PROPERTIES OF SOLUTIONS OF SOME LINEAR CLASS OF INTEGRODIFFERENTIAL EQUATIONS OF VOLTERRA TYPE

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Abstract. We present a method for calculating a fundamental matrix of the equation (3). In addition we give a formula for a particular solution of the system (1).

We shall associate the linear neutral Volterra integrodifferential equation

(1)
$$\frac{d}{dt} \left[x(t) - \int_{-\infty}^{t} C(t-s)x(s) \, ds - g(t) \right]$$
$$= A(t)x(t) + B(t) \int_{-\infty}^{t} F(t-s)x(s) \, ds + f(t)$$

with

(2)
$$\frac{d}{dt} \left[x(t) - \int_{t_0}^t C(t-s)x(s) \, ds - g(t) \right]$$
$$= A(t)x(t) + B(t) \int_{t_0}^t F(t-s)x(s) \, ds + f(t)$$

via the resolvent equation

(3)
$$\frac{d}{dt} \left[Z(t) - \int_{t_0}^t C(t-s)Z(s) \, ds \right]$$
$$= A(t)Z(t) + B(t) \int_{t_0}^t F(t-s)Z(s) \, ds, \qquad Z(t_0) = E_n.$$

Here and hereafter x is an n-vector, A(t) and B(t) are $n \times n$ matrices continuous on $(-\infty, \infty)$, $g, f: (-\infty, \infty) \to \mathbf{R}^n$ are continuous, E_n the $n \times n$ identity matrix, Z an $n \times n$ matrix, and C(t), F(t) are matrices $n \times n$ which can be represented in the form

$$C(t) = \sum_{j=1}^{k} \psi_j(t) \exp(\alpha_j t), \qquad F(t) = \sum_{j=1}^{k} \varphi_j(t) \exp(\beta_j t)$$

where

$$\psi_j(t) = \sum_{s=0}^{n_j} \psi_{sj} t^s, \qquad \varphi_j(t) = \sum_{s=0}^{n_j} \varphi_{sj} t^s$$

and ψ_{sj} , φ_{sj} are constant $n \times n$ matrices, α_j , $\beta_j = \text{const.}$

In the case where C(t)=g(t)=0 and $A(t)=A, \ B(t)=E_n$ T. Burton [1] proved that for any bounded solution x(t) of (2) there exists an integer sequence $n_j\to\infty$ as $j\to\infty$ such that $x(t+n_jT)$ (T>0) converges to a solution $x^*(t)$ of (1). A similar result can be found in [2] for the case g(t)=0 under the assumptions $Z\in L^1(0,\infty)$ and $\lim_{t\to\infty} Z(t)=0$. In [3], the discussion of the T-periodic solution of (1) (in the case g(t)=0) depended heavily on the behaviour of solutions of the integral equation

$$h(t) = \int_0^t C(t-s)h(s) ds + f(t).$$

In [4] Jianhong Wu proved by using the variation of constants formula for equation (2) that if $Z, Z' \in L^1(0, \infty)$), then there exists a unique globally stable T-periodic solution

$$g(t) + \int_{-\infty}^{t} Z'(t-s)g(s) ds + \int_{-\infty}^{t} Z(t-s)f(s) ds$$

of equation (1), where Z(t) is the solution of equation (3).

The present paper is an extension of [1-4]. We shall present some facts relative to the existence of periodic and almost periodic solutions of the systems (1)-(2).

Putting

$$\int_{t_0}^t \exp(\alpha_j(t-z))(t-z)^s x(z) dz = u_{sj}(t),$$

$$\int_{t_0}^t \exp(\beta_j(t-z))(t-z)^s x(z) dz = y_{sj}(t), \quad (s=0,\dots,n_j, \ j=1,\dots,k)$$

the system (2) becomes equivalent to the system

$$\frac{dx}{dt} = \left(A(t) + \sum_{j=1}^{k} \psi_{0j}\right) x + B(t) \sum_{j=1}^{k} \sum_{s=0}^{n_{j}} \varphi_{sj} y_{sj} + \sum_{j=1}^{k} \sum_{s=1}^{n_{j}} \psi_{sj} (\alpha_{j} u_{sj} + s u_{s-1j})$$

