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## AN EXTENSION OF RESULTS OF A. MCD. MERCER AND I. GAVREA

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## Abstract

In this note we extend recent results of A. McD. Mercer and I. Gavrea on convex sequences to other classes of sequences.
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## 1. Introduction

The following result is valid $[1,2]$. Let $\boldsymbol{a}=\left(a_{0}, a_{1}, \ldots, a_{n}\right)$ be a real sequence. The inequality

$$
\begin{equation*}
\sum_{k=0}^{n} a_{k} u_{k} \geq 0 \tag{1.1}
\end{equation*}
$$

holds for every convex sequence $\boldsymbol{u}=\left(u_{0}, u_{1}, \ldots, u_{n}\right)$ if and only if the polynomial

$$
P_{\boldsymbol{a}}(x):=\sum_{k=0}^{n} a_{k} x^{k}
$$

has $x=1$ as a double root and the coefficients $c_{k}(k=0,1, \ldots, n-2)$ of the polynomial

$$
\frac{P_{\boldsymbol{a}}(x)}{(x-1)^{2}}=\sum_{k=0}^{n-2} c_{k} x^{k}
$$

are non-negative. The sufficiency and necessity of this result are due, respectively, to A. McD. Mercer [2] and to I. Gavrea [1].

The purpose of this note is to extend the above result to other classes of sequences $\boldsymbol{u}$.


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## 2. Basic Lemma

A convex cone is a non-empty set $C \subset \mathbb{R}^{n+1}$ such that $\alpha C+\beta C \subset C$ for all non-negative scalars $\alpha$ and $\beta$. We say that a convex cone $C$ is generated by a set $V \subset C$, and write $C=$ cone $V$, if every vector in $C$ can be expressed as a non-negative linear combination of a finite number of vectors in $V$.

Let $\langle\cdot, \cdot\rangle$ stand for the standard inner product on $\mathbb{R}^{n+1}$. The dual cone of $C$ is the cone defined by

$$
\text { dual } C:=\left\{\boldsymbol{u} \in \mathbb{R}^{n+1}:\langle\boldsymbol{u}, \boldsymbol{v}\rangle \geq 0 \text { for all } \boldsymbol{v} \in C\right\}
$$

It is well-known that

$$
\begin{equation*}
\text { dual dual } C=C \tag{2.1}
\end{equation*}
$$

for any closed convex cone $C \subset \mathbb{R}^{n+1}$ (cf. [3, Theorem 14.1, p. 121]). The result below is a key fact in our considerations. It is a consequence of (2.1) for a finitely generated cone $C=$ cone $\left\{\boldsymbol{v}_{0}, \boldsymbol{v}_{1}, \ldots, \boldsymbol{v}_{p}\right\}$.
Lemma 2.1 (Farkas lemma). Let $\boldsymbol{v}, \boldsymbol{v}_{0}, \boldsymbol{v}_{1}, \ldots, \boldsymbol{v}_{p}$ be vectors in $\mathbb{R}^{n+1}$. The following two statements are equivalent:
(i) The inequality $\langle\boldsymbol{u}, \boldsymbol{v}\rangle \geq 0$ holds for all $\boldsymbol{u} \in \mathbb{R}^{n+1}$ such that $\left\langle\boldsymbol{u}, \boldsymbol{v}_{i}\right\rangle \geq 0$, $i=0,1, \ldots, p$.
(ii) There exist non-negative scalars $c_{i}, i=0,1, \ldots, p$, such that

$$
\boldsymbol{v}=c_{0} \boldsymbol{v}_{0}+c_{1} \boldsymbol{v}_{1}+\cdots+c_{p} \boldsymbol{v}_{p}
$$

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## 3. Main Result

Given a sequence $\boldsymbol{q}=\left(q_{0}, q_{1}, \ldots, q_{r}\right) \in \mathbb{R}^{r+1}$ with $0 \leq r \leq n$, we define
(3.1) $\boldsymbol{v}_{i}:=(\underbrace{0, \ldots, 0}_{i \text { times }}, q_{0}, q_{1}, \ldots, q_{r}, 0, \ldots, 0)=S^{i} \boldsymbol{v}_{0} \in \mathbb{R}^{n+1}$

$$
\text { for } \quad i=0,1, \ldots, n-r \text {. }
$$

Here $S$ is the shift operator from $\mathbb{R}^{n+1}$ to $\mathbb{R}^{n+1}$ defined by

$$
\begin{equation*}
S\left(z_{0}, z_{1}, \ldots, z_{n}\right):=\left(0, z_{0}, z_{1}, \ldots, z_{n-1}\right) \tag{3.2}
\end{equation*}
$$

