\}$ , and

$$N : C_{2kT}^1 \longrightarrow C_{2kT}, \quad [Nu](t) = -g(u'(t)) - h(u(t)) + f_k(t). \quad (2.7)$$

Clearly,  $\text{Ker } L = R$ ,  $\text{Im } L = \{y \in Y : \int_{-kT}^{kT} y(s)ds = 0\}$ , which implies that  $\text{Im } L$  is a closed subset of  $Y$ , and  $\dim \text{Ker } L = \text{codim Im } L = 1 < +\infty$ . So  $L$  is a Fredholm operator with index zero. Let

$$P : X \longrightarrow \text{Ker } L, \quad Q : Y \rightarrow Y/\text{Im } L \quad (2.8)$$

be defined respectively by  $Px = (1/2kT) \int_0^{2kT} x(s)ds$ ,  $Qx = (1/2kT) \int_0^{2kT} x(s)ds$  and let

$$L_P = L|_{X \cap \text{Ker } P} : X \cap \text{Ker } P \longrightarrow \text{Im } L. \quad (2.9)$$

Then  $L_P$  has a unique continuous pseudo-inverse  $L_P^{-1}$  on  $\text{Im } L$  defined by  $(L_P^{-1}y)(t) = [Fy](t)$ , where

$$[Fy](t) = \int_0^{2kT} G(t,s)y(s)ds, \quad (2.10)$$

$$G(t,s) = \begin{cases} \frac{s(2kT-t)}{2kT}, & 0 \leq s < t, \\ \frac{t(2kT-s)}{2kT}, & t \leq s \leq 2kT. \end{cases}$$

For each open bounded set  $\Omega \subset C_{2kT}$ , from the above formula, it is easy to see that the mapper  $N$  is  $L$ -compact on  $\overline{\Omega}$ .

*Step 1.* For each  $k \in \mathbf{N}$ , let  $\Omega_1 = \{x \in C_{2kT}^1 : Lx = \lambda Nx, \lambda \in (0, 1)\}$ , that is,

$$\Omega_1 = \left\{ x \in C_{2kT}^1 : x''(t) + \lambda g(x'(t)) + \lambda h(x(t)) = \lambda f_k(t), \lambda \in (0, 1) \right\}. \quad (2.11)$$

We will show that  $\Omega_1$  is bounded in  $C_{2kT}^1$ . Suppose that  $u \in \Omega_1$ , then

$$u''(t) + \lambda g(u'(t)) + \lambda h(u(t)) = \lambda f_k(t), \quad \lambda \in (0, 1). \quad (2.12)$$

Multiplying both sides of (2.12) by  $u'(t)$  and integrating on the interval  $[-kT, kT]$ , we have from assumption (A2) that

$$m \int_{-kT}^{kT} |u'(t)|^{l_0+1} dt \leq - \int_{-kT}^{kT} u'(t)g(u'(t))dt = - \int_{-kT}^{kT} f_k(t)u'(t)dt. \quad (2.13)$$

By using hólder inequality, we get

$$\|u'\|_{l_0+1}^{l_0+1} \leq \frac{1}{m} \|f_k\|_{(l_0+1)/l_0} \cdot \|u'\|_{l_0+1}, \quad (2.14)$$

which together with the conclusion of Remark 2.7 shows

$$\|u'\|_{l_0+1} \leq \left( \frac{1}{m} \|f_k\|_{(l_0+1)/l_0} \right)^{1/l_0} := \beta_1. \quad (2.15)$$

Clearly,  $\beta_1$  is a constant independent of  $k$  and  $\lambda$ .

Multiplying both sides of (2.12) by  $u''(t)$  and integrating on the interval  $[-kT, kT]$ , we have

$$\|u''\|_2^2 - \lambda \int_{-kT}^{kT} (u'(t))^2 h'(u(t)) dt = \lambda \int_{-kT}^{kT} f_k(t) u''(t) dt. \quad (2.16)$$

It follows from (2.16) and assumption (A3) that

$$\|u''\|_2^2 \leq \int_{-kT}^{kT} |f_k(t) u''(t)| dt \leq \|f_k\|_2 \cdot \|u''\|_2, \quad (2.17)$$

which implies

$$\|u''\|_2 \leq \|f_k\|_2 := \beta_2. \quad (2.18)$$

By using Lemma 2.2, we have

$$\begin{aligned} \|u'\|_\infty &\leq T^{-1/(l_0+1)} \|u'\|_{l_0+1} + T^{1/2} \|u''\|_2 \\ &\leq T^{-1/(l_0+1)} \beta_1 + T^{1/2} \beta_2 \\ &:= \beta. \end{aligned} \quad (2.19)$$

Clearly,  $\beta$  is a constant independent of  $k$  and  $\lambda$ .

