The Automorphism Group and the Convex Subgraphs of the Quadratic Forms Graph in Characteristic 2

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Abstract. We determine the automorphism group and the convex subgraphs of the quadratic forms graph Quad(n, q), q even.

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1. Introduction

The quadratic forms graph Quad(n, q) was introduced by Egawa [2]. It has as vertices all quadratic forms on an n-dimensional vector space over GF(q). Two forms f and g are adjacent in Quad(n, q) whenever rank (f - g) = 1 or 2. If n = 1 or 2, then Quad(n, q) is a complete graph; the graph Quad(3,2) is isomorphic to the distance-transitive graph Alt(4, 2) [2]. If $n \ge 3$ and $(n, q) \ne (3, 2)$ then Quad(n, q) is distance-regular, but not distance-transitive. In this paper we investigate the properties of the graph Quad(n, q) when q is even. We determine its automorphism group and describe all its convex (i.e., geodetically closed) subgraphs. In the case of odd q both problems have been solved earlier. The group Aut Quad(n, q), q odd, was determined in [4]. The convex subgraphs of Quad(n, q), q odd, were determined in [5].

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Over a field of odd characteristic, the quadratic forms graph is the $\{1,2\}$ -distance graph of the corresponding symmetric bilinear forms graph. In characteristic 2 this construction fails, and maybe it is the reason why AutQuad(n, q), q even, was not determined earlier. It is quite clear that the mappings $f \mapsto f + g$ ($g \in$ Quad(n, q)) and $f \mapsto \theta^{-1} \circ f \circ g$ ($g \in \Gamma L_n(q)$, θ is the field automorphism associated with g) are automorphisms of Quad(n, q). Together they generate a group Aut⁰ Quad $(n, q) \cong q^{n(n+1)/2} : \Gamma L_n(q)$, which was thought to be the full automorphism group of Quad(n, q). It is a little bit of a surprise that this natural conjecture fails, and Quad(n, q), q even, has more automorphisms.

THEOREM 1.1. Assume $n \ge 3$ and $(n, q) \ne (3, 2)$. If q is a power of 2, then Aut Quad(n, q) is the product of Aut⁰ Quad(n, q) and the group of order q^n constituted by the following automorphisms:

$$f \mapsto f + B_f(\cdot, v)^2 \quad (v \in V),$$

here B_f is the alternating form associated with f, and V the basic n-dimensional vector space over GF(q).

It is easy to check that the permutations given in the theorem are indeed automorphisms of Quad(n, q) and that they form an elementary abelian group Eof order q^n . Also, a nonidentity automorphism $e \in E$ preserves the rank of every form, but maps some (even rank) forms of plus type to forms of minus type, and vice versa. In particular, E has trivial intersection with $Aut^0 Quad(n, q)$.

For a subspace $U \leq V$ and a form $f \in \text{Quad}(n, q)$ let Q(f, U) denote the subgraph in Quad(n, q) induced by the set of forms $\{f + g | \text{Rad}(g) \geq U\}$. Then Q(f, U) is naturally isomorphic to $\text{Quad}(n - \dim U, q)$. Since the parameters c_i of Quad(n, q) do not depend on n, the subgraphs Q(f, U) are convex.

THEOREM 1.2. If Σ is a noncomplete convex subgraph of Quad(n, q), q even, then $\Sigma = Q(f, U)$ for some $f \in \text{Quad}(n, q)$ and a subspace U < V, dim $U \le n - 3$.

The maximal cliques of Quad(n, q) were determined in [3].

2. Preliminaries

Throughout the paper Γ denotes the graph Quad(n, q) and V denotes the *n*-dimensional vector space over GF(q) on which the quadratic forms from Γ (and associated alternating forms) are defined, q is a power of 2. Here and below we use the same letter to denote a graph and its set of vertices.

