

Ratio Vectors of

**Polynomial-Like Functions** 

# **RATIO VECTORS OF POLYNOMIAL-LIKE FUNCTIONS**

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Abstract:	Let $p(x)$ be a hyperbolic polynomial-like function of the form $p(x) = (x - r_1)^{m_1} \cdots (x - r_N)^{m_N}$ , where $m_1, \ldots, m_N$ are given positive real numbers and		Page 1	of 21	
	$r_1 < r_2 < \cdots < r_N$ . Let $x_1 < x_2 < \cdots < x_{N-1}$ be the $N-1$ critical points of p lying in $I_k = (r_k, r_{k+1}), k = 1, 2, \dots, N-1$ . Define the ratios		Go E	Back	
$\sigma_k = \frac{m_1+\dots}{m_1+\dots}$	$\sigma_k = \frac{x_k - r_k}{r_{k+1} - r_k}, k = 1, 2, \dots, N-1$ . We prove that $\frac{m_k}{m_k + \dots + m_N} < \sigma_k < \frac{m_1 + \dots + m_k}{m_1 + \dots + m_{k+1}}$ . These bounds generalize the bounds given by earlier authors for		Full S	creen	
	strictly hyperbolic polynomials of degree $n$ . For $N = 3$ , we find necessary and sufficient conditions for $(\sigma_1, \sigma_2)$ to be a ratio vector. We also find necessary and		Clo	se	
	sufficient conditions on $m_1, m_2, m_3$ which imply that $\sigma_1 < \sigma_2$ . For $N = 4$ , we also give necessary and sufficient conditions for $(\sigma_1, \sigma_2, \sigma_3)$ to be a ratio vector and we simplify some of the proofs given in an earlier paper of the author on ratio vectors of fourth degree polynomials. Finally we discuss the monotonicity of the ratios when $N = 4$ .	ient conditions on $m_1, m_2, m_3$ which imply that $\sigma_1 < \sigma_2$ . For $N = 4$ , we give necessary and sufficient conditions for $(\sigma_1, \sigma_2, \sigma_3)$ to be a ratio vector we simplify some of the proofs given in an earlier paper of the author on vectors of fourth degree polynomials. Finally we discuss the monotonicity ratios when $N = 4$ .		nequalitie d applied ics	S

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# 1. Introduction and Main Results

If p(x) is a polynomial of degree  $n \ge 2$  with n distinct real roots  $r_1 < r_2 < \cdots < r_n$ and critical points  $x_1 < x_2 < \cdots < x_{n-1}$ , let

$$\sigma_k = \frac{x_k - r_k}{r_{k+1} - r_k}, \qquad k = 1, 2, \dots, n-1.$$

 $(\sigma_1, \ldots, \sigma_{n-1})$  is called the *ratio vector* of p, and  $\sigma_k$  is called the *k*th ratio. Ratio vectors were first discussed in [4] and in [1], where the inequalities

$$\frac{1}{n-k+1} < \sigma_k < \frac{k}{k+1}, \qquad k = 1, 2, \dots, n-1$$

were derived. For n = 3 it was shown in [1] that  $\sigma_1$  and  $\sigma_2$  satisfy the polynomial equation  $3(1 - \sigma_1)\sigma_2 - 1 = 0$ . In addition, necessary and sufficient conditions were given in [5] for  $(\sigma_1, \sigma_2)$  to be a ratio vector. For n = 4, a polynomial, Q, in three variables was given in [5] with the property that  $Q(\sigma_1, \sigma_2, \sigma_3) = 0$  for any ratio vector  $(\sigma_1, \sigma_2, \sigma_3)$ . It was also shown that the ratios are monotonic–that is,  $\sigma_1 < \sigma_2 < \sigma_3$  for any ratio vector  $(\sigma_1, \sigma_2, \sigma_3)$ . For n = 3,  $\frac{1}{3} < \sigma_1 < \frac{1}{2}$  and  $\frac{1}{2} < \sigma_2 < \frac{2}{3}$ , and thus it follows immediately that  $\sigma_1 < \sigma_2$ . The monotonicity of the ratios does not hold in general for  $n \ge 5$  (see [5]). Further results on ratio vectors for n = 4 were proved by the author in [6]. In particular, necessary and sufficient conditions were given for  $(\sigma_1, \sigma_2, \sigma_3)$  to be a ratio vector. For a discussion of complex ratio vectors for the case n = 3, see [7].

We now want to extend the notion of ratio vector to hyperbolic polynomial-like functions (HPLF) of the form

$$p(x) = (x - r_1)^{m_1} \cdots (x - r_N)^{m_N}$$

where  $m_1, \ldots, m_N$  are given positive real numbers with  $\sum_{k=1}^N m_k = n$  and  $r_1, \ldots, r_N$  are real numbers with  $r_1 < r_2 < \cdots < r_N$ . See [8] and the references therein for





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much more about HPLFs. We extend some of the results and simplify some of the proofs in [5] and in [6], and we prove some new results as well. In particular, we derive more general bounds on the  $\sigma_k$  (Theorem 1.2). Even for N = 3 or N = 4, the monotonicity of the ratios does not hold in general for all positive real numbers  $m_1, \ldots, m_N$ . We provide examples below and we also derive necessary and sufficient conditions on  $m_1, m_2, m_3$  for  $\sigma_1 < \sigma_2$  (Theorem 1.4). In order to define the ratios for HPLFs, we need the following lemma.