On the other hand, multiplying both sides of (2.12) by  $u(t)$  and integrating on the interval  $[-kT, kT]$ , we have

$$-\int_{-kT}^{kT} |u'(t)|^2 dt + \lambda \int_{-kT}^{kT} h(u(t)) u(t) dt = -\lambda \int_{-kT}^{kT} g(u'(t)) u(t) dt + \lambda \int_{-kT}^{kT} f_k(t) u(t) dt. \quad (2.20)$$

It follows from assumption (A2) that

$$\lambda n \int_{-kT}^{kT} (u(t))^{l_0+1} dt + \int_{-kT}^{kT} (u'(t))^2 dt \leq \lambda m_1 \int_{-kT}^{kT} |u'(t)|^{l_0} |u(t)| dt + \lambda \int_{-kT}^{kT} |f_k(t)| |u(t)| dt, \quad (2.21)$$

which together with (2.19) and  $l_0 \geq l_1$  results in

$$\begin{aligned}
n \int_{-kT}^{kT} |u(t)|^{l_1+1} dt &\leq m_1 \int_{-kT}^{kT} |u'(t)|^{l_0} \cdot |u(t)| dt + \int_{-kT}^{kT} |f_k(t)u(t)| dt \\
&\leq m_1 \left( \int_{-kT}^{kT} |u'(t)|^{l_0(l_1+1)/l_1} dt \right)^{l_1/(l_1+1)} \cdot \left( \int_{-kT}^{kT} |u(t)|^{l_1+1} dt \right)^{1/(l_1+1)} \\
&\quad + \left( \int_{-kT}^{kT} |f_k(t)|^{(l_1+1)/l_1} dt \right)^{l_1/(l_1+1)} \cdot \left( \int_{-kT}^{kT} |u(t)|^{l_1+1} dt \right)^{1/(l_1+1)} \\
&= m_1 \left( \int_{-kT}^{kT} |u'(t)|^{l_0+1} |u'(t)|^{(l_0-l_1)/l_1} dt \right)^{l_1/(l_1+1)} \cdot \|u\|_{l_1+1} + \|f_k\|_{(l_1+1)/l_1} \|u\|_{l_1+1} \\
&\leq m_1 \beta^{(l_0-1)/(l_1+1)} \left( \int_{-kT}^{kT} |u'(t)|^{l_0+1} dt \right)^{l_1/(l_1+1)} \|u\|_{l_1+1} + \|f_k\|_{(l_1+1)/l_1} \|u\|_{l_1+1} \\
&= m_1 \beta^{(l_0-l_1)/(l_1+1)} \left( \|u'\|_{l_0+1} \right)^{l_1(l_0+1)/(l_1+1)} \|u\|_{l_1+1} + \|f_k\|_{(l_1+1)/l_1} \|u\|_{l_1+1} \\
&\leq m_1 \beta^{(l_0-1)/(l_1+1)} \beta_1^{l_1(l_0+1)/(l_1+1)} \|u\|_{l_1+1} + \|f_k\|_{(l_1+1)/l_1} \|u\|_{l_1+1}
\end{aligned} \tag{2.22}$$

that is,

$$\|u\|_{l_1+1}^{l_1+1} \leq \frac{1}{n} \left[ m_1 \beta^{(l_0-l_1)/(l_1+1)} \beta_1^{l_1(l_0+1)/(l_1+1)} + \|f_k\|_{(l_1+1)/l_1} \right] \|u\|_{l_1+1}. \tag{2.23}$$