$$+ \sum_{j=1}^{k} \psi_{0j} \alpha_{j} u_{0j} + f(t) + g'(t)$$

$$\frac{du_{0j}}{dt} = x + \alpha_{j} u_{0j}, \quad \frac{dy_{0j}}{dt} = x + \beta_{j} y_{0j}, \qquad j = 1, \dots, k$$

$$\frac{du_{sj}}{dt} = \alpha_{j} u_{sj} + s u_{s-1j}, \quad \frac{dy_{sj}}{dt} = s y_{s-1j} + \beta_{j} y_{sj}, \qquad j = 1, \dots, n_{j}, j = 1, \dots, k,$$

with initial conditions

(5)
$$y_{sj}(t_0) = 0, \quad u_{sj}(t_0) = 0, \quad s = 0, \dots, n_j, \ j = 1, \dots, k$$

as only g'(t) exists and is continuous for $t \geq t_0$.

Of course the derivative x'(t) and $\int_{t_0}^t C(t-s)x(s) ds$ must exist for the representation (4).

THEOREM 1. Let $W(t, t_0)$, $(W(t_0, t_0) = E_p)$ be the $p \times p$ fundamental matrix of the system (4) with f(t) = g(t) = 0; then the fundamental $n \times n$ matrix $X(t, t_0)$, $(X(t, t_0) = E_n)$ of system (3) is the upper left minor of degree n of $W(t, t_0)$, i.e.

$$W(t,t_0) = \begin{bmatrix} X & P \\ Q & R \end{bmatrix} .$$

Proof. Let $W(t,t_0)$ denote the fundamental $p\times p$ matrix of system (4) with f(t)=g(t)=0, where $p=n(2k+1+2\sum_{j=1}^k n_j)$. Since the general solution of system (4) with f(t)=g(t)=0 has the form $W(t,t_0)C$, where C is a p-dimensional vector, then in order to obtain a general solution of problem (4)–(5) it is necessary to equate all components of $W(t,t_0)C$ except of the first n to zero and express some of the p-n arbitrary constants of the vector C in terms of any constants of the vector C. Since $W(t_0,t_0)=E_p$, then $c_{n+1}=\ldots=c_p=0$, where c_i $(i=1,\ldots,p)$ are components of the vector C. Hence the fundamental $n\times n$ matrix $X(t,t_0)$, $(X(t_0,t_0)=E_n)$ of system (3) is equal to the upper left minor of degree n of $W(t,t_0)$.

Let W(t) $(W(t_0) = E_p)$ denote the fundamental matrix of (4) with f(t) = g(t) = 0 and let A(t), B(t) be periodic of period ω , then by the Floqueta Theorem

(6)
$$W(t) = Q(t) \exp(\Lambda(t - t_0))$$

where Q(t) is periodic of period ω , $Q(t_0) = E_p$, and Λ is a constant matrix.

Theorem 2. Let (6) be the fundamental matrix solution of (4) such that $W(t_0) = E_p$, then

$$X(t) = Q^*(t) \exp(\Lambda(t - t_0))M$$

will be a fundamental matrix solution of (3) such that $X(t_0) = E_n$, where $Q^*(t)$ is an $n \times p$ periodic matrix of period ω obtained by deleting the last p-n rows in the matrix Q(t), $M=(m_{ij})$ is a $p\times n$ matrix with the property that $m_{ii}=1$ for $i=1,\ldots,n$ and $m_{ij}=0$ for $i\neq j$.

Proof. From (6) the general solution of system (4) with f(t) = g(t) = 0 has the form $Q(t) \exp(\Lambda(t - t_0))C$, where C is a p-dimensional vector. Let $x(t_0) = c^*$, where c^* is an n-dimensional vector. By Theorem 1, in order to obtain a general solution of (2) with f(t) = g(t) = 0 it is necessary to equate the components c_{n+1}, \ldots, c_p to zero.

Hence the general solution of (2) with f(t) = g(t) = 0 and the fundamental matrix of (3) can be represented by

$$x(t) = Q^*(t) \exp(\Lambda(t - t_0)) M c^*$$
 and $X(t) = Q^*(t) \exp(\Lambda(t - t_0)) M$.

