# Polynomials with All Zeros Real and in a Prescribed Interval 

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#### Abstract

We provide a characterization of the real-valued univariate polynomials that have only real zeros, all in a prescribed interval $[a, b]$. The conditions are stated in terms of positive semidefiniteness of related Hankel matrices.


Keywords: algebraic combinatorics, real algebraic geometry, the $\mathbb{K}$-moment problem

## 1. Introduction

From a fundamental result of Aissen et al. [1], a real-valued univariate polynomial has all its zeros real and nonpositive, if and only if a certain infinite Toeplitz matrix is totally nonnegative (see also [9, Theorem 1, p. 21]). However, despite its theoretical significance, this result involves checking infinitely many conditions, and therefore, cannot be applied directly for practical purposes (see Stanley [9] on some open problems in Algebraic Combinatorics). Using a modified Routh array, Šiljak has provided a finite algebraic procedure to count the number of positive (or negative) zeros, with their multiplicity (see also the more recent paper [8, Theorem 3.9, p. 140]).

In this paper we provide a characterization of such polynomials $\theta: \mathbb{R} \rightarrow \mathbb{R}$ different from that of Šiljak. Our conditions are stated in terms of two Hankel matrices $M(n, s), B(n, s)$ formed with some functions $s$ of the coefficients of the polynomial $\theta$ (the normalized Newton's sums). The conditions state that $M(n, s)$ and $-B(n, s)$ must be positive semidefinite $(M(n, s) \succeq 0, B(n, s) \preceq 0)$ and the rank of $M(n, s)$ gives the number of distinct zeros. This condition is of the same flavour as Gantmacher's conditions for the number of real zeros of $\theta$ (see Gantmacher [4]). If we drop the nonpositivity condition on the zeros, then the condition reduces to $M(n, s) \succeq 0$, that is, a necessary and sufficient condition for $\theta$ to have only real zeros (as before, the rank of $M(n, s)$ also giving the number of distinct zeros). The basic idea is to consider conditions for a probability measure to have its support on the real zeros of $\theta$. Then, we use a deep result in algebraic geometry of Curto and Fialkow [3] on the $\mathbb{K}$-moment problem.

In addition, this methodology allows us to also provide a similar necessary and sufficient condition on the coefficients for $\theta$ to have all its zeros real and in a prescribed interval $[a, b]$ of the real line.

## 2. Notation and definitions

Let $\mathbb{R}[x]$ be the ring of real-valued univariate polynomials $u: \mathbb{R} \rightarrow \mathbb{R}$. In a standard fashion, we identify $u$ with its vector of coefficients $\left\{u_{i}\right\}$ when we write

$$
\begin{equation*}
u(x)=\sum_{i=0}^{n} u_{i} x^{i} \tag{2.1}
\end{equation*}
$$

in the canonical basis

$$
\begin{equation*}
1, x, x^{2}, \ldots \tag{2.2}
\end{equation*}
$$

The problem under investigation is thus to characaterize the polynomials $u$ with all its zeros real and nonpositive.

### 2.1. Moment matrix

Given an infinite vector $y \in \mathbb{R}^{\infty}$, let $M(n, y), B(n, y) \in \mathbb{R}^{(n+1) \times(n+1)}$ be the Hankel matrices

$$
M(n, y)=\left[\begin{array}{ccccc}
1 & y_{1} & y_{2} & \cdots & y_{n} \\
y_{1} & y_{2} & y_{3} & \cdots & y_{n+1} \\
\cdots & \cdots & \cdots & \cdots & \cdots \\
y_{n} & y_{n} & y_{n+1} & \cdots & y_{2 n}
\end{array}\right]
$$

and

$$
B(n, y)=\left[\begin{array}{ccccc}
y_{1} & y_{2} & y_{3} & \cdots & y_{n+1} \\
y_{2} & y_{3} & y_{4} & \cdots & y_{n+2} \\
\cdots & \cdots & \cdots & \cdots & \cdots \\
y_{n+1} & y_{n+2} & y_{n+3} & \cdots & y_{2 n+1}
\end{array}\right]
$$