For a given $f \in \Gamma$, we denote by R(f) the set $\{f + h | \text{rank } (h) = 1\}$. Clearly, R(f) is a clique of size q^n ; after [1, section 9.6], we call such cliques R_1 -cliques. If B_f denotes the alternating form associated with f (i.e., $B_f(x, y) =$

f(x + y) - f(x) - f(y) then $B_f = B_g$ if and only if R(f) = R(g). It will be convenient to identify R_1 -cliques and corresponding alternating form. Under this identification we will use notation like Rad (X - Y), rank (X), where X and Y are R_1 -cliques. Two R_1 -cliques R(f) and R(g) are at distance 1 from each other whenever rank $(B_f - B_g) = 2$. It means that the identification of R(f) and B_f reveals the structure of the alternating forms graph Alt(n, q) on the set Δ of R_1 -cliques.

Every R_1 -clique X naturally carries the structure of an n-dimensional affine space (denote it by Aff X). The *i*-dimensional subspaces of Aff X are all sets of the form $S(f, U) = \{f + h | h \in R(0), \text{ Rad } (h) \ge U\}$, where $f \in X$ and U is an (n - i)-dimensional subspace of V. When U is fixed and f runs through X, the sets S(f, U) form a parallel class of *i*-spaces in Aff X. Notice also that the intersection of subspaces $S(f, U_1)$ and $S(f, U_2)$ is the subspace $S(f, \langle U_1, U_2 \rangle)$.

LEMMA 2.1. Suppose R_1 -cliques X and Y are at distance s from each other. Then for every $f \in X$ one has that $\Gamma_s(f) \cap Y = S(g, \text{Rad}(X - Y))$ for some $g \in Y$, i.e., $\Gamma_s(f) \cap Y$ is a subspace of Aff Y of dimension 2s.

For an alternating form $B \in Alt(n, q)$ and a subspace $U \leq V$ let $A(B, U) = \{B + B' | \text{ Rad } (B') \geq U\}$. The subgraph A(B, U) of Alt(n, q) is naturally isomorphic to $Alt(n - \dim U, q)$. The following result was proved in [5, Proposition (5.26)].

LEMMA 2.2. Every noncomplete convex subgraph of $\Delta = Alt(n, q)$ coincides with A(B, U) for some B and U < V, dim $U \le n - 4$.

LEMMA 2.3. If $n \ge 3$ and $(n, q) \ne (3, 2)$ then Γ does not contain a subgraph $\Sigma \cong Alt(n, q)$ such that Σ intersects every R_1 -clique of Γ in exactly one vertex.

Proof. Suppose that there exists such a subgraph Σ . Without loss of generality we may assume that 0 is a vertex of Σ . First consider the case q > 2 and $n \ge 3$.

It is known [1, proof of 9.5.6] that the singular lines of Alt(n, q), containing the zero alternating form, are the sets $L(B) = \{\alpha B | \alpha \in GF(q)\}$, where B is a rank 2 alternating form (in case n = 3 Alt(3, q) is complete and still L(B) is a part of the (trivial) singular line). Let $L = \{0, f, g, ...\}$ be the preimage of L(B) in Σ . Then, clearly, Rad (f) = Rad (g). Let $h \in \{0, f\}^{\perp}$ (in Γ) and let $t \in R(h) \cap \Sigma$. Then t is adjacent to 0, f and g. Since h also is adjacent to f, Rad (h-t) > Rad (f). Therefore, the equality Rad (f) = Rad (g) implies that h is adjacent to g. It means that L is contained in a singular line of Γ . On the other hand, it is known [2, Lemma 3.6] that, for an f of rank 2, the singular line $\{0, f\}^{\perp \perp}$ of Γ has size 2. Since |L| = q > 2, we obtain a contradiction.

Now let q = 2 and $n \ge 4$. By [7, Proposition 3.1], the local graph $\Gamma(0)$ is isomorphic to the Grassmann graph $\begin{bmatrix} W \\ 2 \end{bmatrix}$ for an (n + 1)-dimensional vector space

W over GF(2). Let us identify $\Gamma(0)$ with $\begin{bmatrix} W \\ 2 \end{bmatrix}$.

