



**THE EXTENSION OF MAJORIZATION INEQUALITIES WITHIN THE
FRAMEWORK OF RELATIVE CONVEXITY**

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ABSTRACT. Some of the basic inequalities in majorization theory (Hardy-Littlewood-Pólya, Tomić-Weyl and Fuchs) are extended to the framework of relative convexity.

Key words and phrases: Relative convexity, Majorization, Abel summation formula.

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Relative convexity is related to comparison of quasi-arithmetic means and goes back to B. Jessen. See [5], Theorem 92, p. 75. Later contributions came from G. T. Cargo [2], N. Elezović and J. Pečarić [3], M. Bessenyei and Z. Páles [1], C. P. Niculescu [10] and many others. The aim of this note is to prove the extension to this framework of all basic majorization inequalities, starting with the well known inequality of Hardy-Littlewood-Pólya. The classical text on majorization theory is still the monograph of A. W. Marshall and I. Olkin [7], but the results involved in what follows can be also found in [8] and [11].

Throughout this paper f and g will be two real-valued functions with the same domain of definition X . Moreover, g is assumed to be a nonconstant function.

Definition 1. We say that f is convex with respect to g (abbreviated, $g \triangleleft f$) if

$$\begin{vmatrix} 1 & g(x) & f(x) \\ 1 & g(y) & f(y) \\ 1 & g(z) & f(z) \end{vmatrix} \geq 0$$

whenever $x, y, z \in X$ and $g(x) \leq g(y) \leq g(z)$.

When X is an interval, and g is continuous and strictly monotonic, this definition simply means that $f \circ g^{-1}$ is convex in the usual sense on the interval $Y = g(X)$. Our definition is strictly larger since we do not make any assumption on the monotonicity of g . For example,

$$f \triangleleft f^\alpha \text{ for all } f : X \rightarrow \mathbb{R}_+ \text{ and all } \alpha \geq 1.$$

In particular, $\sin \triangleleft \sin^2$ on $[0, \pi]$, and $|x| \triangleleft x^2$ on \mathbb{R} .

Definition 1 allows us to bring together several classes of convex-like functions. In fact,

$$\begin{aligned} f \text{ is convex} &\Leftrightarrow id \triangleleft f \\ f \text{ is log-convex} &\Leftrightarrow id \triangleleft \log f \\ f \text{ is multiplicatively convex} &\Leftrightarrow \log \triangleleft \log f. \end{aligned}$$

Multiplicative convexity means that f acts on subintervals of $(0, \infty)$ and

$$f(x^{1-\lambda}y^\lambda) \leq f(x)^{1-\lambda}f(y)^\lambda$$

for all x and y in the domain of f and all $\lambda \in [0, 1]$. See [9], [11].

Lemma 1. *If $f, g : X \rightarrow \mathbb{R}$ are two functions such that $g \triangleleft f$, then*

$$g(x) = g(y) \text{ implies } f(x) = f(y).$$

Proof. Since g is not constant, then there must be a $z \in X$ such that $g(x) = g(y) \neq g(z)$. The following two cases may occur:

Case 1: $g(x) = g(y) < g(z)$. This yields

$$0 \leq \begin{vmatrix} 1 & g(x) & f(x) \\ 1 & g(x) & f(y) \\ 1 & g(z) & f(z) \end{vmatrix} = (g(z) - g(x))(f(x) - f(y)),$$

so that $f(x) \geq f(y)$. A similar argument gives us the reverse inequality, $f(x) \leq f(y)$.

Case 2: $g(z) < g(x) = g(y)$. This case can be treated in a similar way. \square

The analogue of Fuchs' majorization inequality [4] in the context of relative convexity will be established via a generalization of Galvani's Lemma.

Lemma 2. *If $g \triangleleft f$, then for every $a, u, v \in X$ with $g(u) \leq g(v)$ and $g(a) \notin \{g(u), g(v)\}$, we have*

$$\frac{f(u) - f(a)}{g(u) - g(a)} \leq \frac{f(v) - f(a)}{g(v) - g(a)}.$$

Proof. In fact, the following three cases may occur:

Case 1: $g(a) < g(u) \leq g(v)$. Then

$$\begin{aligned} 0 &\leq \begin{vmatrix} 1 & g(a) & f(a) \\ 1 & g(u) & f(u) \\ 1 & g(v) & f(v) \end{vmatrix} \\ &= (g(u) - g(a))(f(v) - f(a)) - (g(v) - g(a))(f(u) - f(a)) \end{aligned}$$

and the conclusion of Lemma 2 is clear.

