

IVAN KIGURADZE

**SOME BOUNDARY VALUE PROBLEMS ON INFINITE INTERVALS FOR FUNCTIONAL DIFFERENTIAL SYSTEMS**

**Abstract.** For nonlinear functional differential systems optimal sufficient conditions for the solvability and well-posedness of boundary value problems on infinite intervals are established.

**რეზიუმე.** არაწრფივი ფუნქციონალური დიფერენციალური სისტემების საზღვრის მნიშვნელობის უსაზღვრო მუდმივებზე სასაზღვრო ამოცანების ამოხსნადობისა და კარგად დასმის საკმარისი პირობები.

**2000 Mathematics Subject Classification:** 34B40, 34K10.

**Key words and phrases:** Boundary value problem, infinite interval, solvability, well-posedness.

In the present paper on the infinite interval  $I$  we consider the nonlinear functional differential system

$$x'(t) = f_1(x, y)(t), \quad y' = f_2(x, y)(t), \tag{1}$$

where  $f_1$  and  $f_2$  are the operators acting from the space  $C_{loc}(I; \mathbb{R}^{n_1+n_2})$  to the spaces  $L_{loc}(I; \mathbb{R}^{n_1})$  and  $L_{loc}(I; \mathbb{R}^{n_2})$ . In the case  $I = \mathbb{R}_+$ , for this system we investigate the problem

$$x(0) = c, \quad \sup \{ \|x(t)\| + \|y(t)\| : t \in \mathbb{R}_+ \} < +\infty, \tag{2}$$

and in the case  $I = \mathbb{R}$  the problem

$$\sup \{ \|x(t)\| + \|y(t)\| : t \in \mathbb{R} \} < +\infty. \tag{3}$$

Earlier, these problems were studied only in the cases, where  $f_1$  and  $f_2$  are either the Nemytski's operators ([3], [4], [5]), or the linear operators ([1], [2], [6]). Below, we will present new, and in a certain sense, unimprovable conditions which guarantee, respectively, the solvability and well-posedness of (1), (2) and (1), (3).

Throughout the paper, the following notation will be used;

$$\mathbb{R} = ] - \infty, +\infty[, \quad \mathbb{R}_+ = [0, +\infty[, \quad \mathbb{R}_- = ] - \infty, 0].$$

$\mathbb{R}^n$  is the space of  $n$ -dimensional vectors  $x = (x_i)_{i=1}^n$  with components  $x_i \in \mathbb{R}$  ( $i = 1, \dots, n$ ) and the norm

$$\|x\| = \sum_{i=1}^n |x_i|.$$

---

Reported on the Tbilisi Seminar on Qualitative Theory of Differential Equations on May 19, 2008.

$x \cdot y$  is the scalar product of the vectors  $x$  and  $y \in \mathbb{R}^n$ .

If  $x = (x_i)_{i=1}^m \in \mathbb{R}^m$  and  $y = (y_i)_{i=1}^n \in \mathbb{R}^n$ , then  $z = (x, y)$  is the  $(m+n)$ -dimensional vector with components  $z_i = x_i$  ( $i = 1, \dots, m$ ) and  $z_{m+i} = y_i$  ( $i = 1, \dots, n$ ).

If  $x = (x_i)_{i=1}^n$ , then  $\operatorname{sgn} x = (\operatorname{sgn} x_i)_{i=1}^n$ .

$X = (x_{ik})_{i,k=1}^n$  is the  $n \times n$ -matrix with components  $x_{ik} \in \mathbb{R}$  ( $i, k = 1, \dots, n$ ).

$r(X)$  is the spectral radius of  $X$ .

$C(I; \mathbb{R}^n)$  is the space of continuous and bounded on  $I$  vector functions  $x : I \rightarrow \mathbb{R}^n$  with the norm

$$\|x\|_{C(I; \mathbb{R}^n)} = \sup \{ \|x(t)\| : t \in I \}.$$

$C_{loc}(I; \mathbb{R}^n)$  is the space of continuous vector functions  $x : I \rightarrow \mathbb{R}^n$  with topology of uniform convergence on every compact interval contained in  $I$ .