Choose $f \in \Sigma_2(0)$. Then by Lemma 2.2 the convex closure of 0 and f(in Σ) is a subgraph $\Theta \cong \text{Alt}(4, 2)$. The local subgraph $\Theta(0)$ is isomorphic to the Grassmann graph $\begin{bmatrix} U\\2 \end{bmatrix}$ for a 4-dimensional vector space U over GF(2). By [5, Proposition (5.14)], the isomorphism between $\Theta(0)$ and $\begin{bmatrix} U\\2 \end{bmatrix}$ can be established by choosing as U certain 4-dimensional subspace of W (i.e., $\Theta(0) = \begin{bmatrix} U\\2 \end{bmatrix}$ for that subspace U). On the other hand, f must be rank 4 as a quadratic form (otherwise, $\Gamma(f)$ contains a rank 1 form). It was proved in [7, Lemma 5.7 and the remark after it] that, for a rank 4 form f, $\Gamma(0)\cap\Gamma(f)$ is not contained in $\begin{bmatrix} U\\2 \end{bmatrix}$ for any 4-dimensional subspace U < W; a contradiction since $\Gamma(0)\cap\Gamma(f) = \Theta(0)\cap\Theta(f)$.

3. The automorphism group

In this section we prove Theorem 1.1. Throughout the section we assume that $n \ge 3$. If $(n, q) \ne (3, 2)$, it was shown in [2] that $G = \operatorname{Aut}\operatorname{Quad}(n, q)\operatorname{does}$ not mix the edges (f, g) with rank (f-g) = 1 and the edges with rank (f-g) = 2. It implies that, under the above restriction, G leaves the set of R_1 -cliques invariant. It defines a homomorphism of G into the group $\operatorname{Aut}\operatorname{Alt}(n, q)$. The proof of Theorem 1.1 will be given in two steps. First we show that G and the group $G_0 = E \cdot \operatorname{Aut}^0\operatorname{Quad}(n, q)$ from the introduction have the same kernel under this homomorphism. The second step is to show that G and G_0 have the same image in $\operatorname{Aut}\operatorname{Alt}(n, q)$.

Let K be the subgroup of G, consisting of all the automorphisms of Γ , stabilizing every R_1 -clique. Notice that until Proposition 3.2 we do not exclude the case (n, q) = (3, 2).

LEMMA 3.1. For every R_1 -clique X, K induces on X the group of translations of Aff X.

Proof. It suffices to prove that every $a \in K$ induces a translation of Aff X. It follows from Lemma 2.1 that a preserves every parallel class of subspaces in Aff X, and hence a is either a translation or a collineation. Suppose a is a nontrivial collineation with a center $x \in X$ (in particular, q > 2). Take an R_1 -clique Y at distance 1 from X. By Lemma 2.1, $S = \Gamma(x) \cap Y$ is a plane of Aff Y, and $T = \Gamma(y) \cap X$ (y is an arbitrary element of S) is a plane in Aff X. Clearly, a stabilizes T and does not stabilize every plane parallel to T. By Lemma 2.1, adjacency relation establishes a bijection between the parallel classes of S and T (in Aff Y and Aff X, respectively). Consequently, a stabilizes S and does not stabilize every plane of Aff Y, parallel to S. It follows that a cannot induce a translation of Aff Y, hence it induces a nontrivial collineation.

By connectivity, a induces a nontrivial collineation on every R_1 -clique Y. In

particular, a fixes exactly one form t_Y in every Y. Moreover, the above argument shows that t_{Y_1} and t_{Y_2} are neighbors whenever Y_1 and Y_2 are such. It means that the subgraph Σ induced by all t_Y 's is naturally isomorphic to Alt(n, q). This contradicts Lemma 2.3.