Case 2: $g(u) \leq g(v) < g(a)$. This case can be treated in the same way.

Case 3: $g(u) < g(a) < g(v)$. According to the discussion above we have

$$\begin{aligned} \frac{f(u) - f(a)}{g(u) - g(a)} &= \frac{f(a) - f(u)}{g(a) - g(u)} \leq \frac{f(v) - f(u)}{g(v) - g(u)} \\ &= \frac{f(u) - f(v)}{g(u) - g(v)} \leq \frac{f(a) - f(v)}{g(a) - g(v)} = \frac{f(v) - f(a)}{g(v) - g(a)} \end{aligned}$$

and the proof is now complete. \square

Theorem 3 (The generalization of the Hardy-Littlewood-Pólya inequality). *Let $f, g : X \rightarrow \mathbb{R}$ be two functions such that $g \triangleleft f$ and consider points $x_1, \dots, x_n, y_1, \dots, y_n$ in X and real weights p_1, \dots, p_n such that:*

- (i) $g(x_1) \geq \dots \geq g(x_n)$ and $g(y_1) \geq \dots \geq g(y_n)$;
- (ii) $\sum_{k=1}^r p_k g(x_k) \leq \sum_{k=1}^r p_k g(y_k)$ for all $r = 1, \dots, n$;
- (iii) $\sum_{k=1}^n p_k g(x_k) = \sum_{k=1}^n p_k g(y_k)$.

Then

$$\sum_{k=1}^n p_k f(x_k) \leq \sum_{k=1}^n p_k f(y_k).$$

Proof. By mathematical induction. The case $n = 1$ is clear. Assuming the conclusion of Theorem 3 is valid for all families of length $n - 1$, let us pass to the case of families of length n . If $g(x_k) = g(y_k)$ for some index k , then $f(x_k) = f(y_k)$ by Lemma 1, and we can apply our induction hypothesis. Thus we may restrict ourselves to the case where $g(x_k) \neq g(y_k)$ for all indices k . By Abel's summation formula, the difference

$$(1) \quad \sum_{k=1}^n p_k f(y_k) - \sum_{k=1}^n p_k f(x_k)$$

equals

$$\begin{aligned} &\frac{f(y_n) - f(x_n)}{g(y_n) - g(x_n)} \left(\sum_{i=1}^n p_i g(y_i) - \sum_{i=1}^n p_i g(x_i) \right) \\ &+ \sum_{k=1}^{n-1} \left(\frac{f(y_k) - f(x_k)}{g(y_k) - g(x_k)} - \frac{f(y_{k+1}) - f(x_{k+1})}{g(y_{k+1}) - g(x_{k+1})} \right) \left(\sum_{i=1}^k p_i g(y_i) - \sum_{i=1}^k p_i g(x_i) \right) \end{aligned}$$

which, by (iii), reduces to

$$\sum_{k=1}^{n-1} \left(\frac{f(y_k) - f(x_k)}{g(y_k) - g(x_k)} - \frac{f(y_{k+1}) - f(x_{k+1})}{g(y_{k+1}) - g(x_{k+1})} \right) \left(\sum_{i=1}^k p_i g(y_i) - \sum_{i=1}^k p_i g(x_i) \right).$$

According to (ii), the proof will be complete if we show that

$$(2) \quad \frac{f(y_{k+1}) - f(x_{k+1})}{g(y_{k+1}) - g(x_{k+1})} \leq \frac{f(y_k) - f(x_k)}{g(y_k) - g(x_k)}$$

for all indices k .

In fact, if $g(x_k) = g(x_{k+1})$ or $g(y_k) = g(y_{k+1})$ for some index k , this follows from i) and Lemmas 1 and 2.