Therefore

$$\|u\|_{l_1+1} \leq \left( \frac{1}{n} \right)^{1/l_1} \left[ m_1 \beta^{(l_0-l_1)/(l_1+1)} \beta_1^{l_1(l_0+1)/(l_1+1)} + \|f_k\|_{(l_1+1)/l_1} \right]^{1/l_1} := \alpha_1, \tag{2.24}$$

where  $\alpha_1$  is a constant independent of  $k$  and  $\lambda$ . By using Lemma 2.2 again, we get

$$\begin{aligned}
\|u\|_{\infty} &\leq T^{-1/(l_1+1)} \|u\|_{l_1+1} + T^{l_0/(l_0+1)} \|u'\|_{l_0+1} \\
&\leq T^{-1/(l_1+1)} \alpha_1 + T^{l_0/(l_0+1)} \beta_1 := \alpha.
\end{aligned} \tag{2.25}$$

Obviously,  $\alpha$  is a constant independent of  $k$  and  $\lambda$ . Therefore, if  $u \in \Omega_1$ , then by (2.19) we see that

$$\|u\|_{C_{2kT}^1} = \max\{\|u\|_{\infty}, \|u'\|_{\infty}\} \leq \max\{\alpha, \beta\} + \sup_{t \in R} |f(t)| := \widetilde{M}. \tag{2.26}$$

Clearly,  $\widetilde{M} > 0$  is a constant independent of  $k$  and  $\lambda$ ; that is,  $\Omega_1$  is uniformly bounded for all  $k \in \mathbb{N}$  and  $\lambda \in (0, 1)$ .

*Step 2.* From assumptions (A2) and (A3), we see that there must be a constant  $M_1 > 0$  such that  $-h(M_1) + \overline{f_k} > 0$  and  $-h(-M_1) + \overline{f_k} < 0$ . Set  $\Omega_2 = \{u(t) \in C_{2kT}^1 : \|u\|_{C_{2kT}^1} < M\}$ , where  $M = \max\{M_1, \widetilde{M}\}$ . We will show that  $Nu \notin \text{Im } L$ , for all  $u \in \partial\Omega_2 \cap \text{Ker } L$ .

In fact, by assumption (A2), we see that  $g(0) = 0$ , and if  $u \in \partial\Omega_2 \cap \text{Ker } L$ , then  $u(t) \equiv M$  or  $u \equiv -M$ . So

$$\begin{aligned} QN(u) &= -\frac{1}{2kT} \int_{-kT}^{kT} [h(M) - f_k(t)] dt = -h(M) + \overline{f_k} \geq -h(M_1) + \overline{f_k} > 0, \quad \forall u(t) \equiv M, \\ QN(u) &= -\frac{1}{2kT} \int_{-kT}^{kT} [h(-M) - f_k(t)] dt = -h(-M) + \overline{f_k} \leq -h(-M_1) + \overline{f_k} < 0, \quad \forall u(t) \equiv -M, \end{aligned} \quad (2.27)$$

where  $\overline{f_k} = (1/2kT) \int_{-kT}^{kT} f_k(t) dt$ . This implies that  $Nu \notin \text{Im } L$ , for all  $u \in \partial\Omega_2 \cap \text{Ker } L$ .

*Step 3.* Set  $J : \text{Im } Q \rightarrow \text{Ker } L$ ,  $Jx = x$ , we will show  $\deg\{JQN, \Omega_2 \cap \text{Ker } L, 0\} \neq 0$ .

Let  $H(x, \mu) = \mu x + (1 - \mu)JQNx$ , for all  $x \in \Omega_2 \cap \text{Ker } L$ , when  $x \in \partial(\Omega_2 \cap \text{Ker } L)$ , we have  $x = \pm M$  and

$$\begin{aligned} H(M, \mu) &= \mu M + (1 - \mu)JQN(M) = \mu M + (1 - \mu)QN(M) > 0, \\ H(-M, \mu) &= -\mu M + (1 - \mu)JQN(-M) = -\mu M + (1 - \mu)QN(-M) < 0. \end{aligned} \quad (2.28)$$

So for all  $\mu \in [0, 1]$ ,  $H(\partial(\Omega_2 \cap \text{Ker } L), \mu) \neq 0$ , and then

$$\begin{aligned} \deg\{JQN, \Omega_2 \cap \text{Ker } L, 0\} &= \deg\{H(\cdot, 0), \Omega_2 \cap \text{Ker } L, 0\} \\ &= \deg\{H(\cdot, 1), \Omega_2 \cap \text{Ker } L, 0\} = \deg\{I, \Omega_2 \cap \text{Ker } L, 0\} \\ &= 1. \end{aligned} \quad (2.29)$$