LEMMA 3.2. Let $A \leq K$ and let Σ be the subgraph induced by all the vertices of Γ , fixed by A. Then

(1) for every f ∈ Σ, one has R(f) ⊆ Σ;
(2) the image of Σ in Δ = Alt(n, q) is a convex subgraph.

Proof. The part (1) follows from Lemma 3.1. For (2), let $X, Y \subseteq \Sigma$ be two R_1 -cliques at distances s > 1 from each other. Suppose that an R_1 -clique T lies on a shortest path from X to Y, say, rank (X - Y) = 2i and rank $(T - Y) = 2j = \operatorname{rank}(X - Y) - \operatorname{rank}(X - T) = 2s - 2i$. By Lemma 2.1, for $x \in X$ and $y \in Y, S_1 = \Gamma_i(x) \cap T$, is a 2*i*-dimensional subspace of Aff T, and $S_2 = \Gamma_j(y) \cap T$ is a 2*j*-dimensional subspace of Aff T. Clearly, we may choose x and y in such a way that $S_1 \cap S_2 \neq \emptyset$. According to the remark before Lemma 2.1, $S_1 \cap S_2 = S(f, \langle \operatorname{Rad}(X - T), \operatorname{Rad}(T - Y) \rangle)$ for an $f \in S_1 \cap S_2$. But the equality rank $(X - Y) = \operatorname{rank}(X - T) + \operatorname{rank}(T - Y)$ implies that $\langle \operatorname{Rad}(X - T)$, $\operatorname{Rad}(T - Y) = V$ [1, Lemma 9.5.5 (i)]. It means that $S_1 \cap S_2$ consists of a unique form, and hence A fixes T elementwise by Lemma 3.1.

PROPOSITION 3.1. K is contained in G_0 .

Proof. It is easy to see that $|K \cap G_0| = q^{2n}$. Hence it suffices to prove that $|K| \le q^{2n}$.

First we consider the case of even n (recall that $n \ge 3$). Let f be a form of rank n. By Lemma 2.2, the geodetic closure of $\{R(0), R(f)\}$ coincides with the whole of Δ . Hence Lemma 3.2 implies that the stabilizer in K of both 0 and f is trivial. Therefore, $|K| \le |R(0)| \cdot |R(f)| = q^{2n}$.

Now let us separately consider the case n = 3. Choose a rank 2 form fand let X = R(f). Let Y be an R_1 -clique such that Rad $(Y) \neq \text{Rad}(X)$. This condition and Lemma 2.1 imply that $\Gamma(0) \cap Y$ and $\Gamma(f) \cap Y$ are nonparallel planes of Aff Y. Hence $L = \Gamma(0) \cap \Gamma(f) \cap Y$ is a line of Aff Y. Pick a form $g \in L$. If T is an R_1 -clique such that Rad $(T) \not\leq \langle \text{Rad}(X) \text{ Rad}(Y) \rangle$, then the line $\Gamma(0) \cap \Gamma(f) \cap T$ is not parallel to the plane $\Gamma(g) \cap T$ and hence $\Gamma(0) \cap \Gamma(f) \cap \Gamma(g) \cap T$ has cardinality 1. It means that an element of K fixes T whenever it fixes 0, f and g. Let T' be an arbitrary R_1 -clique different from X, Y and T. Then Rad (T') is not contained in at least one of $\langle \text{Rad}(X)$, Rad $(Y) \rangle$, $\langle \text{Rad}(X), \text{Rad}(T) \rangle$, and $\langle \text{Rad}(Y), \text{Rad}(T) \rangle$. We can repeat the above argument for appropriate R_1 -cliques to obtain that an element K fixes T' whenever it fixes 0, f, and g. Thus we have shown that the subgroup of K fixing 0, f and g is trivial. Now we can estimate the order of K. The stabilizer of 0 moves f within the plane $\Gamma(0) \cap X$. The stabilizer of 0 and f moves g within the line L. Therefore, $|K| \le q^{3+2+1} = q^6$.