respectively. $M(0, y)$ is just the $(1,1)$-matrix [1]. $M(n, y)$ is called a moment matrix. Whenever $y$ is the vector of moments of some measure $\mu$, then for every vector $q \in \mathbb{R}[x]$ of degree less than $n$, with vector of coefficients $q \in \mathbb{R}^{n+1}$, we have

$$
\begin{equation*}
\langle q, M(n, y) q\rangle=\int q(x)^{2} \mu(d x) \geq 0 \tag{2.3}
\end{equation*}
$$

and therefore, as (2.3) is true for every $q \in \mathbb{R}^{n+1}$, we must have $M(n, y) \succeq 0$, that is, $M(n, y)$ is positive semidefinite.

### 2.2. Localizing matrix

Similarly, given a polynomial $\theta \in \mathbb{R}[x]$ of degree $s$, and given an infinite vector $y \in \mathbb{R}^{\infty}$, define the localizing matrix $M_{\theta}(n, y)$ (with respect to $\theta$ ) to be

$$
M_{\theta}(n, y)(i, j)=\sum_{k=0}^{s} \theta_{k} y_{i+j+k}, \quad \forall i, j \leq n
$$

Observe that $B(n, y)=M_{x}(n, y)$, that is, $B(n, y)$ is a localizing matrix with respect to the polynomial $x \mapsto \theta(x):=x$. The term localizing is used in Curto and Fialkow [3] because if $y$ is the vector of moments of some measure $\mu, M_{\theta}(n, y) \succeq 0$ states a necessary condition for $\mu$ to have its support contained in the algebraic set $\{x \in \mathbb{R}: \theta(x) \geq 0\}$. Indeed if $y$ is the vector of moments of some measure $\mu$, then for every vector $q \in \mathbb{R}[x]$ of degree less than $n$, with vector of coefficients $q \in \mathbb{R}^{n+1}$, we have

$$
\begin{equation*}
\left\langle q, M_{\theta}(n, y) q\right\rangle=\int \theta(x) q(x)^{2} \mu(d x) \tag{2.4}
\end{equation*}
$$

and therefore, as (2.4) is true for every $q \in \mathbb{R}^{n+1}$, we must have $M_{\theta}(n, y) \succeq 0$, whenever the support of $\mu$ is contained in the set $\{x \in \mathbb{R} \mid \theta(x) \geq 0\}$.

Therefore, if $y$ is the vector of moments of some measure $\mu$, the condition $M_{\theta}(n, y)=0$ will state a necessary condition for $\mu$ to have its support on the real zeros of $\theta(x)$. With the additional condition $B(n, y) \preceq 0$, we will state a necessary condition for $\mu$ to have its support on the nonpositive real zeros of $\theta$.

Remark 2.1 In the sequel, we will use the following observation. Let $\theta \in \mathbb{R}[x]$ be a polynomial of degree $n+1$, and let $\left\{a_{i}\right\}, i=1, \ldots, q$, be its distinct zeros (real or complex) with associated multiplicity $n_{i}$. Let $s \in \mathbb{R}^{\infty}$ be the infinite sequence defined by

$$
\begin{equation*}
s_{k}=\frac{1}{n+1} \sum_{i=1}^{q} n_{i} a_{i}^{k}, \quad k=1,2, \ldots \tag{2.5}
\end{equation*}
$$

From the definition of $M_{\theta}(n,$.$) , it then follows that M_{\theta}(n, s)=0$ for all $n=1,2, \ldots$

## 3. Main result

For notational convenience, we consider a polynomial $\theta \in \mathbb{R}[x]$ of degree $n+1$ and, with no loss of generality, we may and will assume that $\theta_{n+1}=1$, that is, we will consider the polynomial $\theta \in \mathbb{R}[x]$ :

$$
x \mapsto \theta(x):=x^{n+1}+\sum_{i=0}^{n} \theta_{i} x^{i}, \quad x \in \mathbb{R} .
$$

We first need to introduce some additional material. Given $n$ fixed, let $e_{k}: \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ be the elementary symmetric functions

$$
e_{k}:=\sum_{1 \leq i_{1}<i_{2}<\cdots<i_{k} \leq n+1} x_{i_{1}} x_{i_{2}} \cdots x_{i_{k}}, \quad k=1,2, \ldots
$$

It is well known that every symmetric polynomial $p \in \mathbb{C}\left[x_{1}, \ldots, x_{n+1}\right]$ is also a member of $\mathbb{C}\left[e_{1}, \ldots, e_{n+1}\right]$.