Therefore, by Lemma 2.5, (1.4) has a  $2kT$ -periodic solution  $u_k \in \overline{\Omega_2}$ .  $\square$

*Remark 2.8.* Suppose that all the conditions in Lemma 2.6 hold. We see that for each  $k \in \mathbf{N}$ , (1.4) has a  $2kT$ -periodic solution  $u_k \in \Omega_2$ . This implies that

$$\|u_k\|_{\infty} \leq M, \quad \|u'_k\|_{\infty} \leq M. \quad (2.30)$$

Furthermore, as same as the proof of step 1 in Lemma 2.6 with replacing  $u(t)$  by  $u_k(t)$ , we have

$$\|u_k\|_{l_{+1}} \leq \alpha_1, \quad \|u'_k\|_{l_{+1}} \leq \beta_1, \quad (2.31)$$

where  $\alpha_1$  and  $\beta_1$  are two positive constants independent of  $k \in \mathbf{N}$ .



**Lemma 2.9** (see [12]). Let  $u_k \in C^1_{2kT}$  be the  $2kT$ -periodic solution for (1.4) and satisfies (2.30) and (2.31) for all  $k \in \mathbf{N}$ . Then there exists a function  $u_0 \in C^1(\mathbf{R}, \mathbf{R})$  such that for each interval  $[c, d] \subset \mathbf{R}$ , there is a subsequence  $\{u_{k_j}\}$  of  $\{u_k\}_{k \in \mathbf{N}}$  with  $u'_{k_j}(t) \rightarrow u'_0(t)$  uniformly on  $[c, d]$ .

### 3. Main Results

**Theorem 3.1.** Suppose that assumptions (A1), (A2), and (A3) in Lemma 2.6 hold. Then (1.1) has a unique homoclinic solution.

*Proof.* Since assumptions (A1), (A2), consisting of Kuratowski operations we used following principles and (A3) in Lemma 2.6 hold, by using Lemma 2.6, we see that (1.4) has a  $2kT$ -periodic solution  $u_k(t)$  satisfying (2.30) and (2.31) for each  $k \in \mathbf{N}$ . It follows from Lemma 2.9 that there exists a  $u_0 \in C^1(\mathbf{R}, \mathbf{R})$  such that for each interval  $[c, d] \subset \mathbf{R}$ , there is a subsequence  $\{u_{k_j}\}$  of  $\{u_k\}_{k \in \mathbf{N}}$  satisfying  $u'_{k_j}(t) \rightarrow u'_0(t)$  uniformly on  $[c, d]$ . Below, we will show that  $u_0(t)$  is just a unique homoclinic solution to (1.1).

*Step 1.* We show that  $u_0$  is a solution of (1.1).

In view of  $u_{k_j}(t)$  being a  $2k_jT$ -periodic solution to (1.4), we have

$$u''_{k_j}(t) + g(u'_{k_j}(t)) + h(u_{k_j}(t)) = f_{k_j}(t), \quad \text{for } t \in [-k_jT, k_jT], \quad j \in \mathbf{N}. \quad (3.1)$$

Take  $a, b \in \mathbf{R}$  such that  $a < b$ , there exists  $j_0 \in \mathbf{N}$  such that for all  $j > j_0$

$$u''_{k_j}(t) + g(u'_{k_j}(t)) + h(u_{k_j}(t)) = f(t), \quad \text{for } t \in [a, b]. \quad (3.2)$$

Integrating (3.2) from  $a$  to  $t \in [a, b]$ , we have

$$u'_{k_j}(t) - u'_{k_j}(a) = \int_a^t [-g(u'_{k_j}(s)) - h(u_{k_j}(s)) + f(s)] ds, \quad \text{for } t \in [a, b]. \quad (3.3)$$

Since Lemma 2.9 shows that  $u_{k_j} \rightarrow u_0$  uniformly on  $[a, b]$  and  $u'_{k_j} \rightarrow u'_0$  uniformly on  $[a, b]$  as  $j \rightarrow \infty$ , let  $j \rightarrow \infty$  in (3.3), we get

$$u'_0(t) - u'_0(a) = \int_a^t [-g(u'_0(s)) - h(u_0(s)) + f(s)] ds, \quad \text{for } t \in [a, b]. \quad (3.4)$$

In view of  $a$  and  $b$  are arbitrary, (3.4) shows that  $u_0(t)$  is a solution of (1.1).