A sequence $\boldsymbol{u}=\left(u_{0}, u_{1}, \ldots, u_{n}\right) \in \mathbb{R}^{n+1}$ is said to be of $\boldsymbol{q}$-class, if

$$
\begin{equation*}
\left\langle\boldsymbol{u}, \boldsymbol{v}_{i}\right\rangle \geq 0 \text { for all } i=0,1, \ldots, n-r . \tag{3.3}
\end{equation*}
$$

In other words, the $\boldsymbol{q}$-class consists of all vectors of the cone

$$
\begin{equation*}
D:=\text { dual cone }\left\{\boldsymbol{v}_{0}, \boldsymbol{v}_{1}, \ldots, \boldsymbol{v}_{n-r}\right\} . \tag{3.4}
\end{equation*}
$$

Example 3.1.
(a). Set $r=0, q_{0}=1$ and

$$
\boldsymbol{v}_{i}=(\underbrace{0, \ldots, 0}_{i \text { times }}, 1,0, \ldots, 0) \in \mathbb{R}^{n+1} \text { for } i=0,1, \ldots, n \text {. }
$$

Then (3.3) reduces to

$$
u_{i} \geq 0 \text { for } i=0,1, \ldots, n
$$



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Thus $D$ is the class of non-negative sequences.
(b). Put $r=1, q_{0}=-1$ and $q_{1}=1$, and denote

$$
\boldsymbol{v}_{i}=(\underbrace{0, \ldots, 0}_{i \text { times }},-1,1,0, \ldots, 0) \in \mathbb{R}^{n+1} \text { for } i=0,1, \ldots, n-1 \text {. }
$$

Then (3.3) gives

$$
u_{i} \leq u_{i+1} \text { for } i=0,1, \ldots, n-1
$$

which means that $D$ is the class of non-decreasing sequences.
(c). Consider $r=2, q_{0}=1, q_{1}=-2, q_{2}=1$ and

$$
\boldsymbol{v}_{i}=(\underbrace{0, \ldots, 0}_{i \text { times }}, 1,-2,1,0, \ldots, 0) \in \mathbb{R}^{n+1} \text { for } i=0,1, \ldots, n-2
$$

In this case, (3.3) is equivalent to

$$
u_{i+1} \leq \frac{u_{i}+u_{i+2}}{2} \text { for } i=0,1, \ldots, n-2
$$

This says that $\boldsymbol{u}$ is a convex sequence. Therefore $D$ is the class of convex sequences.

Theorem 3.1. Let $\boldsymbol{a}=\left(a_{0}, a_{1}, \ldots, a_{n}\right) \in \mathbb{R}^{n+1}$ and $\boldsymbol{q}=\left(q_{0}, q_{1}, \ldots, q_{r}\right) \in \mathbb{R}^{r+1}$ be given with $0 \leq r \leq n$. Then the inequality

$$
\begin{equation*}
\sum_{k=0}^{n} a_{k} u_{k} \geq 0 \tag{3.5}
\end{equation*}
$$

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holds for every sequence $\boldsymbol{u}=\left(u_{0}, u_{1}, \ldots, u_{n}\right)$ of $\boldsymbol{q}$-class if and only if the polynomial

$$
P_{\boldsymbol{a}}(x):=\sum_{k=0}^{n} a_{k} x^{k}
$$

is divisible by the polynomial

$$
P_{\boldsymbol{q}}(x):=\sum_{k=0}^{r} q_{k} x^{k}
$$

and the coefficients $c_{k}(k=0,1, \ldots, n-r)$ of the polynomial

$$
\frac{P_{\boldsymbol{a}}(x)}{P_{\boldsymbol{q}}(x)}=\sum_{k=0}^{n-r} c_{k} x^{k}
$$

are non-negative.
Proof. The map $\varphi$ that assigns to each sequence $\boldsymbol{b}=\left(b_{0}, b_{1}, \ldots, b_{m}\right)$ the polynomial

$$
\varphi(\boldsymbol{b}):=P_{\boldsymbol{b}}(x):=\sum_{k=0}^{m} b_{k} x^{k}
$$

is a one-to-one linear map from $\mathbb{R}^{m+1}$ to the space of polynomials of degree at most $m$. Also, $\psi:=\varphi^{-1}$ is a one-to-one linear map. It is not difficult to check that

$$
\psi\left(x^{k} P_{\boldsymbol{b}}(x)\right)=S^{k} \psi\left(P_{\boldsymbol{b}}(x)\right)
$$