$L_{loc}(I; \mathbb{R}^n)$  is the space of locally Lebesgue integrable vector functions  $x : I \rightarrow \mathbb{R}^n$  with topology of mean convergence on every compact interval contained in  $I$ .

We say that the operator  $f : C_{loc}(I; \mathbb{R}^n) \rightarrow L_{loc}(I; \mathbb{R}^m)$  satisfies the local Carathéodory conditions if it is continuous and for every  $\rho > 0$  there exists a nonnegative function  $f_\rho^* \in L_{loc}(I; \mathbb{R})$ , such that

$$\|f(x)(t)\| \leq f_\rho^*(t) \text{ for } t \in I, \quad x \in C(I; \mathbb{R}^n), \quad \|x\|_{C(I; \mathbb{R}^n)} \leq \rho.$$

The vector function  $g : I \times \mathbb{R}^n \rightarrow \mathbb{R}^m$  satisfies the local Carathéodory conditions if  $g(\cdot, x) : I \rightarrow \mathbb{R}^m$  is measurable for every  $x \in \mathbb{R}^n$ ,  $g(t, \cdot) : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is continuous for almost all  $t \in I$  and for every  $\rho > 0$  there exists a nonnegative function  $g_\rho^* \in L_{loc}(I; \mathbb{R})$ , such that

$$\|g(t, x)\| \leq g_\rho^*(t) \text{ for } t \in I, \quad x \in \mathbb{R}^n, \quad \|x\| \leq \rho.$$

A particular case (1) is the differential system with deviating arguments

$$x'_i(t) = g_i(t, x(t), x(\tau_1(t)), y(t), y(\tau_i(t))) \quad (i = 1, \dots, n). \quad (4)$$

Everywhere below, when we will be concerned with the problem (1), (2) (with the problem (1), (3)) it will be assumed that  $c \in \mathbb{R}^{n_1}$  and the operators

$$f_i : C_{loc}(I; \mathbb{R}^{n_1+n_2}) \rightarrow L_{loc}(I; \mathbb{R}^{n_i}) \quad (i = 1, 2),$$

where  $I = \mathbb{R}_+$  ( $I = \mathbb{R}$ ) satisfy the local Carathéodory conditions.

Analogously, the problem (4), (2) (the problem (4), (3)) is considered under the assumption that  $c \in \mathbb{R}^{n_1}$  and the functions

$$g_i : I \times \mathbb{R}^{2n_1+2n_2} \rightarrow \mathbb{R}^{n_i} \quad (i = 1, 2),$$

where  $I = \mathbb{R}_+$  ( $I = \mathbb{R}$ ) satisfy the local Carathéodory conditions.

Under the solution of the system (1) (of the system (4)) on  $I$  is meant the function  $(x, y) : I \rightarrow \mathbb{R}^{n_1+n_2}$  with locally absolutely continuous components  $x : I \rightarrow \mathbb{R}^{n_1}$  and  $y : I \rightarrow \mathbb{R}^{n_2}$ , which almost everywhere on  $I$  satisfies this system.

**Theorem 1.** Let  $I = \mathbb{R}_+$  ( $I = \mathbb{R}$ ) and there exist operators  $p_i : C(I; \mathbb{R}^{n_1+n_2}) \rightarrow L_{loc}(I; \mathbb{R}_+)$  ( $i = 1, 2$ ), a nonnegative constant  $h_0$ , and a nonnegative constant matrix  $H = (h_{ik})_{i,k=1}^2$ , such that

$$r(H) < 1 \quad (5)$$

and for any  $(x, y) \in C(I; \mathbb{R}^{n_1+n_2})$  almost everywhere on  $I$  the inequalities