When $g(x_k) > g(x_{k+1})$ and $g(y_k) > g(y_{k+1})$, the following two cases may occur:

Case 1: $g(x_k) \neq g(y_{k+1})$. By a repeated application of Lemma 2 we get

$$\begin{aligned} \frac{f(y_{k+1}) - f(x_{k+1})}{g(y_{k+1}) - g(x_{k+1})} &= \frac{f(x_{k+1}) - f(y_{k+1})}{g(x_{k+1}) - g(y_{k+1})} \leq \frac{f(x_k) - f(y_{k+1})}{g(x_k) - g(y_{k+1})} \\ &= \frac{f(y_{k+1}) - f(x_k)}{g(y_{k+1}) - g(x_k)} \leq \frac{f(y_k) - f(x_k)}{g(y_k) - g(x_k)}. \end{aligned}$$

Case 2: $g(x_k) = g(y_{k+1})$. In this case, $g(x_{k+1}) < g(x_k) = g(y_{k+1}) < g(y_k)$, and Lemmas 1 and 2 leads us to

$$\begin{aligned} \frac{f(y_{k+1}) - f(x_{k+1})}{g(y_{k+1}) - g(x_{k+1})} &= \frac{f(x_k) - f(x_{k+1})}{g(x_k) - g(x_{k+1})} \\ &= \frac{f(x_{k+1}) - f(x_k)}{g(x_{k+1}) - g(x_k)} \leq \frac{f(y_k) - f(x_k)}{g(y_k) - g(x_k)}. \end{aligned}$$

Consequently, (1) is a sum of nonnegative terms, and the proof is complete. \square

The classical Hardy-Littlewood-Pólya inequality corresponds to the case where g is the identity and $p_k = 1$ for all k . In this case, it is easily seen that the hypothesis i) can be replaced by a weaker condition,

$$(i') \quad g(x_1) \geq \dots \geq g(x_n).$$

When X is an interval, g is the identity map of X , and p_1, \dots, p_n are arbitrary weights, we recover the Fuchs inequality [4] (or [8, p. 165]).

An illustration of Theorem 3 is offered by the following simple example.

Example Suppose that $f : [0, \pi] \rightarrow \mathbb{R}$ is a function such that

$$(3) \quad (f(y) - f(z)) \sin x + (f(z) - f(x)) \sin y + (f(x) - f(y)) \sin z \geq 0$$

for all x, y, z in $[0, \pi]$, with $\sin x \leq \sin y \leq \sin z$. Then

$$(4) \quad f\left(\frac{9\pi}{14}\right) - f\left(\frac{3\pi}{14}\right) + f\left(\frac{\pi}{14}\right) \leq f\left(\frac{\pi}{2}\right) - f\left(\frac{\pi}{6}\right) + f(0).$$

In fact, the condition (3) means precisely that $\sin \triangleleft f$. The conclusion (4) is based on a little computation:

$$\begin{aligned} \sin \frac{\pi}{2} &> \sin \frac{\pi}{6} > \sin 0, & \sin \frac{9\pi}{14} &> \sin \frac{3\pi}{14} > \sin \frac{\pi}{14}, \\ \sin \frac{\pi}{2} &> \sin \frac{9\pi}{14}, \\ \sin \frac{\pi}{2} - \sin \frac{\pi}{6} &> \sin \frac{9\pi}{14} - \sin \frac{3\pi}{14}, \\ \sin \frac{\pi}{2} - \sin \frac{\pi}{6} + \sin 0 &= \sin \frac{9\pi}{14} - \sin \frac{3\pi}{14} + \sin \frac{\pi}{14} = \frac{1}{2}. \end{aligned}$$

The inequality (4) is not obvious even when $f(x) = \sin^2 x$.

In the same spirit we can extend the Tomić-Weyl theorem. This will be done for *synchronous* functions, that is, for functions $f, g : X \rightarrow \mathbb{R}$ such that

$$(f(x) - f(y))(g(x) - g(y)) \geq 0$$

for all x and y in X . For example, this happens when X is an interval and f and g have the same monotonicity. Another example is provided by the pair $f = h^\alpha$ and $g = h \geq 0$, for $\alpha \geq 1$; in this case, $g \triangleleft f$.