**Lemma 1.1.** p' has exactly one root,  $x_k \in I_k = (r_k, r_{k+1}), k = 1, 2, ..., N - 1.$ 

*Proof.* By Rolle's Theorem, p' has at least one root in  $I_k$  for each k = 1, 2, ..., N-1. Now  $\frac{p'}{p} = \sum_{k=1}^{N} \frac{m_k}{x - r_k}$ , which has at most N - 1 real roots since  $\left\{\frac{1}{x - r_k}\right\}_{k=1,...,N}$  is a Chebyshev system.

Now we define the N-1 ratios

(1.1) 
$$\sigma_k = \frac{x_k - r_k}{r_{k+1} - r_k}, \qquad k = 1, 2, \dots, N - 1.$$

 $(\sigma_1, \ldots, \sigma_{N-1})$  is called the *ratio vector* of *p*.

We now state our first main result, inequalities for the ratios defined in (1.1).

**Theorem 1.2.** If  $\sigma_1, \ldots, \sigma_{N-1}$  are defined by (1.1), then

(1.2) 
$$\frac{m_k}{m_k + \dots + m_N} < \sigma_k < \frac{m_1 + \dots + m_k}{m_1 + \dots + m_{k+1}}$$

*Remark* 1. Well after this paper was written and while this paper was being considered for publication, the paper of Melman [9] appeared. Theorem 2 of [9] is essentially Theorem 1.2 of this paper for the case when the  $m_k$  are all nonnegative integers.



in pure and applied mathematics Most of the rest of our results are for the special cases when N = 3 or N = 4. For N = 3 we give necessary and sufficient conditions on  $m_1, m_2, m_3$  for  $(\sigma_1, \sigma_2)$  to be a ratio vector. The following theorem generalizes ([5],Theorem 1). Note that  $n = m_1 + m_2 + m_3$ .

**Theorem 1.3.** Let  $p(x) = (x - r_1)^{m_1} (x - r_2)^{m_2} (x - r_3)^{m_3}$ . Then  $(\sigma_1, \sigma_2)$  is a ratio vector if and only if  $\frac{m_1}{n} < \sigma_1 < \frac{m_1}{m_1 + m_2}, \frac{m_2}{m_2 + m_3} < \sigma_2 < \frac{m_1 + m_2}{n}$ , and  $\sigma_2 = \frac{m_2}{n(1 - \sigma_1)}$ .

We now state some results about the monotonicity of the ratios when N = 3. For  $m_1 = m_2 = m_3 = 1$ , Theorem 1.2 yields  $\frac{1}{3} < \sigma_1 < \frac{1}{2}$  and  $\frac{1}{2} < \sigma_2 < \frac{2}{3}$ , and thus it follows immediately that  $\sigma_1 < \sigma_2$ .  $\sigma_1 \leq \sigma_2$  does not hold in general for all positive real numbers(or even positive integers)  $m_1, m_2$ , and  $m_3$ . For example, if  $m_1 = 2$ ,  $m_2 = 1, m_3 = 3$ , then it is not hard to show that  $\sigma_2 < \sigma_1$  for all  $r_1 < r_2 < r_3$ (see the example in § 2 below). Also, if  $m_1 = 4, m_2 = 3$ , and  $m_3 = 6$ , then  $\sigma_1 < \sigma_2$  for certain  $r_1 < r_2 < r_3$ , while  $\sigma_2 < \sigma_1$  for other  $r_1 < r_2 < r_3$ . For

$$p(x) = x^4(x-1)^3 \left(x + \frac{1}{2} - \frac{1}{2}\sqrt{13}\right)^6, \qquad \sigma_1 = \sigma_2 = \frac{1}{2} - \frac{1}{26}\sqrt{13}.$$

One can easily derive **sufficient** conditions on  $m_1, m_2, m_3$  which imply that  $\sigma_1 < \sigma_2$ for all  $r_1 < r_2 < r_3$ . For example, if  $m_1m_3 < m_2^2$ , then  $\frac{m_1}{m_1+m_2} < \frac{m_2}{m_2+m_3}$ , which implies that  $\sigma_1 < \sigma_2$  by (1.2) with N = 3(see (2.6) in § 2). Also, if  $m_1 + m_3 < 3m_2$ , then  $n < 4m_2$ , which implies that

$$\sigma_2 = \frac{m_2}{n(1-\sigma_1)} > \frac{1}{4(1-\sigma_1)} \ge \sigma_1$$

since  $4x(1-x) \leq 1$  for all real x. We shall now derive necessary and sufficient conditions on  $m_1, m_2, m_3$  for  $\sigma_1 < \sigma_2$ .