In particular, denote by $\left\{q_{\alpha}^{(k)}\right\}$ the coefficients in $\mathbb{C}$ of the expansion of $(n+1)^{-1} \sum_{i=1}^{n+1} x_{i}^{k}$ in the basis $\left(e_{1}, \ldots, e_{n+1}\right)$. That is,

$$
\begin{align*}
(n+1)^{-1} \sum_{i=1}^{n+1} x_{i}^{k} & =q_{k}\left(e_{1}, \ldots, e_{n+1}\right) \\
& =\sum_{|\alpha| \leq k} q_{\alpha}^{(k)} e_{1}^{\alpha_{1}} \cdots e_{n+1}^{\alpha_{n+1}}, \quad k=1, \ldots \tag{3.1}
\end{align*}
$$

with $q_{\alpha}^{(k)} \in \mathbb{C}$, for all $\alpha$, and $|\alpha|:=\sum_{i} \alpha_{i}$. In fact, the coefficients $\left\{q_{\alpha}^{(k)}\right\}$ are all in $\mathbb{Q}$ and have a well-known combinatorial interpretation (see e.g. Macdonald [6, Ch. I, Section 6, Example 8] and Beck et al. [2]).

Consider the moment matrix $M(n, s) \in \mathbb{R}^{(n+1) \times(n+1)}$ defined as follows: For all $2<$ $i+j \leq 2 n+2$,

$$
\begin{equation*}
M(n, s)(i, j)=s_{i+j-2}=q_{i+j-2}\left(-\theta_{n}, \theta_{n-1}, \ldots,(-1)^{n+1} \theta_{0}\right), \tag{3.2}
\end{equation*}
$$

where the $q_{i}$ 's are defined in (3.1). Thus, the $s_{i}$ 's are the Newton's sums (here normalized) already considered in Gantmacher [4]. More precisely, if $\theta \in \mathbb{R}[x]$ has $q$ distinct zeros $a_{1}, \ldots, a_{q}$ (real or complex) with associated multiplicity $n_{1}, \ldots, n_{q}$, then

$$
\begin{equation*}
s_{k}=\frac{1}{n+1} \sum_{i=1}^{q} a_{i}^{k} n_{i}, \quad k=0,1, \ldots \tag{3.3}
\end{equation*}
$$

It is important to notice that the number $q$ of all distinct zeros of $\theta$ (real or complex) is equal to the rank of the matrix associated with the quadratic form $Q_{n}: \mathbb{R}^{n} \rightarrow \mathbb{R}$,

$$
\begin{equation*}
x \mapsto Q_{n}(x, x):=\sum_{i, k=0}^{n-1} s_{i+k} x_{i} x_{k}, \quad \forall n \geq q \tag{3.4}
\end{equation*}
$$

see Gantmacher [4, Theorem 6, p. 202]. Similarly, let $B(n, s) \in \mathbb{R}^{(n+1) \times(n+1)}$ be such that for all $1 \leq i, j \leq n+1$,

$$
\begin{equation*}
B(n, s)(i, j)=s_{i+j-1}=q_{i+j-1}\left(-\theta_{n}, \theta_{n-1}, \ldots,(-1)^{n+1} \theta_{0}\right) \tag{3.5}
\end{equation*}
$$

Theorem 3.1 Let $\theta \in \mathbb{R}[x]$ be the polynomial $x \mapsto \theta(x):=x^{n+1}+\sum_{i=0}^{n} \theta_{i} x^{i}$, and let $s \in \mathbb{R}^{\infty}$ be the infinite vector of (normalized) Newton's sums defined in (3.3). Then the following two propositions are equivalent:
(i) All the zeros of $\theta$ are real, nonpositive, and $q$ are distinct.
(ii) $M(n, s) \succeq 0, B(n, s) \preceq 0$ and $\operatorname{rank}(M(n, s))=q$.