*Step 2.* We prove that  $u_0(t) \rightarrow 0$ , as  $t \rightarrow \pm\infty$ .

Obviously, for every  $i \in \mathbb{N}$ , there exists  $j_i \in \mathbb{N}$  such that for all  $j > j_i$ , we have

$$\begin{aligned} \int_{-iT}^{iT} \left[ |u_{k_j}(t)|^{l_1+1} + |u'_{k_j}(t)|^{l_0+1} \right] dt &\leq \int_{-k_j T}^{k_j T} \left[ |u_{k_j}(t)|^{l_1+1} + |u'_{k_j}(t)|^{l_0+1} \right] dt \\ &\leq \alpha_1^{l_1+1} + \beta_1^{l_0+1} \\ &:= M_2. \end{aligned} \quad (3.5)$$

It follows that

$$\begin{aligned} &\int_{-\infty}^{+\infty} \left[ |u_0(t)|^{l_1+1} + |u'_0(t)|^{l_0+1} \right] dt \\ &= \lim_{i \rightarrow +\infty} \int_{-iT}^{iT} \left[ |u_0(t)|^{l_1+1} + |u'_0(t)|^{l_0+1} \right] dt \\ &= \lim_{i \rightarrow +\infty} \lim_{j \rightarrow +\infty} \int_{-iT}^{iT} \left[ |u_{k_j}(t)|^{l_1+1} + |u'_{k_j}(t)|^{l_0+1} \right] dt \\ &\leq M_2, \end{aligned} \quad (3.6)$$

and then

$$\int_{|t| \geq r} \left[ |u_0(t)|^{l_1+1} + |u'_0(t)|^{l_0+1} \right] dt \longrightarrow 0, \quad \text{as } r \longrightarrow +\infty, \quad (3.7)$$

which yields

$$\int_{|t| \geq r} |u_0(t)|^{l_1+1} dt \longrightarrow 0, \quad \int_{|t| \geq r} |u'_0(t)|^{l_0+1} dt \longrightarrow 0, \quad \text{as } r \longrightarrow +\infty. \quad (3.8)$$

By using Lemma 2.1, as  $t \rightarrow \pm\infty$ ,

$$\begin{aligned} |u_0(t)| &\leq (2a)^{-1/(l_1+1)} \left( \int_{t-a}^{t+a} |u_0(s)|^{l_1+1} ds \right)^{1/(l_1+1)} \\ &\quad + a \cdot (2a)^{-1/(l_0+1)} \left( \int_{t-a}^{t+a} |u'_0(s)|^{l_0+1} ds \right)^{1/(l_0+1)} \longrightarrow 0. \end{aligned} \quad (3.9)$$

So we have  $u_0(t) \rightarrow 0$ , as  $t \rightarrow \pm\infty$ .

*Step 3.* We will show that

$$u'_0(t) \longrightarrow 0, \quad \text{as } t \longrightarrow \pm\infty. \quad (3.10)$$

From the Remark 2.8 and Lemma 2.9, we have

$$|u_0(t)| \leq M, \quad |u'_0(t)| \leq M, \quad \text{for all } t \in R, \tag{3.11}$$

which together with (1.1) implies that

$$\|u''_0\|_\infty \leq g_M + h_M + \sup_{t \in R} |f(t)|, \tag{3.12}$$

where  $g_M = \max_{|x| \leq M} |g(x)|$  and  $h_M = \max_{|x| \leq M} |h(x)|$ . If  $u'_0(t) \rightarrow 0$ , as  $t \rightarrow \pm\infty$ , then there exist a  $\varepsilon_0 \in (0, 1/2)$  and a sequence  $\{t_k\}$  such that

$$\begin{aligned} |t_1| < |t_2| < |t_3| < \dots, \quad |t_k| + 1 < |t_{k+1}|, \quad k \in \mathbf{N}, \\ |u'_0(t_k)| \geq 2\varepsilon_0, \quad k \in \mathbf{N}. \end{aligned} \tag{3.13}$$

From this, we have for  $t \in [t_k, t_k + \varepsilon_0 / (1 + M_1)]$

$$|u'_0(t)| = \left| u'_0(t_k) + \int_{t_k}^t u''_0(s) ds \right| \geq |u'_0(t_k)| - \int_{t_k}^t |u''_0(s)| ds \geq \varepsilon_0. \tag{3.14}$$

It follows that

$$\int_{-\infty}^{+\infty} |u'_0(t)|^{l_0+1} dt \geq \sum_{k=1}^{\infty} \int_{t_k}^{t_k + \varepsilon_0 / (1 + M_1)} |u'_0(t)|^{l_0+1} dt = \infty, \tag{3.15}$$

which contradicts (3.6), and so (3.10) holds.