Therefore, for any polynomial

$$
P_{\boldsymbol{c}}(x):=c_{0}+c_{1} x+\cdots+c_{n-r} x^{n-r}
$$

we have

$$
\begin{aligned}
\psi\left(P_{\boldsymbol{c}}(x) P_{\boldsymbol{q}}(x)\right) & =c_{0} S^{0} \boldsymbol{v}_{0}+c_{1} S^{1} \boldsymbol{v}_{0}+\cdots+c_{n-r} S^{n-r} \boldsymbol{v}_{0} \\
& =c_{0} \boldsymbol{v}_{0}+c_{1} \boldsymbol{v}_{1}+\cdots+c_{n-r} \boldsymbol{v}_{n-r}
\end{aligned}
$$

where $\boldsymbol{v}_{i}$ are given by (3.1). In other words,

$$
\begin{align*}
& P_{\boldsymbol{c}}(x) P_{\boldsymbol{q}}(x)=\varphi\left(c_{0} \boldsymbol{v}_{0}+c_{1} \boldsymbol{v}_{1}+\cdots+c_{n-r} \boldsymbol{v}_{n-r}\right)  \tag{3.6}\\
& \text { for any } \quad \boldsymbol{c}=\left(c_{0}, c_{1}, \ldots, c_{n-r}\right) .
\end{align*}
$$

We are now in a position to show that the following statements are mutually equivalent:
(i) Inequality (3.5) holds for every $\boldsymbol{u}$ of $\boldsymbol{q}$-class.
(ii) $\langle\boldsymbol{a}, \boldsymbol{u}\rangle \geq 0$ for every $\boldsymbol{u} \in$ dual cone $\left\{\boldsymbol{v}_{0}, \boldsymbol{v}_{1}, \ldots, \boldsymbol{v}_{n-r}\right\}$.
(iii) There exist non-negative scalars $c_{0}, c_{1}, \ldots, c_{n-r}$ such that $\boldsymbol{a}=c_{0} \boldsymbol{v}_{0}+c_{1} \boldsymbol{v}_{1}+$ $\cdots+c_{n-r} \boldsymbol{v}_{n-r}$.
(iv) There exist non-negative scalars $c_{0}, c_{1}, \ldots, c_{n-r}$ such that $P_{\boldsymbol{a}}(x)=\left(c_{0}+\right.$ $\left.c_{1} x+\cdots+c_{n-r} x^{n-r}\right) P_{\boldsymbol{q}}(x)$.

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In fact, (ii) is an easy reformulation of (i) (see (3.4)). That (ii) and (iii) are equivalent is a direct consequence of Farkas lemma (see Lemma 2.1). We now show the validity of the implication (iii) $\Rightarrow$ (iv). By (iii) and (3.6), we have

$$
P_{\boldsymbol{a}}(x)=\varphi(\boldsymbol{a})=\varphi\left(c_{0} \boldsymbol{v}_{0}+c_{1} \boldsymbol{v}_{1}+\cdots+c_{n-r} \boldsymbol{v}_{n-r}\right)=P_{\boldsymbol{c}}(x) P_{\boldsymbol{q}}(x)
$$

for certain scalars $c_{k} \geq 0, k=0,1, \ldots, n-r$. Thus (iv) is proved.
To prove the implication (iv) $\Rightarrow$ (iii) assume (iv) holds, that is $P_{\boldsymbol{a}}(x)=$ $P_{\boldsymbol{c}}(x) P_{\boldsymbol{q}}(x)$ with $c_{k} \geq 0, k=0,1, \ldots, n-r$. Then by (3.6),

$$
\begin{aligned}
\boldsymbol{a} & =\psi\left(P_{\boldsymbol{a}}(x)\right)=\psi\left(P_{\boldsymbol{c}}(x) P_{\boldsymbol{q}}(x)\right) \\
& =\psi \varphi\left(c_{0} \boldsymbol{v}_{0}+c_{1} \boldsymbol{v}_{1}+\cdots+c_{n-r} \boldsymbol{v}_{n-r}\right) \\
& =c_{0} \boldsymbol{v}_{0}+c_{1} \boldsymbol{v}_{1}+\cdots+c_{n-r} \boldsymbol{v}_{n-r} .
\end{aligned}
$$

This completes the proof of Theorem 3.1.

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## 4. Applications for Convex Sequences of Order $r$

In this section we study special types of sequences related to difference calculus and generalized convex sequences.