$$\begin{aligned} f_1(x, y)(t) \cdot \operatorname{sgn} x(t) &\leq \\ &\leq p_1(x, y)(t) \left( -\|x(t)\| + h_{11}\|x\|_{C(I; \mathbb{R}^{n_1})} + h_{12}\|y\|_{C(I; \mathbb{R}^{n_2})} + h_0 \right), \\ f_2(x, y)(t) \cdot \operatorname{sgn} y(t) &\leq \\ &\leq p_2(x, y)(t) \left( \|y(t)\| - h_{11}\|x\|_{C(I; \mathbb{R}^{n_1})} - h_{12}\|y\|_{C(I; \mathbb{R}^{n_2})} - h_0 \right) \end{aligned}$$

hold. The problem (1), (2) (the problem (1), (3)) has at least one solution.

*Remark 1.* For the condition (5) to be fulfilled, it is necessary and sufficient that

$$h_{11} + h_{22} < 2, \quad h_{11} + h_{22} - h_{11}h_{22} + h_{12}h_{21} < 1.$$

*Remark 2.* In the above-formulated theorem the condition (5) is unimprovable and it cannot be replaced by the condition  $r(H) \leq 1$ .

**Corollary 1.** Let for  $I = \mathbb{R}_+$  (for  $I = \mathbb{R}$ ) all the conditions of Theorem 1 be fulfilled and

$$\int_0^{+\infty} p_2(x, y)(s) ds = +\infty \quad \left( \int_{-\infty}^0 p_1(x, y) ds = \int_0^{+\infty} p_2(x, y)(s) ds = +\infty \right) \quad (6)$$

for any  $(x, y) \in C(I; \mathbb{R}^{n_1+n_2})$ . Then every solution of the problem (1), (2) (of the problem (1), (3)) admits the estimate

$$\begin{aligned} \|x\|_{C(\mathbb{R}_+; \mathbb{R}^{n_1})} + \|y\|_{C(\mathbb{R}_+; \mathbb{R}^{n_2})} &\leq \rho(\|c\| + h_0) \\ \left( \|x\|_{C(\mathbb{R}; \mathbb{R}^{n_1})} + \|y\|_{C(\mathbb{R}; \mathbb{R}^{n_2})} \right) &\leq \rho h_0, \end{aligned} \quad (7)$$

where  $\rho$  is a positive constant depending only on  $H$ .

*Remark 3.* The condition (6) in Corollary 1 is essential and it cannot be omitted.

For the system (4), Theorem 1 and Corollary 1 yield the following propositions.

**Corollary 2.** Let  $I = \mathbb{R}_+$  ( $I = \mathbb{R}$ ), and there exist functions  $p_i : I \times \mathbb{R}^{2n_1+2n_2} \rightarrow \mathbb{R}_+$  ( $i = 1, 2$ ), satisfying the local Carathéodory conditions, and nonnegative constants  $h_{ik}$  ( $i, k = 1, 2$ ),  $h_0, h_1, h_2$  such that the matrix

$$H = \begin{pmatrix} h_{11} & h_1 + h_{12} \\ h_2 + h_{21} & h_{22} \end{pmatrix} \quad (8)$$

satisfies the condition (5) and on the set  $I \times \mathbb{R}^{2n_1+2n_2}$  the inequalities

$$\begin{aligned} & g_1(t, x, \bar{x}, y, \bar{y}) \cdot \operatorname{sgn} x \leq \\ & \leq p_1(t, x, \bar{x}, y, \bar{y})(- \|x\| + h_{11} \|\bar{x}\| + h_{12} \|y\| + h_{13} \|\bar{y}\| + h_0), \\ & g_2(t, x, \bar{x}, y, \bar{y}) \cdot \operatorname{sgn} y \geq \\ & \geq p_2(t, x, \bar{x}, y, \bar{y})(\|y\| - h_2 \|x\| - h_{21} \|\bar{x}\| - h_{22} \|\bar{y}\| + h_0) \end{aligned}$$

hold. Then the problem (4), (2) (the problem (4), (3)) has at least one solution.