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**Theorem 1.4.**  $\sigma_1 < \sigma_2$  for all  $r_1 < r_2 < r_3$  if and only if  $m_2^2 + m_1(m_2 - m_3) > 0$  and one of the following holds:

(1.3) 
$$m_2^2 + m_2(m_1 + m_3) - 2m_1m_3 \ge 0$$
 and  $m_2^2 + m_3(m_2 - m_1) > 0$ 

or

(1.4) 
$$m_2^2 + m_2(m_1 + m_3) - 2m_1m_3 < 0$$
 and  $3m_2 - m_1 - m_3 > 0.$ 

As noted above, if  $m_1 = m_2 = m_3 = 1$ , then  $\sigma_1 < \sigma_2$ . The following corollary is a slight generalization of that and follows immediately from Theorem 1.4.

**Corollary 1.5.** Suppose that  $m_1 = m_2 = m_3 = m > 0$ . Then  $\sigma_1 < \sigma_2$  for all  $r_1 < r_2 < r_3$ .

For N = 4 we now give necessary and sufficient conditions on  $m_1, m_2, m_3, m_4$ for  $(\sigma_1, \sigma_2, \sigma_3)$  to be a ratio vector. Note that  $n = m_1 + m_2 + m_3 + m_4$ . To simplify the notation, we use  $\sigma_1 = u, \sigma_2 = v$ , and  $\sigma_3 = w$  for the ratios. The following theorem generalizes ([6], Theorem 3).

Theorem 1.6. Let

$$D \equiv D(u, v, w) = \begin{vmatrix} n(w-v) - m_3 & n(1-w) - m_4 \\ n(u-1)v(1-w) & n(u-1)vw + m_2 \end{vmatrix},$$

$$D_1 \equiv D_1(u, v, w) = (nu - m_1) (m_2 - nvw (1 - u)),$$
  
$$D_2 \equiv D_2(u, v, w) = (nu - m_1) nv (1 - u) (1 - w),$$

and

$$R \equiv R(u, v, w)$$
  
=  $\frac{nv(1-w)D_1^2 + (nvw-m_1-m_2)D_1D_2 + (n(1-u)(w-v-1)+m_2+m_4)D_1D + (nw(u-1)+m_2+m_3)D_2D}{(nu-m_1)(m_2-nv(1-u))}$ ,



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which is a polynomial in u, v, and w of degree 7. Then  $(u, v, w) \in \Re^3$  is a ratio vector of

$$p(x) = (x - r_1)^{m_1} (x - r_2)^{m_2} (x - r_3)^{m_3} (x - r_4)^{m_4}$$

if and only if  $0 < D_1(u, v, w) < D_2(u, v, w), D(u, v, w) > 0$ , and R(u, v, w) = 0.

We now state a sufficiency result about the monotonicity of the ratios when N = 4. We do not derive necessary and sufficient conditions in general on  $m_1, m_2, m_3, m_4$  for  $\sigma_1 < \sigma_2 < \sigma_3$ .

**Theorem 1.7.** Suppose that  $m_1 + m_4 \le \min \{3m_2 - m_3, 3m_3 - m_2\}$ . Then  $\sigma_1 < \sigma_2 < \sigma_3$ .

As with N = 3, we have the following generalization of the case when  $m_1 = m_2 = m_3 = m_4 = 1$ , which follows immediately from Theorem 1.7

**Corollary 1.8.** Suppose that  $m_1 = m_2 = m_3 = m_4 = m > 0$ . Then  $\sigma_1 < \sigma_2 < \sigma_3$ .





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## 2. Proofs

We shall derive a system of nonlinear equations in the  $\{r_k\}$  and  $\{\sigma_k\}$  using (1.1). Let

$$p(x) = (x - r_1)^{m_1} \cdots (x - r_N)^{m_N}$$

where  $m_1, \ldots, m_N$  are given positive real numbers with  $\sum_{k=1}^N m_k = n$  and  $r_1, \ldots, r_N$  are real numbers with  $r_1 < r_2 < \cdots < r_N$ . By the product rule,

$$p'(x) = (x - r_1)^{m_1 - 1} \cdots (x - r_N)^{m_N - 1} \sum_{j=1}^N \left( m_j \prod_{i=1, i \neq j}^N (x - r_i) \right).$$

Since

$$p'(x) = n(x - r_1)^{m_1 - 1} \cdots (x - r_N)^{m_N - 1} \times \prod_{k=1}^{N-1} (x - x_k)$$

as well, we have

(2.1) 
$$n \prod_{k=1}^{N-1} (x - x_k) = \sum_{j=1}^{N} \left( m_j \prod_{i=1, i \neq j}^{N} (x - r_i) \right).$$