Proof: (i) $\Rightarrow$ (ii). Let $a_{1} ; a_{2}, \ldots, a_{q}$ be the $q$ real zeros of $\theta$, all assumed to be nonpositive, and with associated multiplicity $n_{i}, i=1, \ldots, q$. Let $\mu$ be the probability measure on $\mathbb{R}$, defined by

$$
\mu:=\frac{1}{n+1} \sum_{i=1}^{q} n_{i} \delta_{a_{i}}
$$

(where $\delta_{x}$ stands for the Dirac measure at the point $x \in \mathbb{R}$ ), and let $s \in \mathbb{R}^{\infty}$ be its associated infinite vector of moments, that is,

$$
s_{k}=\int_{\mathbb{R}} x^{k} d \mu=\frac{1}{n+1} \sum_{i=1}^{q} n_{i} a_{i}^{k}, \quad k=1,2, \ldots
$$

In other words, the moments of $\mu$ are the (normalized) Newton's sums defined in (3.3).
Therefore, $M(n, s) \succeq 0$ (as it is the moment matrix associated with $\mu$ ) and moreover, since every zero of $\theta$ is real and nonpositive, then, necessarily, $\mu$ has its support contained in $(-\infty, 0]$. This clearly implies $B(n, s) \preceq 0$. Finally, observe that $M(n, s)$ is the matrix associated with the quadratic form $x \mapsto Q_{n+1}(x, x)$ (cf. (3.4)). Therefore, as the number of distinct zeros is $q$, from Gantmacher [4, Theorem 6, p. 202], we must have $q=\operatorname{rank}(M(n, s))$.
(ii) $\Rightarrow$ (i). Remember that since $M(n, s)$ is the matrix associated with the quadratic form $x \mapsto Q_{n+1}(x, x)$ (cf. (3.4)), we know that $\operatorname{rank}(M(n+k, s))=q$ for all $k=0,1, \ldots$ as it is the number of distinct zeros (real or complex) of $\theta$ (and we will show that they all are real). Next, from $M(n, s) \succeq 0$ and $\operatorname{rank}(M(n+k, s))=\operatorname{rank}(M(n, s))=q$, it follows that $M(n+k, s) \succeq 0$ for all $k=0,1, \ldots$. In other words, and in the terminology of Curto and Fialkow [3], the matrices $M(n+k, s)$ are all flat positive extensions of $M(n, s)$, for all $k=1,2, \ldots$.

In addition, observe that from the definition of the $s_{k}$ 's, and as $\theta\left(a_{i}\right)=0$ for all $i=$ $1,2, \ldots, q$, we also have $M_{\theta}(n, s)=0$ (cf. Remark 2.1). Therefore, $s$ also satisfies

$$
\begin{equation*}
M(2 n+1, s) \succeq 0 ; \quad B(n, s) \preceq 0 ; \quad M_{\theta}(n, s)=0 \tag{3.6}
\end{equation*}
$$

Equivalently,

$$
\begin{equation*}
M(2 n+1, s) \succeq 0 ; \quad M_{-x}(n, s) \succeq 0 ; \quad M_{\theta}(n, s)=0 \tag{3.7}
\end{equation*}
$$

But then, from Theorem 1.6 in Curto and Fialkow [3, p. 6] (adapated here to the onedimensional case), $s$ is the vector of moments of $\operatorname{arank}(M(n, s)$ )-atomic (or, $q$-atomic) probability measure with support contained in $\{\theta(x)=0\} \cap(-\infty, 0]$ (the constraint $M_{\theta}(n, s)=$ 0 is equivalent to $M_{\theta}(n, s) \succeq 0$ and $\left.M_{-\theta}(n, s) \succeq 0\right)$.

As $q$ was the number of distinct (real or complex) zeros of $\theta$, this shows that in fact $\theta$ has only real zeros, all nonpositive and $q$ distinct.

If in Theorem 3.1 we drop the condition $B(n, s) \preceq 0$, then $M(n, s) \succeq 0$ becomes a necessary and sufficient condition for $\theta$ to have only real zeros.