Finally, let us consider the case n > 3 is odd. Choose a form f of the maximal even rank 2s = n - 1. Let g be a rank 2 form such that Rad $(f) \not\leq \text{Rad}(g)$. Then Lemma 2.2 implies that the geodetic closure in Δ of R(0), R(f), and R(g) coincides with the whole of Δ . By Lemma 3.2, the stabilizer in K of 0, f and g is trivial. By Lemma 2.1, $H = \Gamma_s(0) \cap R(f)$ is a hyperplane of Aff R(f). Furthermore, $S_1 = \Gamma_s(f) \cap R(g)$ is a hyperplane of Aff R(g), $S_2 = \Gamma(0) \cap R(g)$ is a plane of Aff R(g) and S_2 is not parallel to S_1 . Hence $|K| \leq |R(0)| \cdot |H| \cdot |S_1 \cap S_2| = q^{n+(n-1)+1} = q^{2n}$.

In case $(n, q) \neq (3, 2)$, K coincides with the kernel of G acting on Δ . Hence, in order to prove Theorem 1.1 it remains to establish the following.

PROPOSITION 3.2. Assume $(n, q) \neq (3, 2)$. Then the images of G and G_0 in Aut Δ coincide.

Proof. In what follows, a bar over an element, or a subgroup of G means taking image in the action on Δ .

If $n \ge 5$, then Aut Δ is known to be \overline{G}_0 [6], so the assertion is trivial. In case n = 4 the automorphism group of Δ is twice larger (i.e., Aut $\Delta = \overline{G}_0.2$), since it contains an element interchanging the two classes Q_1 and Q_2 of maximal cliques in Δ . These two classes are represented, respectively, by the cliques

$$Q_1 = \{B \in \Delta(0) | \operatorname{Rad} (B) \le U_1\} \cup \{0\}$$

and

$$Q_2 = \{B \in \Delta | \text{Rad} (B) \ge U_2\},\$$

where U_1 and U_2 are fixed subspaces of V of dimensions 3 and 1, respectively. Let $f \in \Gamma$ be a rank 1 form, such that Rad $f = U_1$. Then 0 and f have the same set of neighbors in the preimage of Q_1 . On the other hand, the preimage of Q_2 , naturally isomorphic to Quad(3, q), does not contain a pair of vertices with this property. It follows that \overline{G} leaves Q_1 and Q_2 invariant and, hence, $\overline{G} = \overline{G}_0$.

It remains to consider the case n = 3, q > 2. In this case Δ is a complete graph with q^3 vertices. For $f \in \Gamma$ and a subspace U < V, dim U = n - 2, the subgraph $Q(f, U) \cong \text{Quad}(2, q)$ (see Introduction) is a clique of size q^3 . Such cliques will be called *cubic*. Consider the plane S = S(x, U) of Aff R(x). Then S^{\perp} coincides with the union of R(x) and the cubic clique Q = Q(x, U). Moreover, no element from $Q \setminus S$ is adjacent to an element from $R(x) \setminus S$. Since the set of planes of Aff X, where X runs through all R_1 -cliques, is invariant under G, this implies that the set of cubic cliques is also invariant under the action of G. Now the vertices of Δ and the images of the cubic cliques (each image consists of q elements) form a 3-dimensional affine space over GF(q). Since \bar{G}_0 is isomorphic to the full automorphism group of that affine space, we obtain $\bar{G} = \bar{G}_0$.

4. Convex subgraphs

In this section we prove Theorem 1.2. Clearly, it suffices to consider the case $n \ge 3$; we start with n = 3.

PROPOSITION 4.1. Let n = 3 and let $f \in \Gamma$ be a form of rank 3. Then the convex closure of 0 and f coincides with the whole of Γ .