Let  $e_k \equiv e_k(r_1, \ldots, r_N)$  denote the *k*th elementary symmetric function of the  $r_j$ ,  $j = 1, 2, \ldots, N$ , starting with  $e_0(r_1, \ldots, r_N) = 1$ ,  $e_1(r_1, \ldots, r_N) = r_1 + \cdots + r_N$ , and so on. Let

$$e_{k,j}(r_1,\ldots,r_N) = e_k(r_1,\ldots,r_{j-1},r_{j+1},\ldots,r_N),$$

that is,  $e_{k,j}(r_1, \ldots, r_N)$  equals  $e_k(r_1, \ldots, r_N)$  with  $r_j$  removed,  $j = 1, \ldots, N$ . Since p(x + c) and p(x) have the same ratio vectors for any constant c, we may assume that





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Equating coefficients in (2.1) using the elementary symmetric functions yields

$$ne_k(x_1,\ldots,x_{N-1}) = \sum_{j=1}^N m_j e_{k,j}(r_1,0,r_3,\ldots,r_N), \qquad k=1,2,\ldots,N-1.$$

Since

$$e_{k,j}(r_1, 0, r_3, \dots, r_N) = \begin{cases} e_{k,j}(r_1, r_3, \dots, r_N) & \text{if } j \neq 2 \text{ and } k \le N-2; \\ e_k(r_1, r_3, \dots, r_N) & \text{if } j = 2; \\ 0 & \text{if } j \neq 2 \text{ and } k = N-1, \end{cases}$$

we have

(2.2)  

$$ne_{k}(x_{1}, \dots, x_{N-1}) = m_{2}e_{k}(r_{1}, r_{3}, \dots, r_{N}) + \sum_{j=1, j \neq 2}^{N} m_{j}e_{k,j}(r_{1}, r_{3}, \dots, r_{N}), \quad k = 1, \dots, N-2$$

$$nx_{1} \cdots x_{N-1} = m_{2}r_{1}r_{3} \cdots r_{N}.$$

Solving (1.1) for  $x_k$  yields

(2.3) 
$$x_k = \Delta_k \sigma_k + r_k, \qquad k = 1, 2, \dots, N-1,$$

where  $\Delta_k = r_{k+1} - r_k$ . Substituting (2.3) into (2.2) gives the following equivalent system of equations involving the roots and the ratios.

(2.4) 
$$ne_k((1-\sigma_1)r_1, r_3\sigma_2, \Delta_3\sigma_3 + r_3, \dots, \Delta_{N-1}\sigma_{N-1} + r_{N-1})$$
  
=  $m_2e_k(r_1, r_3, \dots, r_N) + \sum_{j=1, j\neq 2}^N m_je_{k,j}(r_1, r_3, \dots, r_N), \quad k = 1, \dots, N-2,$ 





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$$n(1-\sigma_1)r_1r_3\sigma_2(\Delta_3\sigma_3+r_3)\cdots(\Delta_{N-1}\sigma_{N-1}+r_{N-1})=m_2r_1r_3\cdots r_N.$$

Critical in proving the inequalities  $\frac{1}{n-k+1} < \sigma_k < \frac{k}{k+1}$  was the root-dragging theorem (see [2]). First we generalize the root-dragging theorem. The proof is very similar to the proof in [2] where  $m_1 = \cdots = m_N = 1$ . For completeness, we provide the details here.

**Lemma 2.1.** Let  $x_1 < x_2 < \cdots < x_{N-1}$  be the N-1 critical points of p lying in  $I_k = (r_k, r_{k+1}), k = 1, 2, \dots, N-1$ . Let  $q(x) = (x - r'_1)^{m_1} \cdots (x - r'_N)^{m_N}$ , where  $r'_k > r_k, k = 1, 2, \dots, N-1$  and let  $x'_1 < x'_2 < \cdots < x'_{N-1}$  be the N-1critical points of q lying in  $J_k = (r'_k, r'_{k+1}), k = 1, 2, \dots, N-1$ . Then  $x'_k > x_k$ ,  $k = 1, 2, \dots, N-1$ .

*Proof.* Suppose that for some  $i, x'_i \leq x_i$ . Now

$$p'(x_i) = 0 \Rightarrow \sum_{k=1}^{N} \frac{m_k}{x_i - r_k} = 0 \text{ and } q'(x'_i) = 0 \Rightarrow \sum_{k=1}^{N} \frac{m_k}{x'_i - r'_k} = 0.$$

 $r'_k > r_k$  and  $x'_i \le x_i$  implies that

(2.5) 
$$x'_i - r'_k < x_i - r_k, \quad k = 1, 2, \dots, N-1.$$

Since both sides of (2.5) have the same sign,

$$\frac{m_k}{x'_i - r'_k} > \frac{m_k}{x_i - r_k}, \quad k = 1, 2, \dots, N - 1,$$

which contradicts the fact that  $\sum_{k=1}^{N} \frac{m_k}{x_i - r_k}$  and  $\sum_{k=1}^{N} \frac{m_k}{x'_i - r'_k}$  are both zero.