We introduce the difference operator on sequences $\boldsymbol{z}=\left(z_{0}, z_{1}, \ldots, z_{m}\right)$ by

$$
\Delta \boldsymbol{z}:=\left(z_{1}-z_{0}, z_{2}-z_{1}, \ldots, z_{m}-z_{m-1}\right) .
$$

Notice that $\Delta=\Delta_{m}$ acts from $\mathbb{R}^{m+1}$ to $\mathbb{R}^{m}$. We define

$$
\Delta^{0} \boldsymbol{z}:=\boldsymbol{z} \text { and } \Delta^{r} \boldsymbol{z}:=\Delta_{m-r+1} \cdots \Delta_{m-1} \Delta_{m} \boldsymbol{z} \text { for } r=1,2, \ldots, m .
$$

A sequence $\boldsymbol{u} \in R^{n+1}$ is said to be convex of order $r$ (in short, $r$-convex), if

$$
\Delta^{r} \boldsymbol{u} \geq 0
$$

The last inequality is meant in the componentwise sense in $\mathbb{R}^{n+1-r}$, that is

$$
\begin{equation*}
\left\langle\Delta^{r} \boldsymbol{u}, \boldsymbol{e}_{i}\right\rangle \geq 0 \text { for } i=0,1, \ldots, n-r \tag{4.1}
\end{equation*}
$$

where

$$
\boldsymbol{e}_{i}:=(\underbrace{0, \ldots, 0}_{i \text { times }}, 1,0, \ldots, 0) \in \mathbb{R}^{n+1-r} .
$$

In order to relate the $r$-convex sequences to the $\boldsymbol{q}$-class of Section 3, observe that (4.1) amounts to

$$
\left\langle\boldsymbol{u},\left(\Delta^{r}\right)^{T} \boldsymbol{e}_{i}\right\rangle \geq 0 \text { for } i=0,1, \ldots, n-r
$$

where $(\cdot)^{T}$ denotes the transpose. By a standard induction argument, we get

$$
\left(\Delta^{r}\right)^{T} \boldsymbol{e}_{i}=S^{i} \boldsymbol{v}_{0} \text { for } i=0,1, \ldots, n-r
$$

where $S$ is the shift operator from $\mathbb{R}^{n+1}$ to $\mathbb{R}^{n+1}$ given by (3.2), and

$$
\begin{gather*}
\boldsymbol{v}_{0}:=(\boldsymbol{q}, 0, \ldots, 0) \in \mathbb{R}^{n+1} \quad \text { and } \quad \boldsymbol{q}:=\left(q_{0}, q_{1}, \ldots, q_{r}\right)  \tag{4.2}\\
\text { with } q_{j}:=\binom{r}{j}(-1)^{r-j} .
\end{gather*}
$$

As in (3.1), we set

$$
\boldsymbol{v}_{i}:=S^{i} \boldsymbol{v}_{0} \text { for } i=0,1, \ldots, n-r
$$

In summary, the $r$-convex sequences form the $\boldsymbol{q}$-class for $\boldsymbol{q}$ given by (4.2). For example, the class of $r$-convex sequences for $r=0$ (resp. $r=1, r=2$ ) is the class of non-negative (resp. non-decreasing, convex) sequences in $\mathbb{R}^{n+1}$ (cf. Example 3.1).

By virtue of (4.2) we get

$$
P_{\boldsymbol{q}}(x)=\sum_{k=0}^{r} q_{k} x^{k}=(x-1)^{r} .
$$

Therefore we obtain from Theorem 3.1
Corollary 4.1. Let $\boldsymbol{a}=\left(a_{0}, a_{1}, \ldots, a_{n}\right) \in \mathbb{R}^{n+1}$ be given with $0 \leq r \leq n$. Then the inequality

$$
\begin{equation*}
\sum_{k=0}^{n} a_{k} u_{k} \geq 0 \tag{4.3}
\end{equation*}
$$

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holds for every r-convex sequence $\boldsymbol{u}=\left(u_{0}, u_{1}, \ldots, u_{n}\right)$ if and only if the polynomial

$$
P_{\boldsymbol{a}}(x)=\sum_{k=0}^{n} a_{k} x^{k}
$$

has $x=1$ as a root of multiplicity at least $r$, and the coefficients $c_{k}(k=$ $0,1, \ldots, n-r)$ of the polynomial

$$
\frac{P \boldsymbol{a}(x)}{(x-1)^{r}}=\sum_{k=0}^{n-r} c_{k} x^{k}
$$

are non-negative.
Corollary 4.1 extends the mentioned results of A. McD. Mercer and I. Gavrea from $r=2$ to an arbitrary $0 \leq r \leq n$.

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