Proof. Let C denote the convex closure of 0 and f. Let X be an R_1 -clique such that Rad $(X) \neq$ Rad (R(f)). Then the line $L_1 = \Gamma(0) \cap \Gamma(f) \cap X$ of Aff X is contained in C. Choose now an R_1 -clique Y, such that Rad $(Y) \not\leq (\text{Rad}(R(f)))$, Rad (X)). Then the line $L_2 = \Gamma(0) \cap \Gamma(f) \cap Y$ of Aff Y also is contained in C. Moreover, for $x \in L_1$ and $y \in L_2$, one has that L_1 is not parallel to the plane $\Gamma(y) \cap X$ and L_2 is not parallel to the plane $\Gamma(x) \cap Y$. Now every $a \in X$ is adjacent to every x on L_1 and to some y on L_2 . Clearly, we can choose x to be nonadjacent to that y. Therefore, a belongs to C. It follows that X (and, symmetrically, Y) is contained in C. Notice now that the sets of lines A(X, U), where $X \in \Delta$ and U < V has dimension 1, makes Δ an affine 3-space. In terms of this affine space the above conclusion can be rephrased as follows: if P, Q, $R \in \Delta$ are noncollinear and $P \cap C \neq \emptyset \neq Q \cap C$, then $R \subseteq C$. Now for every R_1 -clique T we can choose two out of three R_1 -cliques R(f), X and R(0) to form together with T a noncollinear triple. It means that $T \subseteq C$ and hence $C = \Gamma$.

Recall that $\Delta \cong \operatorname{Alt}(n, q)$ is the graph of R_1 -cliques.

LEMMA 4.1. If Σ is a convex subgraph of Γ then the image of Σ in Δ is convex.

Proof. Let X and Y be two R_1 -cliques at distance s > 1 from each other, such that $X \cap \Sigma \neq \emptyset \neq Y \cap \Sigma$. Let T be an R_1 -clique such that T is at distance i from X and at distance j from Y with s = i + j. It suffices to prove that $T \cap \Sigma$ is nonempty.

Let $x \in X \cap \Sigma$ and $y \in Y \cap \Sigma$. If rank (x - y) = 2s + 1 then $\Gamma_s(y) \cap X$ is a nonempty set contained in Σ . Replacing x by any element from $\Gamma_s(y) \cap X$, we may assume without loss of generality that rank (x - y) = 2s. By Lemma 2.1, both x and y belong to the subgraph $\Gamma_0 = Q(x, \text{Rad } (X - Y)) \cong \text{Quad}(2s, q)$. Since Rad $(X - Y) = \text{Rad } (X - T) \cap \text{Rad } (T - Y)$ [1, Lemma 9.5.5 (i)], we have that $T \cap \Gamma_0 \neq \emptyset$. Also Γ_0 is a convex subgraph and hence $\Sigma_0 = \Gamma_0 \cap \Sigma$ is convex. It means that we can substitute Γ_0 and Σ_0 in place of Γ and Σ . In other words we may assume that n = 2s. Finally, $V = \langle \text{Rad} (X - T), \text{Rad} (T - Y) \rangle$ implies that the 2*i*-dimensional subspace $\Gamma_i(x) \cap T$ and the 2*j*-dimensional subspace $\Gamma_j(y) \cap T$ of Aff T must intersect each other in exactly one point.

According to this lemma and Lemma 2.2, the image of Σ must be a clique, or a natural subgraph Alt $(k, q), k \leq n$.

PROPOSITION 4.2. Suppose $\Sigma \subseteq \Gamma$ is convex and its image in Δ is a clique. Then either Σ is a clique, or $\Sigma = Q(f, U) \cong \text{Quad}(3, q)$ for an $f \in \Sigma$ and some subspace U < V, dim U = n - 3.