Let W(t) ($W(t_0) = E_p$) denote the fundamental matrix of (4). Equation (4) with initial values $x(t_0) = x_0$, $y_{sj}(t_0) = 0$, $u_{sj}(t_0) = 0$, $s = 0, \ldots, n_j$, $j = 1, \ldots, k$, is equivalent to the equation

(7)
$$z(t) = W(t)z_0 + \int_{t_0}^t W(t)W^{-1}(r)[\Phi_1(r) + \Phi_2(r)] dr$$

where

$$\Phi_1(t) = \operatorname{col}(f(t), 0, 0, 0, 0), \qquad \Phi_2(t) = \operatorname{col}(g'(t), 0, 0, 0, 0),
z(t) = \operatorname{col}(x(t), y_{0j}(t), y_{sj}(t), u_{0j}(t), u_{sj}(t))
z_0 = \operatorname{col}(x_0, 0, 0, 0, 0), \qquad (s = 0, \dots, n_j, j = 1, \dots, k).$$

The first n components of (7) give the solution of (2) with initial conditions $x(t_0) = x_0$, i.e.

(8)
$$x(t) = X(t, t_0)(x_0 - g_0) + g(t) + \int_{t_0}^t X(t, r)f(r) dr + \int_{t_0}^t X'_r(t, r)g(r) dr,$$

where $g_0 = g(t_0)$ and X(t,s) is the fundamental $n \times n$ matrix of (3) defined in Theorem 1.

For further consideration we assume that $t_0 = 0$.

Lemma. If 1° A(t), B(t), f(t), g(t) are periodic of period ω ; 2° x(t) is the solution of (2), then $x(t + \omega)$ is the solution of (2) if and only if

(9)
$$\int_0^\omega [C_t(t+\omega-r) + B(t)F(t+\omega-r)]x(r) dr = 0.$$

Proof . From the identity

$$\frac{d}{dt} \left[x(t+\omega) - \int_0^{t+\omega} C(t+\omega - r)x(r) dr - g(t) \right]$$

$$= A(t)x(t+\omega) + B(t) \int_0^{t+\omega} F(t+\omega - r)x(r) dr + f(t)$$

and

$$\frac{d}{dt} \left[x(t+\omega) - \int_0^t C(t-r)x(r+\omega) \, dr - g(t) \right]$$
$$= A(t)x(t+\omega) + B(t) \int_0^t F(t-r)x(r+\omega) \, dr + f(t)$$

we see that

$$\frac{d}{dt} \int_0^\omega C(t+\omega-r)x(r) dr + B(t) \int_0^\omega F(t+\omega-r)x(r) dr = 0.$$

Hence

$$\int_0^\omega \left(C_t(t+\omega-r) + B(t)F(t+\omega-r) \right) x(r) dr = 0.$$

The sufficiency is obvious.

Theorem 3. If A(t), B(t), f(t) and g(t) are periodic of period ω , then the solution x(t) of (2) is periodic if and only if (9) and $x(0) = x(\omega)$ hold.

Proof. If (9) and $x(0) = x(\omega)$ hold, then the solutions $x(t + \omega)$ and x(t) coincide for t = 0. Hence, according to the uniqueness theorem, they coincide for any t and thus x(t) is periodic of period ω . If the solution x(t) of (2) is periodic of period ω , then the above conditions are obviously verified.

Example. Consider the scalar equation

$$\frac{d}{dt} \left[x(t) - \int_0^t \exp(-4(t-s))x(s) \, ds - \frac{3}{2} \cos t \right]$$

$$= -x(t) + 4 \int_0^t \exp(-4(t-s))x(s) \, ds + 2 \cos t + \sin t.$$

It is not difficult to show that this equation has a periodic solution

$$x^*(t) = 2\sin t + (1/2)\cos t$$

Theorem 4. If $1^{\circ} A(t), B(t), f(t), g(t)$ are periodic of period ω ; $2^{\circ} \det(E_n - X(\omega, 0)) \neq 0$,

then the system (2) admits a periodic solution of period ω if and only if

(10)
$$x(t) = X(t,0)[E_n - X(\omega,0)]^{-1} \left\{ \int_0^\omega X(\omega,r) f(r) dr + \int_0^\omega X_r'(\omega,r) g(r) dr \right\}$$

$$+ g(t) + \int_0^t X(t,r) f(r) dr + \int_0^t X_r'(t,r) g(r) dr$$

satisfies (9). This solution is (10).