*Proof of Theorem 1.2.* To obtain an upper bound for  $\sigma_k$  we use Lemma 2.1. Arguing as in [1], we can move the critical point  $x_k \in (r_k, r_{k+1})$  as far to the right as possible





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by letting  $r_1, \ldots, r_{k-1} \to r_k$  and  $r_{k+2}, \ldots, r_N \to \infty$ . Let  $s = m_1 + \cdots + m_k$ ,  $t = m_{k+2} + \cdots + m_N$ , and let

$$q_b(x) = (x - r_k)^s (x - r_{k+1})^{m_{k+1}} (x - b)^t.$$

Then

$$q'_{b}(x) = (x - r_{k})^{s} \left[ (x - r_{k+1})^{m_{k+1}} t(x - b)^{t-1} + m_{k+1} (x - r_{k+1})^{m_{k+1}-1} (x - b)^{t} \right] + s(x - r_{k})^{s-1} (x - r_{k+1})^{m_{k+1}} (x - b)^{t} = (x - r_{k+1})^{m_{k+1}-1} (x - r_{k})^{s-1} (x - b)^{t-1} \times \left[ t(x - r_{k+1}) (x - r_{k}) + m_{k+1} (x - r_{k}) (x - b) + s(x - r_{k+1}) (x - b) \right].$$

 $x_k$  is the smallest root of the quadratic polynomial

$$t(x - r_{k+1})(x - r_k) + m_{k+1}(x - r_k)(x - b) + s(x - r_{k+1})(x - b)$$
  
=  $(m_{k+1} + t + s) x^2 + (-tr_{k+1} - tr_k - m_{k+1}r_k - m_{k+1}b - sr_{k+1} - sb) x$   
+  $tr_{k+1}r_k + sr_{k+1}b + m_{k+1}r_kb.$ 

As  $b \to \infty$ ,  $x_k$  increases and approaches the root of  $(-m_{k+1}-s)x+sr_{k+1}+m_{k+1}r_k$ . Thus

$$x_{k} \uparrow \frac{sr_{k+1} + m_{k+1}r_{k}}{m_{k+1} + s} \Rightarrow \sigma_{k} \uparrow \left(\frac{sr_{k+1} + m_{k+1}r_{k}}{m_{k+1} + s} - r_{k}\right) / (r_{k+1} - r_{k})$$

$$= \frac{sr_{k+1} + m_{k+1}r_{k} - r_{k}(m_{k+1} + s)}{(m_{k+1} + s)(r_{k+1} - r_{k})}$$

$$= \frac{s}{m_{k+1} + s} = \frac{m_{1} + \dots + m_{k}}{m_{1} + \dots + m_{k+1}}.$$

Similarly, to obtain a lower bound for  $\sigma_k$ , move the critical point  $x_k \in (r_k, r_{k+1})$  as far to the left as possible by letting  $r_{k+2}, \ldots, r_N \to r_{k+1}$  and  $r_1, \ldots, r_{k-1} \to -\infty$ .



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By considering

$$q_b(x) = (x - r_k)^{m_k} (x - r_{k+1})^s (x + b)^t,$$

where  $s = m_{k+1} + \cdots + m_N$  and  $t = m_1 + \cdots + m_{k-1}$ , one obtains  $\sigma_k \downarrow \frac{m_k}{m_k + \cdots + m_N}$ .

*Proof of Theorem 1.3.* Let  $n = m_1 + m_2 + m_3$ . To prove the necessity part, from Theorem 1.2 with N = 3 we have

(2.6) 
$$\frac{m_1}{n} < \sigma_1 < \frac{m_1}{m_1 + m_2}, \qquad \frac{m_2}{m_2 + m_3} < \sigma_2 < \frac{m_1 + m_2}{n}.$$

With N = 3, (2.4) becomes

(2.7) 
$$n\left((1-\sigma_1)r_1+r_3\sigma_2\right) = m_2\left(r_1+r_3\right)+m_1r_3+m_3r_1,\\ n(1-\sigma_1)r_1(r_3\sigma_2) = m_2r_1r_3.$$

Since  $r_1 \neq 0 \neq r_3$ , the second equation in (2.4) immediately implies that  $n(1 - \sigma_1)\sigma_2 = m_2$ .

To prove sufficiency, suppose that  $(\sigma_1, \sigma_2)$  is any ordered pair of real numbers with  $\frac{m_1}{n} < \sigma_1 < \frac{m_1}{m_1+m_2}$  and  $\sigma_2 = \frac{m_2}{n(1-\sigma_1)}$ . Let  $r = \frac{n\sigma_1-m_1}{m_1+m_2-n\sigma_2}$  and let  $p(x) = (x+1)^{m_1}x^{m_2}(x-r)^{m_3}$ . Note that r > 0 since  $n\sigma_1 - m_1 > 0$  and

$$m_1 + m_2 - n\sigma_2 = m_1 + m_2 - n\frac{m_2}{n(1 - \sigma_1)}$$
$$= \frac{\sigma_1 (m_1 + m_2) - m_1}{-1 + \sigma_1}$$
$$= \frac{m_1 - \sigma_1 (m_1 + m_2)}{1 - \sigma_1} > 0.$$



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A simple computation shows that the critical points of p in (-1,0) and in (0,r), respectively, are  $x_1 = \sigma_1 - 1$  and

$$x_2 = -\frac{m_2}{m_1 + m_2 + m_3} \frac{\sigma_1(m_2 + m_3) + (\sigma_1 - 1)m_1}{(m_1 + m_2)\sigma_1 - m_1}$$

Thus the ratios of p are  $x_1 + 1 = \sigma_1$  and  $\frac{x_2}{r} = \frac{m_2}{n(1-\sigma_1)} = \sigma_2$ . That finishes the proof of Theorem 1.3.