**Corollary 3.** Let for  $I = \mathbb{R}_+$  ( for  $I = \mathbb{R}$ ) all the conditions of Corollary 2 be fulfilled, and

$$\int_0^{+\infty} p_{02}(s) ds = +\infty \left( \int_{-\infty}^0 p_{01}(s) ds = \int_0^{+\infty} p_{02}(s) ds = +\infty \right), \quad (9)$$

where

$$p_{0i}(t) = \inf \{ p_i(t, x, \bar{x}, y, \bar{y}) : (x, \bar{x}) \in \mathbb{R}^{2n_1}, (y, \bar{y}) \in \mathbb{R}^{2n_2} \} \quad (i = 1, 2). \quad (10)$$

Then every solution of the problem (4), (2) (of the problem (4), (3)) admits the estimate (7), where  $\rho$  is a positive constant depending only on  $H$ .

Now along with the functional differential system (1) consider the perturbed system

$$x'(t) = f_1(x, y)(t) + q_1(x, y)(t), \quad y'(t) = f_2(x, y)(t) + q_2(x, y)(t) \quad (1')$$

with the boundary conditions

$$x(a) = \tilde{c}, \quad \sup \{ \|x(t)\| + \|y(t)\| : t \in \mathbb{R}_+ \} < +\infty \quad (2')$$

and (3).

Let us introduce the following

**Definition.** Let  $I = \mathbb{R}_+$  ( $I = \mathbb{R}$ ) and  $p_i : C_{loc}(I; \mathbb{R}^{n_1+n_2}) \rightarrow L_{loc}(I; \mathbb{R}_+)$  ( $i = 1, 2$ ). The problem (1), (2) (the problem (1), (3)) is said to be well-posed with the weight  $(p_1, p_2)$  if it has a unique solution  $(x_0, y_0)$  and there exists a positive constant  $\rho$  such that for arbitrary  $\tilde{c} \in \mathbb{R}^{n_1}$ ,  $q_0 \in \mathbb{R}_+$ , and for any operators  $q_i : C_{loc}(\mathbb{R}_+; \mathbb{R}^{n_1+n_2}) \rightarrow L_{loc}(I; \mathbb{R}^{n_i})$  ( $i = 1, 2$ ), satisfying the local Carathéodory conditions and the inequalities

$$|q_i(x, y)(t)| \leq p_i(x, y)(t)q_0 \quad (i = 1, 2),$$

the problem (1'), (2') (the problem (1'), (3)) is solvable and its arbitrary solution admits the estimate

$$\begin{aligned} \|x - x_0\|_{C(\mathbb{R}_+; \mathbb{R}^{n_1})} + \|y - y_0\|_{C(\mathbb{R}_+; \mathbb{R}^{n_2})} &\leq \rho(\|c - \tilde{c}\| + q_0) \\ \left( \|x - x_0\|_{C(\mathbb{R}; \mathbb{R}^{n_1})} + \|y - y_0\|_{C(\mathbb{R}; \mathbb{R}^{n_2})} \right) &\leq \rho q_0. \end{aligned}$$

**Theorem 2.** Let  $I = \mathbb{R}_+$  ( $I = \mathbb{R}$ ),  $c = 0$ ,  $f_i(0, 0)(t) \equiv 0$  ( $i = 1, 2$ ), and let there exist operators  $p_i : C_{loc}(I; \mathbb{R}^{n_1+n_2}) \rightarrow L_{loc}(I; \mathbb{R}_+)$  ( $i = 1, 2$ ) and a nonnegative constant matrix  $H = (h_{ik})_{i,k=1}^2$ , satisfying the conditions (5) and (6), such that for any  $(x, y) \in C(I; \mathbb{R}^{n_1+n_2})$  the inequalities