Proof. Let x(t) be a periodic solution of period ω of the system (2), then from (8)

$$x(0) = X(\omega, 0)(x_0 - g_0) + g(\omega) + \int_0^{\omega} X(\omega, r) f(r) dr + \int_0^{\omega} X'_r(\omega, r) g(r) dr.$$

Hence, since $\det(E_n - X(\omega, 0)) \neq 0$ we have that

$$x_0 = g_0 + (E_n - X(\omega, 0))^{-1} \left\{ \int_0^\omega X(\omega, r) f(r) \, dr + \int_0^\omega X_r'(\omega, r) g(r) \, dr \right\}.$$

The solution x(t) can therefore be written as (10).

The rest of this proof is very similar and therefore is omitted.

Following an argument similar to those of $[\mathbf{4},$ Theorem 2; $\mathbf{3},$ Theorem 2] we get

Theorem 5. Let $C, F \in L^1(0, \infty)$ and let A(t), B(t), f(t), g(t) be periodic of period ω . If $x(t) = x(t, 0, x_0)$ is a bounded solution of (2) on $(0, \infty)$, then there is a sequence of positive integers $\{n_j\}$, $n_j \to \infty$ as $j \to \infty$, such that $\{x(t+n_j\omega)\}$ converges uniformly on compact subsets of $(-\infty, \infty)$ to a function $x^*(t)$ which is a solution of (1).

Proof. Let $C, F \in L^1(0, \infty)$ and let x(t) be a bounded solution of (2) on $(0, \infty)$. We want to show that $\{x(t + n\omega) : n = 1, \ldots\}$ is equicontinuous and uniformly bounded on any fixed interval (-k, k).

For $t_2 \ge t_1 \ge -n\omega$, we integrate (2) from $t_1 + n\omega$ to $t_2 + n\omega$ and get

$$\begin{split} x(t_2 + n\omega) - x(t_1 + n\omega) \\ &= \int_0^{t_2 + n\omega} C(t_2 + n\omega - s)x(s) \, ds - \int_0^{t_1 + n\omega} C(t_1 + n\omega - s)x(s) \, ds \\ &+ \int_{t_1 + n\omega}^{t_2 + n\omega} \left(A(t)x(t) + B(t) \int_0^t F(t - s)x(s) \, ds + f(t) \right) dt \\ &+ q(t_2 + n\omega) - q(t_1 + n\omega). \end{split}$$

The functions x(t), f(t), A(t), B(t) are bounded and $F \in L^1(0, \infty)$, hence there exist M and N such that $|x(t)| \leq M$, $|f(t)| \leq M$, $|A(t)| \leq M$, $|B(t)| \leq M$ for $t \in (0, \infty)$ and $\int_0^\infty |F(t)| \, dt = N < \infty$. Thus

$$\int_{t_1+n\omega}^{t_2+n\omega} \left| A(t)x(t) + B(t) \int_0^t F(t-s)x(s) \, ds + f(t) \right| dt \le M_1 |t_2 - t_1|$$

where $M_1 = M(1 + MN + M)$. Since $C \in L^1(0, \infty)$, then for any $\varepsilon > 0$, there exists a T > 0 such that

$$\int_t^\infty |C(s)| \ ds < \frac{\varepsilon}{8M} \quad \text{for } t \geq T \quad \text{and so} \quad \int_T^\infty |C(t_2 - t_1 + v) - C(v)| \ dv < \frac{\varepsilon}{4M}.$$

By the continuity of C, there exists a $\delta_1 > 0$ such that for $v \in \langle 0, T \rangle$ and $0 \le t_2 - t_1 \le \delta_1$ we have

$$|C(t_2 - t_1 + v) - C(v)| < \frac{\varepsilon}{4TM}$$
 and $\int_0^{t_2 - t_1} |C(v)| \, dv < \frac{\varepsilon}{4M}$.