*Proof of Theorem 1.4.* Since p(cx) and p(x) have the same ratios when c > 0, in addition to  $r_1 = 0$ , we may also assume that  $r_2 = 1$ . Thus  $p(x) = x^{m_1}(x-1)^{m_2}(x-r)^{m_3}$ , r > 1. A simple computation shows that

$$\sigma_1 = \frac{1}{2n} \left( (n - m_3)r - n - m_2 - \sqrt{A(r)} \right) + 1,$$
  
$$\sigma_2 = \frac{\frac{1}{2n} \left( (n - m_3)r - n - m_2 + \sqrt{A(r)} \right)}{r - 1},$$

where

$$A(r) = (m_1 + m_2)^2 r^2 + 2(m_2 m_3 - m_1 n)r + (m_1 + m_3)^2.$$

Let

$$f(r) = (n - m_3) r^2 + (-n + 2m_3 - m_2) r + 2m_2.$$

Note that  $f(1) = m_2 + m_3 > 0$ ,  $f'(1) = m_1 + m_3 > 0$ , and  $f''(r) = 2m_2 + 2m_1 > 0$ , which implies that f(r) > 0 when r > 1. Now

$$\sigma_2 - \sigma_1 = \frac{\frac{1}{2n} \left( (n - m_3)r - n - m_2 + \sqrt{A(r)} \right)}{r - 1} - \frac{1}{2n} \left( (n - m_3)r - n - m_2 - \sqrt{A(r)} \right) - 1$$



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$$=\frac{r\sqrt{A(r)}-f(r)}{2n\left(r-1\right)}.$$

 $\sigma_2 - \sigma_1 > 0$  when

$$r > 1 \iff \sqrt{Ar} > f(r)$$
  
$$\iff Ar^{2} > ((n - m_{3})r^{2} + (-n + 2m_{3} - m_{2})r + 2m_{2})^{2}$$
  
$$\iff 4(r - 1)((m_{2}^{2} + m_{1}m_{2} - m_{1}m_{3})r^{2} + (m_{2}m_{3} - m_{1}m_{2} - m_{2}^{2})r + m_{2}^{2}) > 0$$
  
$$\iff h(r) > 0$$

when r > 1, where

$$h(r) = \left(m_2^2 + m_1(m_2 - m_3)\right)r^2 + m_2\left(m_3 - m_2 - m_1\right)r + m_2^2.$$

We want to determine necessary and sufficient conditions on  $m_1, m_2, m_3$  which imply that h(r) > 0 for all r > 1. A necessary condition is clearly

(2.8) 
$$m_2^2 + m_1(m_2 - m_3) > 0,$$

so we assume that (2.8) holds. Let

$$r_0 = \frac{1}{2}m_2 \frac{m_1 + m_2 - m_3}{m_2^2 + m_1(m_2 - m_3)}$$

be the unique root of h'. If  $r_0 \leq 1$ , then it is necessary and sufficient to have h(1) > 0. If  $r_0 > 1$ , then it is necessary and sufficient to have  $h(r_0) > 0$ . Now

$$r_{0} \leq 1 \iff 2\left(m_{2}^{2} + m_{1}(m_{2} - m_{3})\right) \geq m_{2}\left(m_{2} + m_{1} - m_{3}\right)$$
$$\iff m_{2}^{2} + m_{2}\left(m_{1} + m_{3}\right) - 2m_{1}m_{3} \geq 0,$$



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and

$$h(1) > 0 \iff m_2^2 + m_3(m_2 - m_1) > 0.$$

That proves (1.3). If

$$m_2^2 + m_2 \left( m_1 + m_3 \right) - 2m_1 m_3 < 0,$$

then  $r_0 > 1$ . It is then necessary and sufficient that

$$h(r_0) = \frac{1}{4}m_2^2(m_1 + m_2 + m_3)\frac{3m_2 - m_1 - m_3}{m_2^2 + m_1(m_2 - m_3)} > 0 \iff 3m_2 - m_1 - m_3 > 0.$$

That proves (1.4).