Theorem 4 (The extension of the Tomić-Weyl theorem). . *Suppose that $f, g : X \rightarrow \mathbb{R}$ are two synchronous functions with $g \triangleleft f$. Consider points $x_1, \dots, x_n, y_1, \dots, y_n$ in X and real weights p_1, \dots, p_n such that:*

- i) $g(x_1) \geq \dots \geq g(x_n)$ and $g(y_1) \geq \dots \geq g(y_n)$;
- ii) $\sum_{k=1}^r p_k g(x_k) \leq \sum_{k=1}^r p_k g(y_k)$ for all $r = 1, \dots, n$.

Then

$$\sum_{k=1}^n p_k f(x_k) \leq \sum_{k=1}^n p_k f(y_k).$$

Proof. Clearly, the statement of Theorem 4 is true for $n = 1$. Suppose that $n \geq 2$ and the statement is true for all families of length $n - 1$. If there exists a $k \in \{1, \dots, n\}$ such that $g(x_k) = g(y_k)$, then the conclusion is a consequence of our induction hypothesis. If $g(x_k) \neq g(y_k)$ for all k , then we may compute the difference (1) as in the proof of Theorem 3, by using the Abel summation formula. By our hypothesis, all the terms in this formula are nonnegative, hence the difference (1) is nonnegative. \square

The integral version of the above results is more or less routine. For example, using Riemann sums, one can prove the following generalization of Theorem 4:

Theorem 5. *Suppose there are given a pair of synchronous functions $f, g : X \rightarrow \mathbb{R}$, with $g \triangleleft f$, a continuous weight $w : [a, b] \rightarrow \mathbb{R}$, and functions $\varphi, \psi : [a, b] \rightarrow X$ such that*

$f \circ \varphi$ and $f \circ \psi$ are Riemann integrable and $g \circ \varphi$ and $g \circ \psi$ are nonincreasing

and

$$\int_a^x g(\varphi(t))w(t)dt \leq \int_a^x g(\psi(t))w(t)dt \quad \text{for all } x \in [a, b].$$

Then

$$\int_a^b f(\varphi(t))w(t)dt \leq \int_a^b f(\psi(t))w(t)dt.$$

With some extra work one can adapt these results to the context of Lebesgue integrability and symmetric-decreasing rearrangements. Notice that a less general integral form of the Hardy-Littlewood-Pólya inequality appears in [7], Ch. 1, Section D. See [5] and [6] for a thorough presentation of the topics of symmetric-decreasing rearrangements.

Finally, let us note that a more general concept of relative convexity, with respect to a pair of functions, is available in the literature. Given a pair (ω_1, ω_2) of continuous functions on an interval I such that

$$(5) \quad \begin{vmatrix} \omega_1(x) & \omega_1(y) \\ \omega_2(x) & \omega_2(y) \end{vmatrix} \neq 0 \quad \text{for all } x < y,$$

a function $f : I \rightarrow \mathbb{R}$ is said to be (ω_1, ω_2) -convex (in the sense of Pólya) if

$$\begin{vmatrix} f(x) & f(y) & f(z) \\ \omega_1(x) & \omega_1(y) & \omega_1(z) \\ \omega_2(x) & \omega_2(y) & \omega_2(z) \end{vmatrix} \geq 0$$

for all $x < y < z$ in I . It is proved that the (ω_1, ω_2) -convexity implies the continuity of f at the interior points of I , as well as the integrability on compact subintervals of I .

If I is an open interval, $\omega_1 > 0$ and the determinant in the formula (5) is positive, then f is (ω_1, ω_2) -convex if and only if the function $\frac{f}{\omega_1} \circ \left(\frac{\omega_2}{\omega_1}\right)^{-1}$ is convex in the usual sense (equivalently, if and only if $\omega_2/\omega_1 \triangleleft f/\omega_1$).

Historically, the concept of (ω_1, ω_2) -convexity can be traced back to G. Pólya. See [12] and the comments to Theorem 123, p. 98, in [5]. Recently, M. Bessenyei and Z. Páles [1] have obtained a series of interesting results in this context, which opens the problem of a full generalization of the Theorems 3 and 4 to the context of relative convexity in the sense of Pólya. But this will be considered elsewhere.

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