*Step 4.* Finally, we will prove that (1.1) possesses a unique homoclinic solution. In order to do it, let  $u(t) = u_1(t) - u_2(t)$ , where  $u_1(t)$  and  $u_2(t)$  are two arbitrary homoclinic solutions of (1.1). Then

$$u(t) \rightarrow 0 \quad \text{as } t \rightarrow \pm\infty. \tag{3.16}$$

We will show that

$$u(t) \equiv 0. \tag{3.17}$$

If (3.17) does not hold, then there must be a  $t^* \in R$  such that

$$u(t^*) > 0 \tag{3.18}$$

or

$$u(t^*) < 0. \tag{3.19}$$

If  $u(t^*) > 0$ , then from (3.16), we see that there is a constant  $X > 0$  such that  $t^* \in (-X, X)$  and  $u(t) < u(t^*)/2$  for  $t \in (-\infty, X) \cup (X, +\infty)$ . Let  $t^{**} \in [-X, X]$  such that  $u(t^{**}) = \max_{t \in [-X, X]} u(t)$ , then

$$u(t^{**}) \geq u(t^*) > 0, \quad (3.20)$$

$$u(t^{**}) \geq u(t^*) > \sup_{t \in (-\infty, X) \cup (X, +\infty)} u(t), \quad (3.21)$$

that is,

$$u(t^{**}) = \max_{t \in \mathbb{R}} u(t). \quad (3.22)$$

So  $u'(t^{**}) = 0$  and  $u''(t^{**}) \leq 0$ , and then from (1.1), we see

$$-[h(u_1(t^{**})) - h(u_2(t^{**}))] = u_1''(t^{**}) - u_2''(t^{**}) = u''(t^{**}) \leq 0. \quad (3.23)$$

By using the condition (A3), we have that

$$u(t^{**}) = u_1(t^{**}) - u_2(t^{**}) \leq 0, \quad (3.24)$$

which contradicts to (3.20). This contradiction implies that (3.18) does not hold. Similarly, we can prove that (3.19) does not hold, either. So  $u(t) \equiv 0$ .

As an application, we consider the following example:

$$u''(t) - m(u'(t))^3 - n(u(t)) = \frac{e^{t/2}}{e^{-t} + e^t}, \quad (3.25)$$

where  $m, n > 0$  are constants and,  $f(t) = e^{t/2}/(e^{-t} + e^t)$ . Corresponding to (1.1), we can choose  $l_0 = 3$  and  $l_1 = 1$  such that assumptions (A2) and (A3) hold. Furthermore, by the direct calculation, we can easily obtain that

$$\begin{aligned} \int_{\mathbb{R}} |f(t)|^{(l_1+1)/l_1} dt &= \int_{-\infty}^{+\infty} |f(t)|^2 dt = \frac{\pi}{4} < \infty, \\ \int_{\mathbb{R}} |f(t)|^{(l_0+1)/l_0} dt &= \int_{-\infty}^{+\infty} |f(t)|^{4/3} dt = \frac{3}{2} < \infty. \end{aligned} \quad (3.26)$$

This implies that assumption (A1) also holds. So by applying Theorem 3.1, we know that (3.25) possesses a unique homoclinic solution.  $\square$

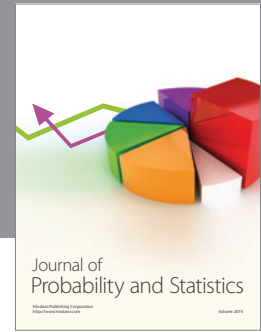
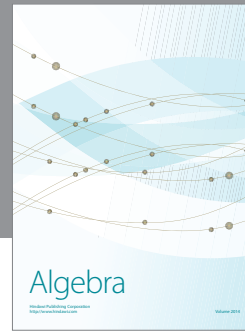
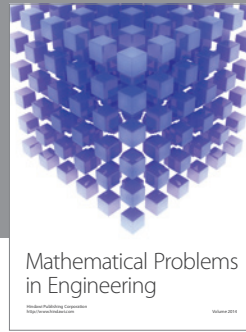
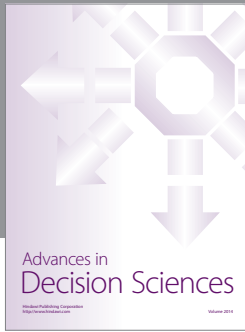
## Acknowledgments