One can also easily derive necessary and sufficient conditions on  $m_1, m_2, m_3$  for  $\sigma_2 < \sigma_1$ . We simply cite an example here that shows that this is possible. *Example 2.1.* Let  $m_1 = 2, m_2 = 1, m_3 = 3$ . As noted above, we may assume that  $p(x) = x^2(x-1)(x-r)^3, r > 1$ . Then a simple computation shows that

$$\sigma_1 = \frac{5}{12} + \frac{1}{4}r - \frac{1}{12}\sqrt{25 - 18r + 9r^2} \qquad \text{and} \qquad \sigma_2 = \frac{3r - 7 + \sqrt{25 - 18r + 9r^2}}{12}$$

Simplifying yields

$$\sigma_2 - \sigma_1 = \frac{-3r^2 + r - 2 + r\sqrt{25 - 18r + 9r^2}}{12(r-1)}$$

 $\sigma_2 - \sigma_1 < 0,$ 

$$r > 1 \iff r\sqrt{25 - 18r + 9r^2} < 3r^2 - r + 2$$
  
$$\iff (3r^2 - r + 2)^2 - r^2 (25 - 18r + 9r^2) > 0$$
  
$$\iff 4 (r - 1) (3r^2 - 1) > 0.$$

Hence  $\sigma_2 < \sigma_1$  for all r > 1.





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*Remark* 2. For the example above, if we choose r = 2, then the roots are **equispaced**, but  $\sigma_2 < \sigma_1$ . Contrast this with ([5, Theorem 6]), where it was shown that for any  $N \ge 3$ , if  $m_1 = \cdots = m_N = 1$  and the roots are *equispaced*, then the ratios of p are **increasing**.

We now discuss the case N = 4, so that  $n = m_1 + m_2 + m_3 + m_4$ . Theorem 1.2 then yields

(2.9) 
$$\frac{\frac{m_1}{n} < u < \frac{m_1}{m_1 + m_2},}{\frac{m_2}{m_2 + m_3 + m_4}} < v < \frac{m_1 + m_2}{m_1 + m_2 + m_3},\\\frac{m_3}{m_3 + m_4} < w < \frac{m_1 + m_2 + m_3}{n}.$$

In [6] necessary and sufficient conditions were given for  $(\sigma_1, \sigma_2, \sigma_3)$  to be a ratio vector when  $m_1 = m_2 = m_3 = 1$ . We now give a simpler proof than that given in [6] which also generalizes to any positive real numbers  $m_1, m_2$ , and  $m_3$ . The proof here for N = 4 does not require the use of Groebner bases as in [6].

*Proof of Theorem 1.6.* ( $\Leftarrow$  Suppose first that (u, v, w) is a ratio vector of

$$p(x) = (x - r_1)^{m_1} (x - r_2)^{m_2} (x - r_3)^{m_3} (x - r_4)^{m_4}$$

Since p(x + c) and p(x) have the same ratio vectors for any constant c, we may assume that  $r_2 = 0$ , and thus the equations (2.4) hold with N = 4. In addition, since p(cx) and p(x) have the same ratio vectors for any constant c > 0, we may also assume that  $r_1 = -1$ . Let  $r_3 = r$  and  $r_4 = s$ , so that 0 < r < s. Then (2.4) becomes

(2.10) 
$$(n(w-v) - m_3)r + (n(1-w) - m_4)s = nu - m_1,$$



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(2.11) 
$$nv(1-w)r^2 + (nvw - m_1 - m_2)rs + (n(1-u)(w-v-1) + m_2 + m_4)r + (nw(u-1) + m_2 + m_3)s = 0,$$

(2.12) 
$$nv(u-1)(1-w)r + (nvw(u-1) + m_2)s = 0.$$

In particular, (2.10) - (2.12) must be consistent. Eliminating r and s from (2.10) and (2.12) yields

$$(nv(u-1)(1-w)(n(1-w)-m_4) - (n(w-v)-m_3)(nvw(u-1)+m_2))s = (nu-m_1)nv(u-1)(1-w),$$

or

$$D(u, v, w)s = (nu - m_1) nv (1 - u) (1 - w).$$

Note that  $nu - m_1 > 0$ , 1 - u > 0, v > 0, and 1 - w > 0 by (2.9). Thus D(u, v, w) > 0 and by Cramer's Rule,

(2.13) 
$$r = \frac{D_1(u, v, w)}{D(u, v, w)}, \qquad s = \frac{D_2(u, v, w)}{D(u, v, w)},$$

where

$$D_1(u, v, w) = \begin{vmatrix} nu - m_1 & n(1 - w) - m_4 \\ 0 & nvw (u - 1) + m_2 \end{vmatrix} = (nu - m_1) (m_2 - nvw (1 - u)),$$

and

$$D_2(u, v, w) = \begin{vmatrix} n(w - v) - m_3 & nu - m_1 \\ nv (u - 1) (1 - w) & 0 \end{vmatrix} = (nu - m_1) nv (1 - u) (1 - w).$$



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(2.13) and D(u, v, w) > 0 imply that  $D_1(u, v, w) > 0$ , and r < s implies that  $D_1(u, v, w) < D_2(u, v, w)$ . Now substitute the expressions for r and s in (2.13) into (2.11). Clearing denominators gives