Thus

$$\begin{split} &\left| \int_0^{t_2+n\omega} C(t_2+n\omega-s)x(s)\,ds - \int_0^{t_1+n\omega} C(t_1+n\omega-s)x(s)\,ds \right| \\ &\leq M \int_0^{t_1+n\omega} \left| C(t_2-t_1+v) - C(v) \right| dv + M \int_0^{t_2-t_1} \left| C(v) \right| dv \\ &\leq M \int_0^T \left| C(t_2-t_1+v) - C(v) \right| dv + M \int_T^{\infty} \left| C(t_2-t_1+v) - C(v) \right| dv \\ &+ M \int_0^{t_2-t_1} \left| C(v) \right| dv \leq \frac{3}{4} \end{split}$$

if $0 \le t_2 - t_1 \le \delta_1$.

By the continuity of g, there exists a $\delta_2 > 0$ such that

$$0 \le (t_2 + n\omega) - (t_1 + n\omega) \le \delta_2$$
 imply $|g(t_2 + n\omega) - g(t_1 + n\omega)| \le \varepsilon/8$.

Let $\delta = \min(\delta_1, \varepsilon/8M_1, \delta_2)$. Then we have

$$|x(t_2 + n\omega) - x(t_1 + n\omega)| < \varepsilon$$
 if $0 < t_2 - t_1 < \delta$.

This implies that $\{x(t+n\omega)\}$ is equicontinuous and uniformly bounded on any fixed interval $\langle -k,k\rangle$, $k=1,2,\ldots$. By Ascoli's theorem there is a subsequence $\{x(t+n_1\omega)\}$ of the $x(t+n\omega)$'s converging uniformly on $\langle -1,1\rangle$, which contains a subsequence $\{x(t+n_2\omega)\}$ on $\langle -2,2\rangle$. Proceeding inductively we obtain a subsequence, say $\{x(t+n_j\omega)\}$, converging uniformly on any fixed interval $\langle -k,k\rangle$ to a continuous function $x^*(t)$.

Now, we show that $x^*(t)$ is a solution of (1). Integrating (2) from $n_j\omega$ to $t + n_j\omega$, we have

$$\begin{split} x(t+n_{j}\omega)-x(n_{j}\omega) &= \int_{0}^{t+n_{j}\omega} C(t+n_{j}\omega-s)x(s)\,ds - \int_{0}^{n_{j}\omega} C(n_{j}\omega-s)x(s)\,ds \\ &+ \int_{n_{j}\omega}^{t+n_{j}\omega} \left(A(s)x(s)+B(s)\int_{0}^{s} F(s-v)x(v)\,dv + f(s)\right)ds \\ &+ g(t+n_{j}\omega)-g(n_{j}\omega) \\ &= \int_{-n_{j}\omega}^{t} C(t-v)x(v+n_{j}\omega)\,dv - \int_{-n_{j}\omega}^{0} C(-v)x(v+n_{j}\omega)\,dv \\ &+ \int_{0}^{t} \left(A(v+n_{j}\omega)x(v+n_{j}\omega) + B(v+n_{j}\omega)\int_{-n_{j}\omega}^{v} F(v-u)x(u+n_{j}\omega)\,du + f(v)\right)dv + g(t) - g(n_{j}\omega) \\ &= \int_{-n_{j}\omega}^{t} C(t-v)x(v+n_{j}\omega)\,dv - \int_{-n_{j}\omega}^{0} C(-v)x(v+n_{j}\omega)\,dv \\ &+ \int_{0}^{t} \left(A(v)x(v+n_{j}\omega) + B(v)\int_{-n_{j}\omega}^{v} F(v-u)x(u+n_{j}\omega)\,du + f(v)\right)dv \\ &+ g(t) - g(n_{j}\omega). \end{split}$$

Since $C, F \in L^1(0, \infty)$, by Lebesgue's dominated convergence theorem by letting $j \to \infty$, we have

$$x^{*}(t) - x^{*}(0) = \int_{-\infty}^{t} C(t - v)x^{*}(v) dv - \int_{-\infty}^{0} C(-v)x^{*}(v) dv + \int_{0}^{t} \left(A(v)x^{*}(v) + B(v) \int_{-\infty}^{v} F(v - u)x^{*}(u) du + f(v) \right) dv + g(t) - g(\infty).$$

Hence, by differentiation, we have

$$\frac{d}{dt} \left[x^*(t) - \int_{-\infty}^t C(t - v) x^*(v) \, dv - g(t) \right]$$

$$= A(t) x^*(t) + B(t) \int_{-\infty}^t F(t - v) x^*(v) \, dv + f(t)$$

and so the limit function $x^*(t)$ is a solution of (1).