The authors are very grateful to the referee for her/his careful reading of the original paper and for her/his valuable suggestions for improving this paper. This work was sponsored by

the key NNSF of China (no. 11271197) and Science Foundation of NUIST (no. 20090202; 2012r101).

## References

- [1] E. N. Dancer, "On the ranges of certain damped nonlinear differential equations," *Annali di Matematica Pura ed Applicata*, vol. 119, pp. 281–295, 1979.
- [2] P. Girg and F. Roca, "On the range of certain pendulum-type equations," *Journal of Mathematical Analysis and Applications*, vol. 249, no. 2, pp. 445–462, 2000.
- [3] P. Amster and M. C. Mariani, "Some results on the forced pendulum equation," *Nonlinear Analysis. Theory, Methods & Applications*, vol. 68, no. 7, pp. 1874–1880, 2008.
- [4] M. Izydorek and J. Janczewska, "Homoclinic solutions for nonautonomous second order Hamiltonian systems with a coercive potential," *Journal of Mathematical Analysis and Applications*, vol. 335, no. 2, pp. 1119–1127, 2007.
- [5] J. Mawhin and M. Willem, *Critical Point Theory and Hamiltonian Systems*, vol. 74 of *Applied Mathematical Sciences*, Springer, New York, NY, USA, 1989.
- [6] X. Lv, S. Lu, and P. Yan, "Homoclinic solutions for nonautonomous second-order Hamiltonian systems with a coercive potential," *Nonlinear Analysis. Theory, Methods & Applications A*, vol. 72, no. 7-8, pp. 3484–3490, 2010.
- [7] S. Lu, "Homoclinic solutions for a class of second-order  $p$ -Laplacian differential systems with delay," *Nonlinear Analysis. Real World Applications*, vol. 12, no. 1, pp. 780–788, 2011.
- [8] X. H. Tang and L. Xiao, "Homoclinic solutions for nonautonomous second-order Hamiltonian systems with a coercive potential," *Journal of Mathematical Analysis and Applications*, vol. 351, no. 2, pp. 586–594, 2009.
- [9] X. Lv, S. Lu, and P. Yan, "Existence of homoclinic solutions for a class of second-order Hamiltonian systems," *Nonlinear Analysis. Theory, Methods & Applications A*, vol. 72, no. 1, pp. 390–398, 2010.
- [10] Y. Xu and M. Huang, "Homoclinic orbits and Hopf bifurcations in delay differential systems with T-B singularity," *Journal of Differential Equations*, vol. 244, no. 3, pp. 582–598, 2008.
- [11] X. H. Tang and L. Xiao, "Homoclinic solutions for a class of second-order Hamiltonian systems," *Nonlinear Analysis. Theory, Methods & Applications A*, vol. 71, no. 3-4, pp. 1140–1152, 2009.
- [12] X. H. Tang and L. Xiao, "Homoclinic solutions for ordinary  $p$ -Laplacian systems with a coercive potential," *Nonlinear Analysis. Theory, Methods & Applications A*, vol. 71, no. 3-4, pp. 1124–1132, 2009.
- [13] D. C. Offin and H. F. Yu, "Homoclinic orbit in the forced pendulum system," *Fields Institute of Communication*, vol. 8, pp. 113–126, 1996.
- [14] R. E. Gaines and J. L. Mawhin, *Coincidence Degree, and Nonlinear Differential Equations*, vol. 568 of *Lecture Notes in Mathematics*, Springer, Berlin, Germany, 1977.
- [15] C. Vladimirescu, "An existence result for homoclinic solutions to a nonlinear second-order ODE through differential inequalities," *Nonlinear Analysis. Theory, Methods & Applications A*, vol. 68, no. 10, pp. 3217–3223, 2008.



# Hindawi

Submit your manuscripts at  
<http://www.hindawi.com>