(2.14) 
$$nv(1-w)D_1^2 + (nvw - m_1 - m_2) D_1D_2$$
  
+  $(n(1-u)(w-v-1) + m_2 + m_4) D_1D$   
+  $(nw(u-1) + m_2 + m_3) D_2D = 0.$ 

Factoring the LHS of (2.14) yields

$$(nu - m_1) (nv(1 - u) - m_2) R(u, v, w) = 0.$$

Also, (2.12) and r < s implies that

(2.15) 
$$\frac{m_2}{n} - vw(1-u) < v(1-u)(1-w)$$
$$\Rightarrow \frac{m_2}{n} < vw(1-u) + v(1-u)(1-w) = v(1-u)$$
$$\Rightarrow v(1-u) > \frac{m_2}{n}.$$

Thus  $m_2 - nv(1 - u) \neq 0$ , which implies that R(u, v, w) = 0.

( $\implies$  Now suppose that u, v, and w are real numbers with  $0 < D_1(u, v, w) < D_2(u, v, w)$ , D(u, v, w) > 0, and R(u, v, w) = 0. Let  $r = \frac{D_1(u, v, w)}{D(u, v, w)}$  and  $s = \frac{D_2(u, v, w)}{D(u, v, w)}$ . Then 0 < r < s and it follows as above that (r, s, u, v, w) satisfies (2.10) - (2.12). Let  $x_1 = u - 1$ ,  $x_2 = rv$ , and  $x_3 = (s - r)w + r$ . Then (2.2) must hold since (2.2) and (2.4) are an equivalent system of equations. Let

$$p(x) = (x+1)^{m_1} x^{m_2} (x-r)^{m_3} (x-s)^{m_4}.$$



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Working backwards, it is easy to see that (2.1) must hold and hence  $x_1, x_2$ , and  $x_3$  must be the critical points of p. Since  $u = \frac{x_1 - (-1)}{0 - (-1)}$ ,  $v = \frac{x_2 - 0}{r - 0}$ , and  $w = \frac{x_3 - r}{s - r}$ , (u, v, w) is a ratio vector of p.

*Remark* 3. As noted in [6] for the case when  $m_1 = m_2 = m_3 = m_4 = 1$ , the proof above shows that if (u, v, w) is a ratio vector, then there are *unique* real numbers 0 < r < s such that the polynomial

 $p(x) = (x+1)^{m_1} x^{m_2} (x-r)^{m_3} (x-s)^{m_4}$ 

has (u, v, w) as a ratio vector. For general N we make the following conjecture.

#### Conjecture 2.2. Let

$$p(x) = (x+1)^{m_1} x^{m_2} (x-r_3)^{m_3} \cdots (x-r_N)^{m_N},$$
  

$$q(x) = (x+1)^{m_1} x^{m_2} (x-s_3)^{m_3} \cdots (x-s_N)^{m_N},$$

where  $0 < r_3 < \cdots < r_N$  and  $0 < s_3 < \cdots < s_N$ . Suppose that p and q have the same ratio vectors. Then p = q.

As with N = 3, it was shown in [5] that  $m_1 = m_2 = m_3 = m_4 = 1$  implies that  $\sigma_1 < \sigma_2 < \sigma_3$ . Not suprisingly, this does not hold for general positive real numbers  $m_1, m_2, m_3$ , and  $m_4$ . For example, if  $p(x) = (x + 1)^{3/2} x (x - 4)^{\sqrt{2}} (x - 6)^2$ , then  $\sigma_1 > \sigma_3 > \sigma_2$ .

Proof of Theorem 1.7.  $m_1 + m_4 \leq 3m_2 - m_3 \Rightarrow n \leq 4m_2$ . By (2.15) in the proof of Theorem 1.6,  $v(1-u) > \frac{1}{4}$ . Thus  $\frac{v}{u} > \frac{1}{4u(1-u)} \geq 1$  since  $u(1-u) \leq 1$ . By letting  $r_1 = r < r_2 = -1 < r_3 = 0 < r_4 = s$ , one can derive equations similar to (2.2) with N = 4. The third equation becomes

$$(m_3 - nw(1 - u)(1 - v))r + nwu(1 - v) = 0 \Rightarrow r = \frac{nwu(1 - v)}{nw(1 - v)(1 - u) - m_3}$$





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$$\begin{aligned} r < -1 \Rightarrow \frac{1}{r} > -1 \\ \Rightarrow \frac{nw\left(1-v\right)\left(1-u\right) - m_3}{nwu(1-v)} > -1 \\ \Rightarrow nw\left(1-v\right)\left(1-u\right) - m_3 > -nwu(1-v) \\ \Rightarrow nw\left(1-v\right)\left(1-u\right) + nwu(1-v) > m_3 \\ \Rightarrow nw\left(1-v\right) > m_3 \\ \Rightarrow \frac{w}{v} > \frac{m_3}{nv(1-v)}. \end{aligned}$$

Now 
$$m_1 + m_4 \leq 3m_3 - m_2 \Rightarrow n \leq 4m_3$$
. Thus  $\frac{w}{v} > \frac{1}{4v(1-v)} \geq 1$ .



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