Let A(t) and B(t) be periodic and f, g — almost periodic and $\operatorname{Re} \alpha_j < 0$, $\operatorname{Re} \beta_j < 0$. Let x(t) be an almost periodic solution of (2). Then

$$\int_0^t e^{\beta_j (t-z)} (t-z)^s x(z) dz$$

$$= -\int_{-\infty}^0 e^{\beta_j (t-z)} (t-z)^s x(z) dz + \int_{-\infty}^t e^{\beta_j (t-z)} (t-z)^s x(z) dz,$$

where $\int_{-\infty}^{t} e^{\beta_j(t-z)}(t-z)^s x(z) dz$ is an almost periodic function. Since x(t) is an almost periodic solution of (2), then

(11)
$$\sum_{s=0}^{n_j} B(t) \varphi_{sj} \int_{-\infty}^0 e^{\beta_j (t-z)} (t-z)^s x(z) \, dz \equiv 0 \qquad (j=1,\ldots,k).$$

It is easy to see that

$$\sum_{s=0}^{n_j} B(t) \varphi_{sj} \int_{-\infty}^0 e^{\beta_j (t-z)} (t-z)^s x(z) dz \qquad (j=1,\ldots,k)$$

is an almost periodic function. In this case, if

(11')
$$\sum_{s=0}^{n_j} \varphi_{sj} \int_{-\infty}^0 e^{\alpha_j (t-z)} (t-z)^s x(z) \, dz \equiv 0 \qquad (j=1,\ldots,k).$$

then

$$\sum_{s=0}^{n_j} \varphi_{sj} \int_0^t e^{\alpha_j (t-z)} (t-z)^s x(z) dz$$

is an almost periodic function.

On the ground of conditions (11), (11'), the solution x(t) of the system (2) is the solution of the system (1).

Note that (1) is equivalent to the system

$$\frac{dx}{dt} = \left[A(t) + \sum_{j=1}^{k} \psi_{0j} \right] + B(t) \sum_{j=1}^{k} \sum_{s=0}^{n_j} \varphi_{sj} w_{sj}
+ \sum_{j=1}^{k} \sum_{s=1}^{n_j} \psi_{sj} (\alpha_j v_{sj} + s v_{s-1j}) + \sum_{j=1}^{k} \psi_{0j} \alpha_j v_{0j} + f(t) + g'(t)$$
(12)

$$dv_{0j}/dt = x + \alpha_j v_{0j},$$
 $dw_{0j}/dt = x + \beta_j w_{0j}$ $s = 1, ..., n_j$
 $dv_{sj}/dt = \alpha_j v_{sj} + s v_{s-1j},$ $dw_{sj}/dt = s w_{s-1j} + \beta_j w_{sj}$ $j = 1, ..., k$

where

$$w_{sj}(t) = \int_{-\infty}^{t} e^{\beta_j(t-z)} (t-z)^s x(z) dz, \qquad v_{sj}(t) = \int_{-\infty}^{t} e^{\alpha_j(t-z)} (t-z)^s x(z) dz.$$

According to the assumption, x(t) is an almost periodic function, so $w_{sj}(t)$ and $v_{sj}(t)$ are almost periodic functions.

Theorem 6. If A(t) and B(t) are periodic, f,g are almost periodic and $\operatorname{Re}\alpha_j < 0$, $\operatorname{Re}\beta_j < 0$ $(j=1,\ldots,k)$, then x(t) is an almost periodic solution of the system (2) if and only if $(x(t),w_{sj}(t),v_{sj}(t))$ is an almost periodic solution of the system (12) and conditions (11)–(11') are satisfied.

Proof. If the system (2) admits an almost periodic solution x(t), then the conditions (11)–(11') are obviously verified and (12) has an almost periodic solution.

Conversely, if (12) has an almost periodic solution and conditions (11)–(11') are satisfied, then the solution x(t) of (2) is almost periodic.

Remark. If A(t) = A = const, B(t) = B = const, $t_0 = 0$, then the system (2) has a general solution of the form

$$x(t) = X(t)(x_0 - g_0) + g(t) + \int_0^t X(t - s)f(s) ds + \int_0^t X'(t - s)g(s) ds.$$

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