$$\begin{aligned} & f_1(x, y)(t) \cdot \operatorname{sgn} x(t) \leq \\ & \leq p_1(x, y)(t) (-\|x(t)\| + h_{11}\|x\|_{C(I; \mathbb{R}^{n_1})} + h_{12}\|y\|_{C(I; \mathbb{R}^{n_2})}), \\ & f_2(x, y)(t) \cdot \operatorname{sgn} y(t) \geq \\ & \geq p_2(x, y)(t) (\|y(t)\| - h_{21}\|x\|_{C(I; \mathbb{R}^{n_1})} - h_{22}\|y\|_{C(I; \mathbb{R}^{n_2})}) \end{aligned}$$

hold almost everywhere on  $I$ . Then the problem (1), (2) (the problem (1), (3)) is well-posed with the weight  $(p_1, p_2)$ .

**Corollary 4.** Let  $I = \mathbb{R}_+$  ( $I = \mathbb{R}$ ),  $c = 0$ ,  $g_i(t, 0, 0, 0, 0) \equiv 0$  ( $i = 1, 2$ ), and on the set  $I \times \mathbb{R}^{2n_1+2n_2}$  the inequalities

$$\begin{aligned} & g_1(t, x, \bar{x}, y, \bar{y}) \cdot \operatorname{sgn} x \leq \\ & \leq p_1(t, x, \bar{x}, y, \bar{y}) (-\|x\| + h_{11}\|\bar{x}\| + h_{12}\|y\| + h_{12}\|\bar{y}\|), \\ & g_2(t, x, \bar{x}, y, \bar{y}) \cdot \operatorname{sgn} y \geq \\ & \geq p_2(t, x, \bar{x}, y, \bar{y}) (\|y\| - h_{21}\|x\| - h_{21}\|\bar{x}\| - h_{22}\|\bar{y}\|) \end{aligned}$$

hold, where  $h_i, h_{ik}$  ( $i, k = 1, 2$ ) are nonnegative constants, and  $p_i : I \times \mathbb{R}^{2n_1+2n_2} \rightarrow \mathbb{R}_+$  ( $i = 1, 2$ ) are functions, satisfying the local Carathéodory conditions. Let, moreover, the matrix  $H$  and the functions  $p_{0i}$  ( $i = 1, 2$ ), given by the equalities (8) and (10), satisfy the conditions (5) and (9). Then the problem (4), (2) (the problem (4), (3)) is well-posed with the weight  $(p_1, p_2)$ .

#### ACKNOWLEDGEMENT

This work is supported by the Georgian National Science Foundation (Grant No. GNSF/ST06/3-002).

#### REFERENCES

1. R. HAKL, On bounded solutions of systems of linear functional differential equations. *Georgian Math. J.* **6** (1999), No. 5, 429–440.
2. R. HAKL, On nonnegative bounded solutions of systems of linear functional differential equations. *Mem. Differential Equations Math. Phys.* **19** (2000), 154–158.
3. I. KIGURADZE, Boundary value problems for systems of ordinary differential equations. (Russian) *Itoqi Nauki Tekh., Ser. Sovrem. Probl. Mat., Novejshie Dostizh.* **30** (1987), 3-103; English transl.: *J. Sov. Math.* **43** (1988), No. 2, 2259–2339.
4. I. KIGURADZE, On some boundary value problems with conditions at infinity for nonlinear differential systems. *Bull. Georgian National Acad. Sci.* **175** (2007), No. 1, 27–33.
5. I. KIGURADZE AND B. PŮŽA, On some boundary value problems for a system of ordinary differential equations. (Russian) *Differentsial'nye Uravneniya* **12** (1976), No. 12, 2139–2148; English transl.: *Differ. Equations* **12** (1976), 1493–1500.

6. I. KIGURADZE AND B. PŮŽA, Boundary value problems for systems of linear functional differential equations. *Masaryk University, Brno*, 2003.

(Received 30.05.2008)

Author's address:

A. Razmadze Mathematical Institute

1, M. Aleksidze St., Tbilisi 0193

Georgia

E-mail: [kig@rmi.acnet.ge](mailto:kig@rmi.acnet.ge)