We next consider the case where all the zeros are real and in a prescribed interval $[a, b] \subseteq \mathbb{R}$.

Theorem 3.2 Let $[a, b] \subseteq \mathbb{R}, \theta \in \mathbb{R}[x]$ be the polynomial $x \mapsto \theta(x):=x^{n+1}+\sum_{i=0}^{n} \theta_{i} x^{i}$, and let $s \in \mathbb{R}^{\infty}$ be the infinite vector of (normalized) Newton's sums defined in (3.3). Then the following two propositions are equivalent:
(i) All the zeros of $\theta$ are in $[a, b]$, and $q$ are distinct.
(ii) $M(n, s) \succeq 0, b M(n, s) \succeq B(n, s) \succeq a M(n, s)$ and $\operatorname{rank}(M(n, s))=q$.

Proof: The proof mimics that of Theorem 3.1. It is immediate to check that $b M(n, s)-$ $B(n, s)$ is the localizing matrix $M_{b-x}(n, s)$ whereas $B(n, s)-a M(n, s)$ is the localizing matrix $M_{x-a}(n, s)$. Therefore, exactly as in the proof of Theorem 3.1, invoking Theorem 1.6 in Curto and Fialkow [3], the conditions in (ii) are necessary and sufficient for the vector $s$ to be the vector of moments of a probability measure with support in the set

$$
\{x \in \mathbb{R} \mid \theta(x)=0 ; b-x \geq 0 ; x-a \geq 0\}
$$

When $a>-\infty$ and $b<\infty$, the condition $M(n, s) \succeq 0$ is implied by the other one. However, as it stands, Theorem 3.2 includes Theorem 3.1 as a particular case with $a=-\infty$ and $b=0$.

Example Consider the 3rd degree polynomial

$$
x \mapsto \theta(x):=x^{3}+\theta_{2} x^{2}+\theta_{1} x+\theta_{0}, \quad x \in \mathbb{R} .
$$

$M(2, s) \in \mathbb{R}^{3 \times 3}$ is the Hankel matrix

$$
\left[\begin{array}{ccc}
1 & -\theta_{2} / 3 & \left(\theta_{2}^{2}-2 \theta_{1}\right) / 3 \\
-\theta_{2} / 3 & \left(\theta_{2}^{2}-2 \theta_{1}\right) / 3 & -\theta_{2}^{3} / 3+\theta_{1} \theta_{2}-\theta_{0} \\
\left(\theta_{2}^{2}-2 \theta_{1}\right) / 3 & -\theta_{2}^{3} / 3+\theta_{1} \theta_{2}-\theta_{0} & \theta_{2}^{4} / 3-4 \theta_{2}^{2} \theta_{1} / 3+2 \theta_{1}^{2} / 3+4 \theta_{2} \theta_{0} / 3
\end{array}\right],
$$

whereas $B(2, s) \in \mathbb{R}^{3 \times 3}$ is the Hankel matrix

$$
\left[\begin{array}{ccc}
-\theta_{2} / 3 & \left(\theta_{2}^{2}-2 \theta_{1}\right) / 3 & -\theta_{2}^{3} / 3+\theta_{1} \theta_{2}-\theta_{0} \\
* & -\theta_{2}^{3} / 3+\theta_{1} \theta_{2}-\theta_{0} & \theta_{2}^{4} / 3-4 \theta_{2}^{2} \theta_{1} / 3+2 \theta_{1}^{2} / 3+4 \theta_{2} \theta_{0} / 3 \\
* & * & -\theta_{2}^{5} / 3+5\left(\theta_{2}^{3} \theta_{1}-\theta_{2}^{2} \theta_{0}-\theta_{2} \theta_{1}^{2}+\theta_{1} \theta_{0}\right) / 3
\end{array}\right],
$$

where we have displayed only the upper triangle.

## 4. Conclusion

In this paper we have provided finitely many necessary and sufficient conditions on the coefficients of a polynomial $\theta \in \mathbb{R}[x]$, for $\theta$ to have only real zeros, all in a prescribed
interval $[a, b]$ of the real line. Those conditions are diffferent from those of Šiljak stated for $a, b= \pm \infty$.

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