Proof. Suppose Σ is not a clique. Then there exist $f, g \in \Sigma$ such that rank (f-g) = 3. By Proposition 4.1, the closure Σ_0 of f and g coincides with $Q(f, \operatorname{Rad} (f-g)) \cong \operatorname{Quad}(3, q)$. Notice that the image of Σ_0 in Δ is a maximal clique. It follows that the images of Σ and Σ_0 coincide. Suppose $\Sigma \neq \Sigma_0$ and $x \in \Sigma \setminus \Sigma_0$. Let X = R(x) and let $Y \neq X$ be another R_1 -clique such that $Y \cap \Sigma \neq \emptyset$. Then also $T \cap \Sigma_0 \neq \emptyset$. Choose $y \in Y \cap \Sigma_0$. Then the plane $\Gamma(y) \cap X$ is contained in Σ_0 and hence rank (x - y) = 3. Moreover, Rad $(x - y) \neq \operatorname{Rad} (f - g)$. One more application of Proposition 4.1 gives that the image of Σ is bigger than the image of Σ_0 ; a contradiction.

PROPOSITION 4.3. Suppose that Σ is a convex subgraph of Γ such that the image of Σ in Δ coincides with A(B, U) for some alternating form B and subspace U < V, dim $U \le n - 4$. Then $\Sigma = Q(f, U)$ for an $f \in \Sigma$.

Proof. Let $f \in \Sigma$ and $\Sigma_0 = Q(f, U)$. We first prove that $\Sigma \subseteq \Sigma_0$. Indeed, let an R_1 -clique $Y \in A(B, U)$ be a neighbor of R(f). Suppose there is $g \in Y \cap \Sigma$ such that $g \notin Q(f, U)$. Then rank (g - f) = 3 and Rad $(g - f) \not\geq U$. By Proposition 4.1 it follows that $Q(f, \text{Rad } (g - f)) \subseteq \Sigma$. But $A(B_f \text{ Rad } (g - f)) \not\subseteq A(B, U) = A(B_f, U)$, a contradiction. Hence $Y \cap \Sigma \subseteq \Sigma_0$. By connectivity of A(B, U), we obtain that $\Sigma \subseteq \Sigma_0$. It means that without loss of generality we may assume that Σ covers the whole of Δ (i.e., U = 0).

Now we claim that there is an R_1 -clique X such that $|X \cap \Sigma| > 1$. Indeed, suppose $|X \cap \Sigma| = 1$ for every R_1 -clique X. Let $\{t_X\} = X \cap \Sigma$. If two R_1 -cliques X and Y are adjacent then t_X and t_Y are adjacent, otherwise Proposition 4.1 forces a contradiction. Therefore, Σ is isomorphic to Δ ; a contradiction with Lemma 2.3, since $n \ge 4$.

Let X be an R_1 -clique such that $x_1 \neq x_2 \in X \cap \Sigma$. Let L be the line of Aff X containing x_1 and x_2 . Let Y be an R_1 -clique at distance 1 from X, such that for $y \in Y$ the plane $\Gamma(y) \cap X$ is not parallel to L. Notice that $\Gamma(x_1) \cap Y \cap \Sigma$ is nonempty. Indeed, if $y \in Y \cap \Sigma$ is not adjacent to x_1 then the whole plane $\Gamma(x_1) \cap Y$ is contained in Σ . Let us choose $y \in \Gamma(x_1) \cap Y \cap \Sigma$. Since L is not parallel to $\Gamma(y) \cap X$, y is not adjacent to x_2 . By convexity of Σ , $\Gamma(y) \cap X \subseteq \Sigma$. It follows that all planes of Aff X, which contain x_1 and do not contain x_2 ,

are contained in Σ . Substituting now other elements of X in place of x_2 we establish that $X \subseteq \Sigma$.

Finally, for an R_1 -clique Y at distance 1 from X, and for $y \in Y \cap \Sigma$ we can find an $x \in X$ which is not adjacent to y. Therefore, $Y \cap \Sigma \supseteq \Gamma(x) \cap Y$ has cardinality at least q^2 . Applying the argument from the previous paragraph to the R_1 -clique Y, we obtain $Y \subseteq \Sigma$. Repeating this argument and using the connectivity of Δ we eventually establish that $\Gamma = \Sigma$.

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